Operating Instructions Liquiline CM442R/CM444R/ CM448R

Universal four-wire multichannel controller Cabinet installation

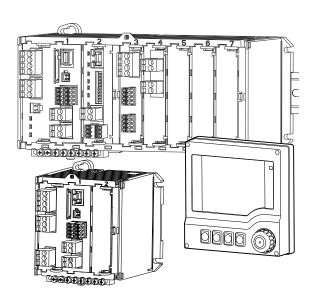




Table of contents

1	Document information	. 5
1.1	Warnings	5
1.2	Symbols	. 5
1.3	Symbols at the device	
1.4	Documentation	6
2	Basic safety instructions	7
2.1	Requirements for the personnel	. 7
2.2	Designated use	
2.3	Occupational safety	
2.4 2.5	Operational safety	
2.2		,)
3	Device description	10
3.1	Overview	10
3.2 3.3	Slot and port assignment	11 12
2.2	Terminal diagram	12
4	Incoming acceptance and product	
	identification	13
4.1	Incoming acceptance	13
4.2	Product identification	13
4.3	Scope of delivery	14
4.4	Certificates and approvals	14
5	Installation	15
5.1	Installation conditions	15
5.2	Mounting the measuring device	19
5.3	Post-installation check	22
6	Electrical connection	23
6.1	Connection conditions	23
6.2	Connecting the measuring device	24
6.3	Connecting the sensors	28
6.4	Connecting additional inputs, outputs or relays	30
6.5	Connecting digital communication	34
6.6	Hardware settings	37
6.7	Ensuring the degree of protection	38
6.8	Post-connection check	39
7	System integration	40
7.1	Web server	40
7.2	Service interface	41
7.3	Fieldbuses	42
8	Operation options	44
8.1	Overview	44
8.2	Access to the operating menu via the local	
	display	45

8.3	Configuration options	46
9	Commissioning	49
9.1	Function check	49
9.1 9.2	Power up	49 49
9.2 9.3	User definable screens	49 50
9.4	Basic setup	51
9.4		1
10	Operation	52
10.1	Display	52
10.2	General settings	54
10.3	Current inputs	66
10.4	Outputs	67
10.5	Binary inputs and outputs	74
10.6	Additional functions	80
11	Calibration	108
12	Diagnostics and troubleshooting	109
12.1	General troubleshooting	109
12.2	Diagnostic information on the local display	
	(optional)	110
12.3	Diagnostic information via web browser	110
12.4	Diagnostic information via fieldbus	110
12.5	Adapting the diagnostic information	110
12.6	Overview of diagnostic information	112
12.7	Pending diagnostic messages	116
12.8	Diagnostics list	116
12.9	Event logbook	116
12.10		119
12.11	Device test	121
12.12	Resetting the measuring device	121
12.13	Device information	122
12.14	Firmware history	124
13	Maintenance	126
13.1	Cleaning	126
15.1	Cleaning	120
14	r	128
14.1	Spare parts	128
14.2	Return	129
14.3	Disposal	130
15	Accessories	131
15.1	Measuring cable	131
15.2	Sensors	131
15.3	Additional functionality	136
15.4	Software	138
15.5	Other accessories	138
17.7		170
16	Technical data	L40

17 Installation and operation in hazardous environment Class I Div.2 (CM444R and CM448R only) 152

Index 153

1 Document information

1.1 Warnings

Structure of information	Meaning
▲ DANGER Causes (/consequences) If necessary, Consequences of non-compliance (if applicable) ► Corrective action	This symbol alerts you to a dangerous situation. Failure to avoid the dangerous situation will result in a fatal or serious injury.
WARNING Causes (/consequences) If necessary, Consequences of non-compliance (if applicable) ► Corrective action	This symbol alerts you to a dangerous situation. Failure to avoid the dangerous situation can result in a fatal or serious injury.
▲ CAUTION Causes (/consequences) If necessary, Consequences of non-compliance (if applicable) ► Corrective action	This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in minor or more serious injuries.
NOTICE Cause/situation If necessary, Consequences of non-compliance (if applicable) Action/note	This symbol alerts you to situations which may result in damage to property.

1.2 Symbols

Symbol	Meaning			
i	Additional information, tips			
	Permitted or recommended			
	Not permitted or not recommended			
I	Reference to device documentation			
1	Reference to page			
	Reference to graphic			
L .	Result of a step			

1.3 Symbols at the device

Symbol	Meaning
	Reference to device documentation

1.4 Documentation

The following instructions complement these Operating Instructions and are available on the product pages on the internet:

- Brief Operating Instructions Liquiline CM44xR, KA01160C
- Operating Instructions Memosens, BA01245C
 - Software description for Memosens inputs
 - Calibration of Memosens sensors
 - Sensor-specific diagnostics and troubleshooting
- Operating Instructions for HART communication, BA00486C
- Onsite settings and installation instructions for HART
- Description of HART driver
- Guidelines for communication via fieldbus and web server
 - HART, SD01187C
 - PROFIBUS, SD01188C
 - Modbus, SD01189C
 - Web server, SD01190C
 - EtherNet/IP, SD01293C

2 Basic safety instructions

2.1 Requirements for the personnel

- Installation, commissioning, operation and maintenance of the measuring system may be carried out only by specially trained technical personnel.
- The technical personnel must be authorized by the plant operator to carry out the specified activities.
- The electrical connection may be performed only by an electrical technician.
- The technical personnel must have read and understood these Operating Instructions and must follow the instructions contained therein.
- Faults at the measuring point may only be rectified by authorized and specially trained personnel.

Repairs not described in the Operating Instructions provided must be carried out only directly at the manufacturer's site or by the service organization.

2.2 Designated use

2.2.1 Non-hazardous atmosphere

Liquiline CM44xR is a multichannel controller for connecting digital sensors with Memosens technology in non-hazardous environments.

The device is designed for use in the following applications:

- Food and beverages
- Life science
- Water and wastewater
- Chemical industry

2.2.2 Hazardous environment in accordance with cETLus NI Cl. I, Div. 2 (CM444R and CM448R only)

- Please note the control drawing and the specified application conditions in the appendix of these Operating Instructions and follow the instructions.
- The device must be installed in a housing or cabinet where access is only possible with a tool or key.

2.2.3 Non-designated use and improper use

NOTICE

Objects stored on top of the housing

May result in short-circuits or fire, the failure of individual cabinet components to complete failure of the measuring point.

- Never place any objects e.g. tools, cables, paper, food, liquid containers or similar on top
 of the housing.
- Always observe the operator's regulations, in particular with regard to fire safety (smoking) and foodstuffs (beverages).

Use of the device for any purpose other than that described, poses a threat to the safety of people and of the entire measuring system and is therefore not permitted.

The manufacturer is not liable for damage caused by improper or non-designated use.

2.2.4 Installation environment

The device and the associated power units can be operated with 24 V AC, 24 V DC or 100 to 230 V AC and provide shock protection in accordance with IP20.

The components have been designed for pollution degree 2, and moisture must not be allowed to collect in them. The components must therefore be installed in an appropriate enclosure for protection. The ambient conditions specified in the instructions must be observed here.

2.3 Occupational safety

As the user, you are responsible for complying with the following safety conditions:

- Installation guidelines
- Local standards and regulations
- Regulations for explosion protection

Electromagnetic compatibility

- The product has been tested for electromagnetic compatibility in accordance with the applicable European standards for industrial applications.
- The electromagnetic compatibility indicated applies only to a product that has been connected in accordance with these Operating Instructions.

2.4 Operational safety

- **1.** Before commissioning the complete measuring point, verify that all connections are correct. Ensure that electrical cables and hose connections are undamaged.
- 2. Do not operate damaged products, and protect them against unintentional operation. Label the damaged product as defective.
- 3. If faults cannot be rectified,

products must be taken out of service and protected against unintentional operation.

ACAUTION

Cleaning not switched off during calibration or maintenance activities

Risk of injury due to medium or cleaning agent

- If a cleaning system is connected, switch if off before removing a sensor from the medium.
- If you wish to check the cleaning function and have therefore not switched off the cleaning system, please wear protective clothing, goggles and gloves or take other appropriate measures.

2.5 Product safety

2.5.1 State of the art

The product is designed to meet state-of-the-art safety requirements, has been tested, and left the factory in a condition in which it is safe to operate. The relevant regulations and European standards have been observed.

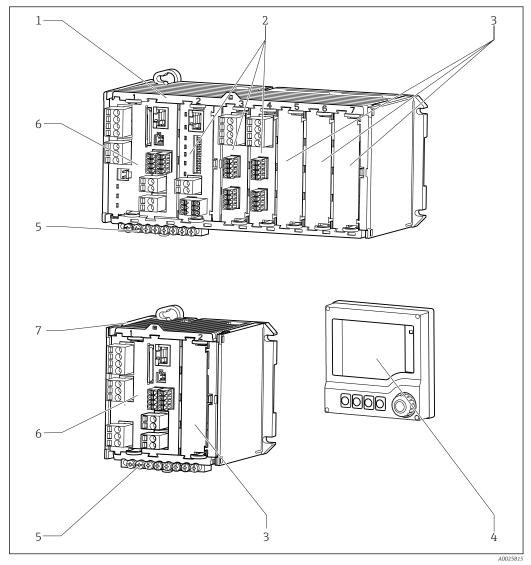
2.5.2 IT security

We only provide a warranty if the device is installed and used as described in the Operating Instructions. The device is equipped with security mechanisms to protect it against any inadvertent changes to the device settings.

IT security measures in line with operators' security standards and designed to provide additional protection for the device and device data transfer must be implemented by the operators themselves.

3 Device description

3.1 Overview



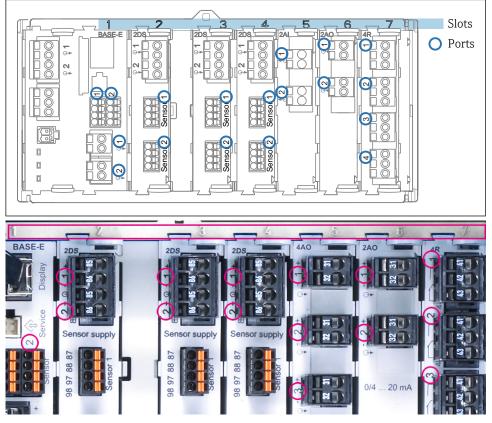
■ 1 Device with optional, external display (excluding cables)

- 1 Four-channel or eight-channel device
- 2 Extension modules (optional)
- 3 Shock protection, dummy module
- 4 External display (optional)

- Terminal strip
- 6 Basic module

5

- 7 Two-channel device
- 8 External power unit (CM444R or CM448R only)



3.2 Slot and port assignment

Slot and port assignment of the hardware modules

Outlet 1				0
CH1: 11)pH Glass	s AT	C 6.95 pH	D. (
CH2: 1:2	TU/TS		500.0 g	/I Port Slot
CH3: 5:1	SAC		500.0 1	/m 5101
CH4: 5:2	Cond i	AT	(<mark>2.62</mark> mS	/cm
CH5: 6:1	Chlorine		28.33 m	g/I
CH6: 6:2	Redox	4	51 mV	
CH7: 7:1	Oxygen	(am	32.86 m	g/l
CH8: 7:2	Cond c	AT	(131.1 p	S/cm
MENU	CAL	DIAG	HOLD	

Slot and port assignment on the display

- Inputs are assigned to measuring channels in the ascending order of the slots and ports. Adjacent example:
 "CH1: 1:1 pH glass" means: Channel 1 (CH1) is slot 1 (basic module) : Port 1 (input 1), pH glass sensor
- Outputs and relays are named according to their function, e.g. "current output", and are displayed with the slot and port numbers in ascending order

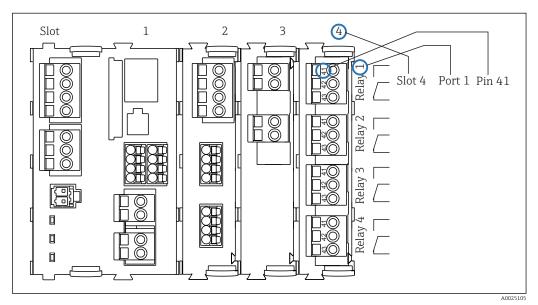
3.3 Terminal diagram

The unique terminal name is derived from:

Slot no. : Port no. : Terminal

Example, NO contact of a relay

- Device with 4 inputs for digital sensors, 4 current outputs and 4 relays
- Base module BASE-E (contains 2 sensor inputs, 2 current outputs)
- 2DS module (2 sensor inputs)
- 2AO module (2 current outputs)
- 4R module (4 relays)



🖻 4 Creating a terminal diagram using the example of the NO contact (terminal 41) of a relay

4 Incoming acceptance and product identification

4.1 Incoming acceptance

1. Verify that the packaging is undamaged.

- Notify your supplier of any damage to the packaging.
 Keep the damaged packaging until the matter has been settled.
- 2. Verify that the contents are undamaged.
 - └→ Notify your supplier of any damage to the delivery contents. Keep the damaged products until the matter has been settled.
- 3. Check the delivery for completeness.
 - └ Check it against the delivery papers and your order.
- 4. Pack the product for storage and transportation in such a way that it is protected against impact and moisture.
 - The original packaging offers the best protection.
 The permitted ambient conditions must be observed (see "Technical data").

If you have any questions, please contact your supplier or your local sales center.

4.2 Product identification

4.2.1 Nameplate

The nameplate provides you with the following information on your device:

- Manufacturer identification
- Order code
- Extended order code
- Serial number
- Firmware version
- Ambient and process conditions
- Input and output values
- Activation codes
- Safety information and warnings
- Compare the data on the nameplate with your order.

4.2.2 Product identification

Product page

www.endress.com/cm442r www.endress.com/cm444r www.endress.com/cm448r

Interpreting the order code

The order code and serial number of your product can be found in the following locations:

- On the nameplate
- In the delivery papers

Obtaining information on the product

1. Go to the product page for your product on the Internet.

- 2. At the bottom of the page, click the link **Online Tools** and then select **Access device specific information**.
 - └ An additional window opens.
- 3. Enter the order code from the nameplate into the search field and then select **Show details**.
 - You will receive information on each feature (selected option) of the order code.

Manufacturer's address

Endress+Hauser Conducta GmbH+Co. KG Dieselstraße 24 D-70839 Gerlingen

4.3 Scope of delivery

The scope of delivery comprises:

- 1 multichannel controller in the version ordered
- 1 mounting plate
- 1 external display (if selected as an option) ¹⁾
- 1 DIN rail power unit incl. Cable (CM444R and CM448R only)
- 1 printed copy of the Operating Instructions for DIN rail power unit
- 1 printed copy of the Brief Operating Instructions in the language ordered

If you have any questions, please contact your supplier or local sales center.

4.4 Certificates and approvals

4.4.1 EAC

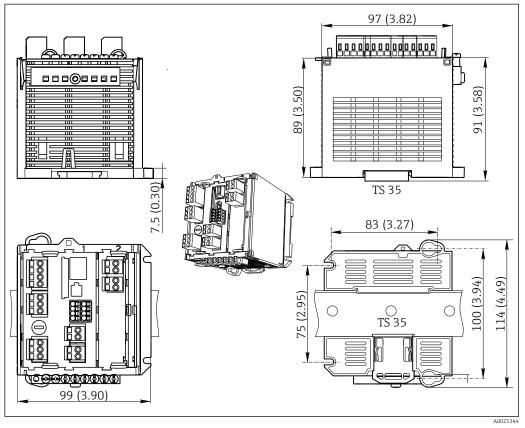
The product has been certified according to guidelines TP TC 004/2011 and TP TC 020/2011 which apply in the European Economic Area (EEA). The EAC conformity mark is affixed to the product.

¹⁾ The external display can be selected as an option in the order structure or ordered as an accessory at a later stage.

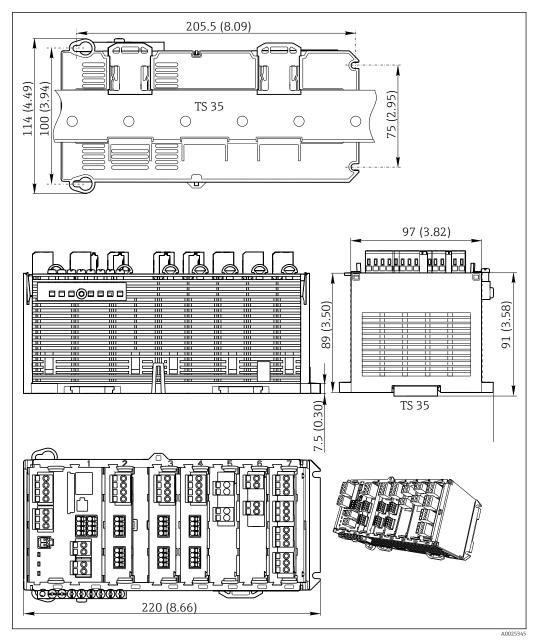
5 Installation

5.1 Installation conditions

5.1.1 Dimensions



☑ 5 Dimensions in mm (inch)



6 Dimensions in mm (inch)

5.1.2 Mounting on DIN rail as per IEC 60715

ACAUTION

The power unit can get very hot under full load Burn hazard

- Avoid touching the power unit during operation.
- Make sure to keep the minimum distance to other devices.
- After switching off the power unit, allow it to cool before performing any work on it.

ACAUTION

Impermissible collection of moisture in the device

Puts the safety of the user at risk

- The device has IP20 shock protection. Moisture must not be allowed to collect in the device.
- Comply with the specified ambient conditions, e.g. by installing the device in an appropriate protective enclosure.

NOTICE

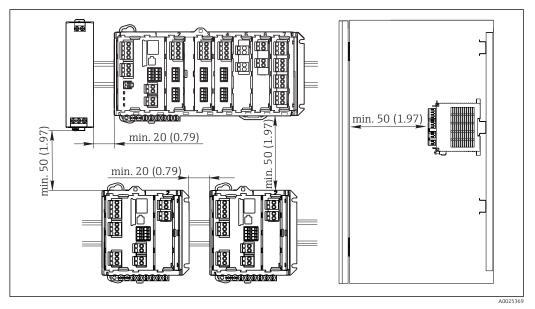
Incorrect mounting location in the cabinet, spacing regulations not observed Possible malfunctions as a result of heat development and interference from neighboring devices

- Do not position the device directly above sources of heat. Make sure to observe the temperature specification.
- The components are designed for convection-based cooling. Avoid the buildup of heat and ensure openings are not covered over, e.g. by cables.
- Make sure to keep the specified distance to other devices.
- Physically separate the device from frequency converters and high-voltage devices.
- Recommended installation direction: horizontal. The specified ambient conditions, and particularly the ambient temperatures, only apply for horizontal installation.
- Vertical orientation is also possible. However, this requires additional fixing clips at the place of installation to hold the device in position on the DIN rail.
- Recommended installation of power unit for CM444R and CM448R: to the left of the device.

The following minimum spacing specifications must be observed:

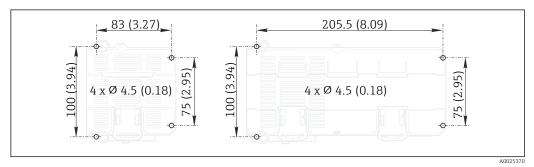
- Distance at the side to other devices including power units and distance to control cabinet wall:
 - at least 20 mm (0.79 inch)
- Distance above and below the device and depth distance (to control cabinet door or other devices installed there):

at least 50 mm (1.97 inch)



☑ 7 Minimum spacing in mm (inch)

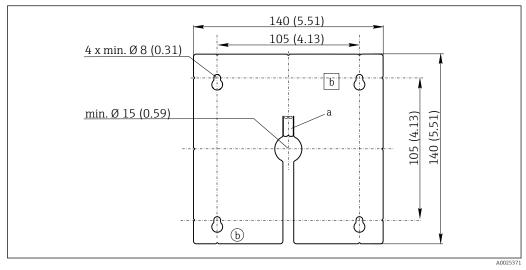
5.1.3 Wall mounting



B Drilling pattern for wall mounting in mm (inch)

5.1.4 Mounting the external display

The mounting plate also serves as the drilling template. The marks on the side help you mark the position of the drill holes.



Mounting plate of external display in mm (inch)

- a Retaining tab
- *b Production-related recesses, no function for the user*

5.1.5 Cable length for optional display

Length of display cable provided: 3 m (10 ft)

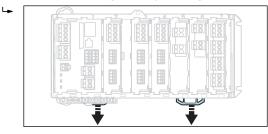
Maximum permitted length of a display cable: 5 m (16.5 ft)

5.2 Mounting the measuring device

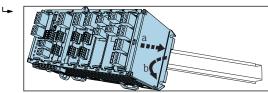
5.2.1 DIN rail mounting

The mounting procedure is the same for all Liquiline devices. The example shows a CM448R.

1. In the order configuration, the securing clips are "tightened" to secure the DIN rail. Release the securing clips by pulling them downwards.



Attach the device from the top to the DIN rail (a) and then press it down to secure it (b).



3. Slide the securing clips upwards until they click, thereby securing the device to the DIN rail.

	l.e.i			
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4. CM444R and CM448R only

Mount the external power unit in the same way.

5.2.2 Wall mounting

┕►

Mounting material (screws, dowels) are not included in the scope of delivery and must be provided by the customer.

CM444R and CM448R: The external power unit can be mounted on a DIN rail only.

Use the back of the housing to mark the mounting holes. (\rightarrow \blacksquare 8, \blacksquare 17)

1. Drill the required holes and place dowels in them if necessary.

2. Screw the housing onto the wall.

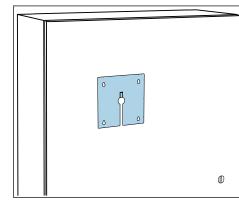
5.2.3 Mounting the optional external display

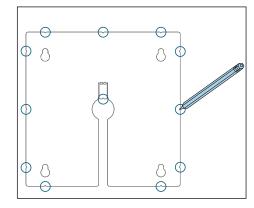
Sharp-edged, non-deburred drill holes

Risk of injury, display cable may get damaged

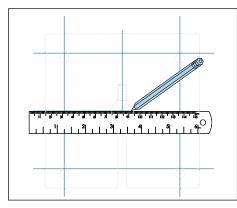
► In particular, deburr the central drill hole for the display cable.

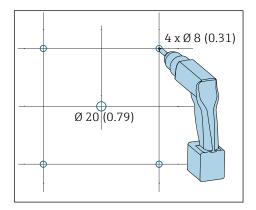
Mounting the display on the door of the cabinet



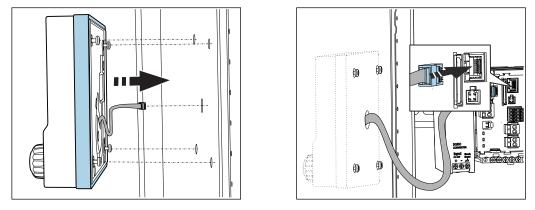


- 1. Hold the mounting plate from the outside against the door of the control cabinet. Choose the point at which you wish to install the display.
- 2. Make all the markings.



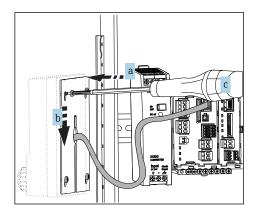


- 3. Draw lines connecting the markings. This will indicate the position of the five drill holes needed.
- 4. Drill the holes ($\rightarrow \blacksquare 9, \boxdot 18$).

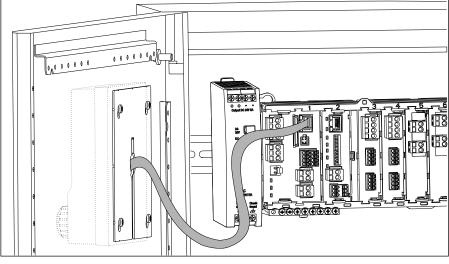


5. Pull the display cable through the hole in the middle, and place the display from the outside through the four holes drilled for this purpose, ensuring that the torx screws have been unscrewed to the last half turn but are still in place. Ensure that the rubber frame (seal, highlighted blue) does not become damaged and is properly positioned on the surface of the door.

6. Connect the display cable to the RJ-45 socket in the base module.



7. Place the mounting plate (a) on the inside over the screws, slide it down (b) and tighten the screws (c).



└ The display is now mounted and ready to use.

🖻 10 Mounted display

NOTICE

Installation error

Damage, e.g. to the cable, or malfunctions are possible

- Lay cables in such a way that they do not get squashed e.g. when closing the cabinet door.
- ► Plug the display cable only into the RJ45 socket in the base module. Otherwise, the display will not function.

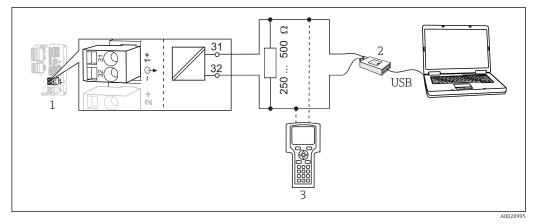
5.3 Post-installation check

- **1.** Following installation, check all devices (controller, power unit, display) for damage.
- 2. Verify that the specified mounting distances have been observed.
- 3. Verify that all securing clips have been snapped into place and that the components are securely positioned on the DIN rail.
- 4. Ensure that the temperature limits at the mounting location are observed.

6 Electrical connection

6.1 Connection conditions

6.1.1 Via HART (e.g. using HART modem and FieldCare)

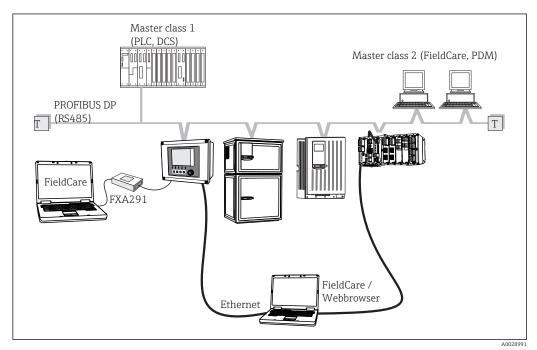


🗷 11 HART using modem

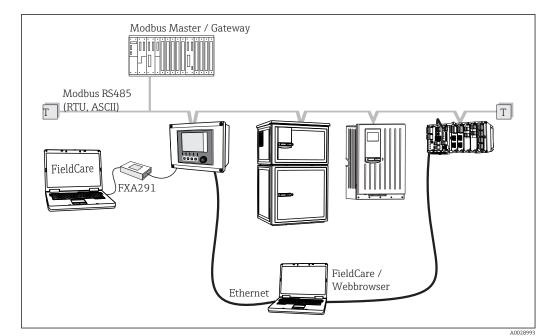
- 1 Device module Base L, H or E: current output 1 with HART
- 2 HART modem for connection to PC, e.g. Commubox FXA191 (RS232) or FXA195¹⁾ (USB)
- 3 HART handheld terminal

¹⁾ Switch position "on" (substitutes the resistor)

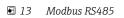
6.1.2 Via PROFIBUS DP



- 12 PROFIBUS DP
- T Terminating resistor

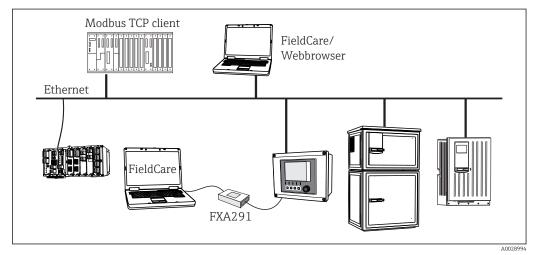


6.1.3 Via Modbus RS485



T Terminating resistor

6.1.4 Via Ethernet/Web server/Modbus TCP/EtherNet/IP



14 Modbus TCP and/or EtherNet/IP

6.2 Connecting the measuring device

WARNING

Device is live

Incorrect connection may result in injury or death

- The electrical connection may be performed only by an electrical technician.
- The electrical technician must have read and understood these Operating Instructions and must follow the instructions contained therein.
- **Prior** to commencing connection work, ensure that no voltage is present on any cable.

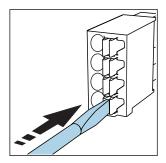
NOTICE

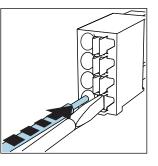
The device does not have a power switch

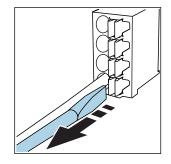
- The customer must provide a protected circuit breaker in the vicinity of the device.
- The circuit breaker must be a switch or power switch, and you must label it as the circuit breaker for the device.
- ► At the supply point, the power supply must be isolated from dangerous live cables by double or reinforced insulation in the case of devices with a 24 V supply voltage.

6.2.1 Cable terminals

Plug-in terminals for Memosens and PROFIBUS/RS485 connections





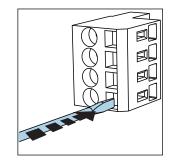


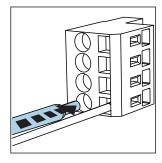
Press the screwdriver against the clip Insert the cable until the limit stop (opens the terminal)

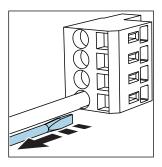
Remove the screwdriver (closes the terminal)

After connection, make sure that every cable end is securely in place. Terminated cable ends, in particular, tend to come loose easily if they have not been correctly inserted as far as the limit stop.

All other plug-in terminals

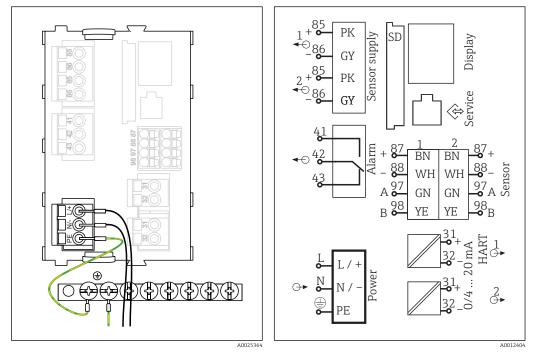






Press the screwdriver against the clip Insert the cable until the limit stop (opens the terminal)

Remove the screwdriver (closes the terminal)



6.2.2 Connecting the supply voltage for CM442R

■ 15 Connecting power supply on the BASE-H or -L

🖻 16 Overall wiring diagram for BASE-H or -L

- H Power unit 100 to 230 VAC
- L Power unit 24 VAC or 24 VDC

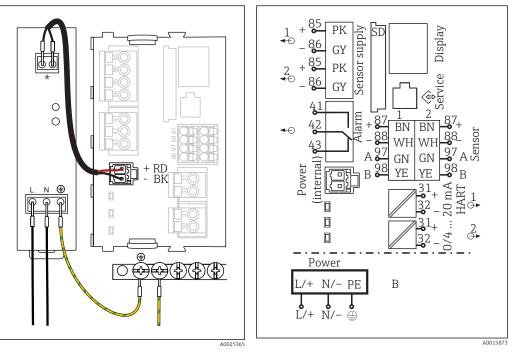
NOTICE

cables.

Incorrect connection and cable run not separate

Faults in signal or display cable, incorrect measured values or failure of display may occur

Do not place the cable shield of the display cable on PE (terminal strip of device)!
Run the signal/display cable in the control cabinet separately from current-carrying



6.2.3 Connecting the supply voltage for CM444R and the CM448R

I7 Connecting power supply with BASE-E
 * Assignment depending on power unit, make sure

to connect correctly

I8 Overall wiring diagram BASE-E and external power unit (B)

The two device versions may only be operated with the power unit supplied and the power unit cable. Also pay attention to the information in the operating manual supplied for the power unit.

NOTICE

Incorrect connection and cable run not separate

Faults in signal or display cable, incorrect measured values or failure of display may occur

- Do not place the cable shield of the display cable on PE (terminal strip of device)!
- Run the signal/display cable in the control cabinet separately from current-carrying cables.

6.3 Connecting the sensors

6.3.1 Sensor types with Memosens protocol

Sensors with Memosens protocol

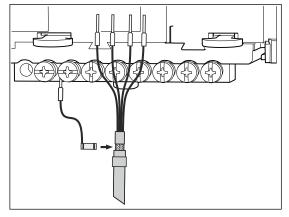
Sensor types	Sensor cable	Sensors
Digital sensors without additional internal power supply	With plug-in connection and inductive signal transmission	 pH sensors ORP sensors Combined sensors Oxygen sensors (amperometric and optical) Conductivity sensors with conductive measurement of conductivity Chlorine sensors (disinfection)
	Fixed cable	Conductivity sensors with inductive measurement of conductivity
Digital sensors with additional internal power supply		 Turbidity sensors Sensors for interface measurement Sensors for measuring the spectral absorption coefficient (SAC) Nitrate sensors Optical oxygen sensors Ion-sensitive sensors

The following rule applies if connecting CUS71D sensors:

- CM442R
 - Only one CUS71D is possible; an additional sensor is not permitted.
 - The second sensor input may also not be used for another type of sensor.
- CM444R
 - No restrictions. All the sensor inputs can be used as required.
- CM448R
 - If a CUS71D is connected, the number of sensor inputs that can be used is limited to a maximum of 4.
 - Of these, all 4 inputs can be used for CUS71D sensors.
 - Every combination of CUS71D and other sensors is possible, provided that the total number of connected sensors does not exceed 4.

6.3.2 Connecting the functional ground

You must always connect the terminal strip with PE from the central node in the cabinet. Use the conductor with cable clamp that is included with the Memosens cable to connect the functional earth to the terminal strip of the device.



Functional earth connection

You must only ever connect one functional earth to each screw in the terminal strip. Otherwise, shielding is not guaranteed.

6.3.3 Connecting the sensors

Connection

Direct connection of sensor cable to terminal connector of the sensor module 2DS or of base module L, H or E ($\rightarrow \blacksquare$ 20 ff.)

► Sensor cable connected directly

Connect the sensor cable to the Memosens terminal connector of the sensor module 2DS or of base module L, H or E.

sensors with additional supply voltage

П

0

F

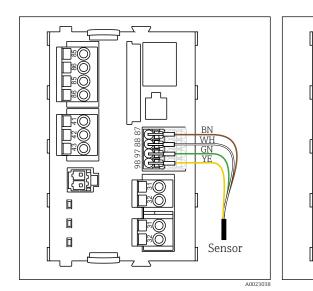
🖻 21

РK

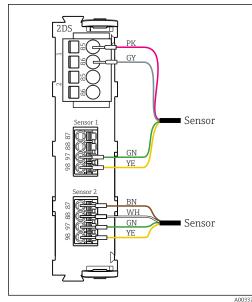
GY

GN

Sensor



20 sensors without additional supply voltage



22 sensors with and without additional supply voltage at sensor module 2DS

6.4 Connecting additional inputs, outputs or relays

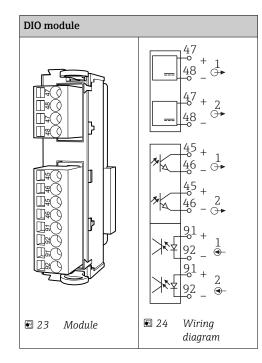
WARNING

Module not covered

No shock protection. Danger of electric shock!

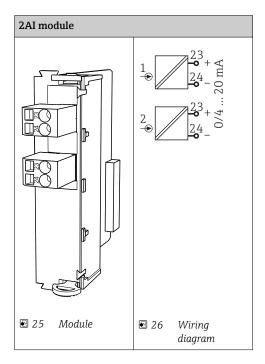
- If you are modifying or extending your hardware, always fill the slots from left to right. Do not leave any gaps.
- Always ensure shock protection is guaranteed particularly in the case of relay modules (2R, 4R, AOR).

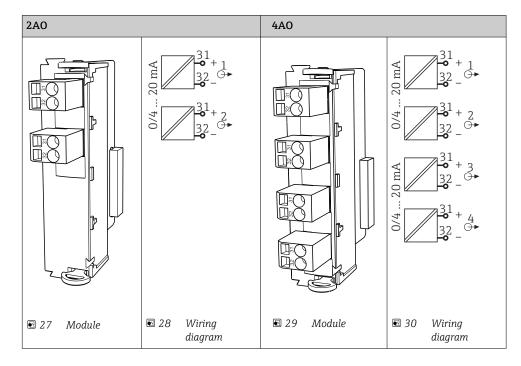
The terminal strip is used to connect the cable shields. Additionally required shields must be connected with PE centrally in the control cabinet via terminal blocks supplied by the customer.



6.4.1 Digital inputs and outputs

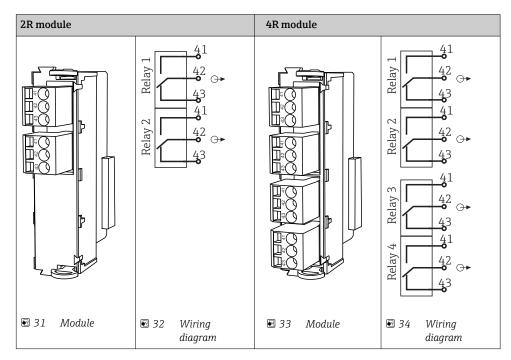
6.4.2 Current inputs





6.4.3 Current outputs

6.4.4 Relay



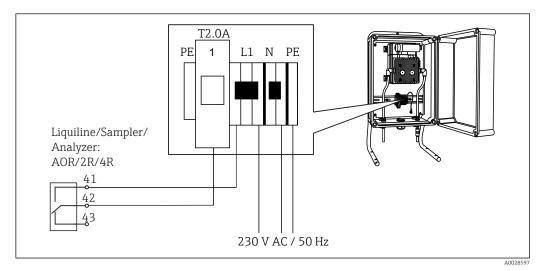
Example: Connecting the cleaning unit 71072583 for CAS40D

NOTICE

Power consumption too high for the Liquiline alarm relay

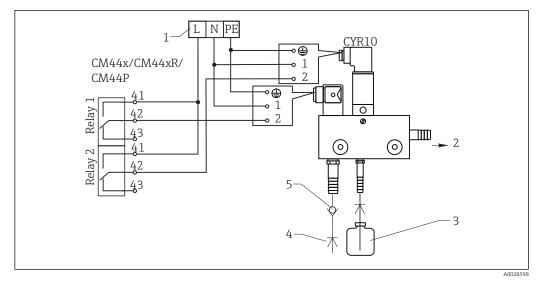
Can cause irreparable damage to the base module

 Only connect the cleaning unit to terminals of an additional module (AOR, 2R or 4R), not to the alarm relay of the base module.



■ 35 Connecting the cleaning unit for CAS40D

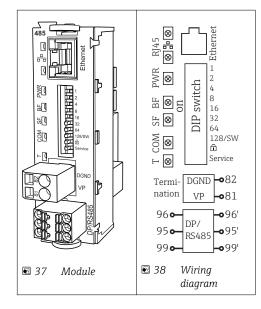
Example: Connecting the Chemoclean CYR10 injector cleaning unit



- 36 Connecting the CYR10 injector cleaning unit
- 1 External power supply
- 2 Cleaner to spray head
- 3 Container with cleaner
- 4 Motive water 2 to 12 bar (30 to 180 psi)
- 5 Backflow valve (to be provided by the customer)

6.5 Connecting digital communication

6.5.1 Module 485



Terminal	PROFIBUS DP	Modbus RS485
95	А	В
96	В	А
99	Not connected	С
82	DGND	DGND
81	VP	VP

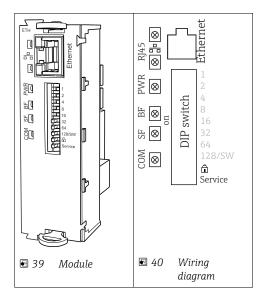
LEDs on front of module

LED	Description	Color	Description
RJ45	LNK/ACT	GN	 Off = Connection is not active On = Connection is active Flashing = Data transmission
RJ45	10/100	YE	 Off = Transmission rate 10 MBit/s On = Transmission rate 100 MBit/s
PWR	Power	GN	Supply voltage is applied and module is initialized
BF	Bus failure	RD	Bus failure
SF	System failure	RD	Device error
COM	Communication	YE	Modbus message sent or received
Т	Bus termination	YE	 Off = No termination On = Termination is used

DIP switches on front of module

DIP	Factory setting	Assignment
1-128	ON	Bus address (\rightarrow "Commissioning/communication")
â	OFF	Write protection: "ON" = configuration not possible via the bus, only via local operation
Service	OFF	If the switch is set to "ON" , the user settings for Ethernet addressing are saved and connection settings programmed into the device at the factory are activated: IP address=192.168.1.212, Subnet mask=255.255.255.0, Gateway=0.0.0, DHCP=Off. If the switch is set to "OFF" , the saved user settings are reactivated.

6.5.2 Module ETH



LEDs on front of module

LED	Designation	Color	Description
RJ45	LNK/ACT	GN	 Off = Connection is not active On = Connection is active Flashing = Data transmission
RJ45	10/100	YE	 Off = Transmission rate 10 MBit/s On = Transmission rate 100 MBit/s
PWR	Power	GN	Supply voltage is applied and module is initialized
BF	Bus failure	RD	Not used
SF	System failure	RD	Device error
СОМ	Communication	YE	Modbus message sent or received

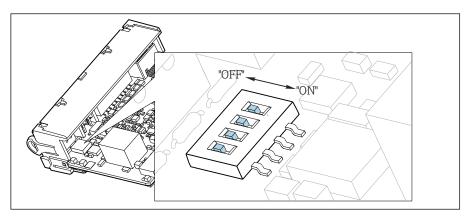
DIP switches on front of module

DIP	Factory setting	Assignment
1-128	ON	Bus address (\rightarrow "Commissioning/communication")
â	OFF	Write protection: "ON" = configuration not possible via the bus, only via local operation
Service	OFF	If the switch is set to "ON" , the user settings for Ethernet addressing are saved and connection settings programmed into the device at the factory are activated: IP address=192.168.1.212, Subnet mask=255.255.255.0, Gateway=0.0.0.0, DHCP=Off. If the switch is set to "OFF" , the saved user settings are reactivated.

6.5.3 Bus termination

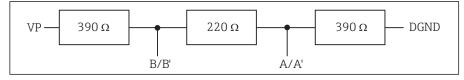
There are two ways to terminate the bus:

1. Internal terminating resistor (via DIP switch on the module board)



🖻 41 DIP switches for internal terminating resistor

Using a suitable tool, such as a tweezers, set all 4 DIP switches to the "ON" position.
 The internal terminating resistor is used.



42 Structure of the internal terminating resistor

2. External terminating resistor

Here, leave the DIP switches on the module board in the "OFF" position (factory setting).

- Connect the resistor to terminals 81 and 82 on the front of module 485 for 5-V power supply.
 - └ The external terminating resistor is used.

6.6 Hardware settings

Setting the bus address

- 1. Open the housing.
- 2. Set the desired bus address via the DIP switches of module 485.
- For PROFIBUS DP, valid bus addresses are anything between 1 and 126, and anything between 1 and 247 for Modbus. If you configure an invalid address, software addressing is automatically enabled via the local configuration or via the fieldbus.



Valid PROFIBUS address 67
 44 Valid Modbus address 195
 45 Invalid address 255 ¹)
 ¹⁾ Order configuration, software addressing is active, software address configured at the factory: PROFIBUS 126, Modbus 247

6.7 Ensuring the degree of protection

Only the mechanical and electrical connections which are described in these instructions and which are necessary for the required, designated use, may be carried out on the device delivered.

• Exercise care when carrying out the work.

Individual types of protection permitted for this product (impermeability (IP), electrical safety, EMC interference immunity, Ex protection) can no longer be guaranteed if, for example:

- Covers are left off.
- Different power units to the ones supplied are used.
- Cable glands are not sufficiently tightened (must be tightened with 2 Nm for the confirmed level of IP protection).
- Modules are not fully secured.
- The display is not fully secured (risk of moisture entering due to inadequate sealing).
- Loose or insufficiently tightened cables/cable ends.
- Conductive cable strands are left in the device.

6.8 Post-connection check

WARNING

Connection errors

The safety of people and of the measuring point is under threat. The manufacturer does not accept any responsibility for errors that result from failure to comply with the instructions in this manual.

• Operate the device only if you can answer **yes** to **all** of the following questions.

Instrument status and specifications

▶ Is there any external damage to the device and cables?

Electrical connection

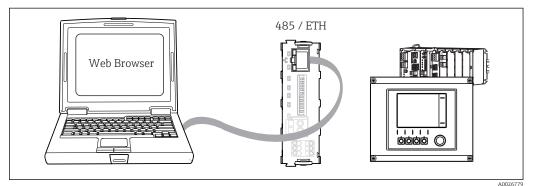
- Are the mounted cables strain-relieved?
- ► Have the cables been routed without loops and cross-overs?
- ► Have the signal lines been connected correctly in accordance with the wiring diagram?
- Are all plug-in terminals securely engaged?
- Are all the connection wires securely positioned in the cable terminals?

7 System integration

7.1 Web server

7.1.1 Connection

• Connect the PC communication cable to the RJ45 port of module 485 or module ETH.



☑ 46 Web server/Ethernet connection

7.1.2 Establishing the data connection

To ensure that your device has a valid IP address, you must disable the **DHCP** parameter in the Ethernet settings. (Menu/Setup/General settings/Extended setup/Ethernet/Settings)

You can then set the IP address in the same menu.

- 1. Start your PC.
- 2. First, set a manual IP address in the network connection settings of the operating system.

Example: Microsoft Windows 7

Via the Control Panel, go to the Network and Sharing Center. You should see an active "Local Area Connection" link. Select this link.

- ► In the pop-up window select the "Properties" button.
- ► Double click "Internet Protocol Version 4 (TCP/IPv4)".
- ► Select "Use the Following IP Address".

• Enter the desired IP address.

- This address must be in the same subnetwork as the IP address of the device, e.g.:
- IP address of Liquiline: 192.168.1.212 (as configured previously)
- IP address for the PC: 192.168.1.213

3. Start the Internet browser.

4. If you use a proxy server to connect to the Internet:

Disable the proxy (browser settings under "Connections/LAN settings").

- 5. Enter the IP address of your device in the address line (192.168.1.212 in the example).
 - The system takes a few moments to establish the connection and then the CM44 web server starts. You might be asked for a password. The factory setting is "admin" for the user name and "admin" for the password.

- Enter the following address(es) to download logbooks:
 - 192.168.1.212/logbooks_csv.fhtml (for logbooks in CSV format) 192.168.1.212/logbooks_fdm.fhtml (for logbooks in FDM format)

Downloads in FDM format can be securely transmitted, saved and visualized with Endress+Hauser's "Field Data Manager Software".

 $(\rightarrow$ www.endress.com/ms20)

7.1.3 Operation

The menu structure of the web server corresponds to the onsite operation.

Menu/Setup			
Device tag: Measuri Device state: OK	ing point no. 1		
Software version: 01.06.0	00		
Homo	► Basic setup	?	
Home	 ▶ Basic setup ▶ General settings 	?	
ESC	General settings	?	
	 General settings Inputs 	? ?	

Example of web server (menu/language=English)

- Clicking a menu name or a function corresponds to pressing the navigator.
- You can make your settings conveniently via the computer keyboard.
 - Instead of using an Internet browser, you can also use FieldCare for configuration via ethernet. The ethernet DTM required for this is an integral part of the "Endress +Hauser Interface Device DTM Library".

Download: https://portal.endress.com/webdownload/FieldCareDownloadGUI/

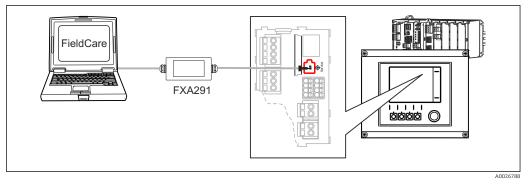
7.2 Service interface

You can connect the device to a computer via the service interface and configure it using "Fieldcare". Furthermore, configurations can also be saved, transferred and documented.

7.2.1 Connection

- **1.** Connect the service connector to the interface on the Liquiline base module and connect it to the Commubox.
- 2. Via the USB port, connect the Commubox to the computer running the Fieldcare software.

A0026780



E 48 Connection overview

7.2.2 Creating the data connection

1. Start Fieldcare.

2. Establish a connection to the Commubox. For this, select the ComDTM "CDI Communication FXA291"

3. Then select the "Liquiline CM44x" DTM and start the configuration.

You can now start online configuration via the DTM.

Online configuration competes with onsite operation, i.e. each of the two options blocks the other one. On both sides it is possible to take away access from the other side.

7.2.3 Operation

- In the DTM the menu structure corresponds to the onsite operation. The functions of the Liquiline soft keys are found in the main window on the left.
- Clicking a menu name or a function corresponds to pressing the navigator.
- You can make your settings conveniently via the computer keyboard.
- Via Fieldcare, you can save logbooks, make backups of configurations and transfer the configurations to other devices.
- You can also print out configurations or save them as PDFs.

7.3 Fieldbuses

7.3.1 HART

You can communicate using the HART protocol via current output 1.

- Connect the HART modem or handheld to current output 1 (communication load 230 500 Ohm).
- 2. Establish the connection via your HART device.
- **3.** Operate Liquiline via the HART device. To do so, follow the instructions in the manual.

More detailed information on HART communication is provided on the product pages on the Internet (\rightarrow BA00486C).

7.3.2 PROFIBUS DP

With the fieldbus module 485 and the appropriate device version, you can communicate via PROFIBUS DP.

More detailed information on PROFIBUS communication is provided on the product pages on the Internet (\rightarrow SD01188C).

7.3.3 Modbus

With the fieldbus module 485 and the appropriate device version, you can communicate via Modbus RS485 or Modbus TCP.

For Modbus TCP, you can use the ETH module as an alternative to module 485.

The RTU and ASCII protocols are available when connecting via Modbus RS485. You can switch to ASCII on the device.

► Connect the Modbus data cable to the terminals of the fieldbus module (RS 485) or to the RJ45 (TCP) port as described.

More detailed information on Modbus communication is provided on the product pages on the Internet (\rightarrow SD01189C).

7.3.4 EtherNet/IP

With the fieldbus module 485 or the ETH module and the appropriate device version, you can communicate via EtherNet/IP.

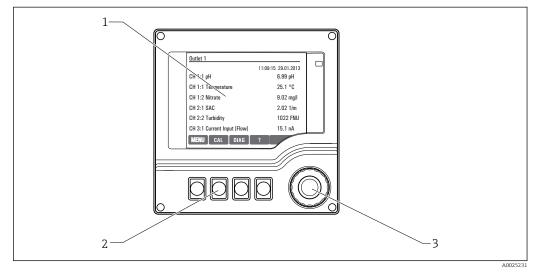
• Connect the EtherNet/IP data cable to the RJ45 socket of module 485 or ETH.

More detailed information on EtherNet/IP communication is provided on the product pages on the Internet (\rightarrow SD01293C).

8 Operation options

8.1 Overview

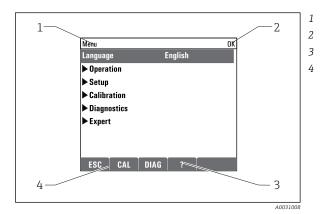
8.1.1 Display and operating elements (only with optional display)



■ 49 Overview of operation

- 1 Display (with red display background in alarm condition)
- 2 Soft keys (function depends on menu)
- 3 Navigator (jog/shuttle and press/hold function)

8.1.2 Display

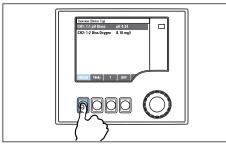


- Menu path and/or device designation
- Status display
- Help if available
- Assignment of the soft keys

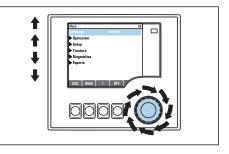
Endress+Hauser

8.2 Access to the operating menu via the local display

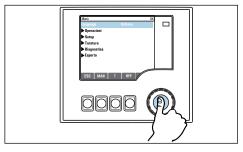
8.2.1 Operating concept (with optional display)



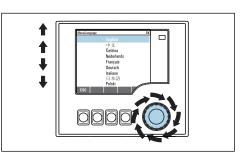
• Pressing the soft key: selecting the menu directly



• Turning the navigator: moving the cursor in the menu

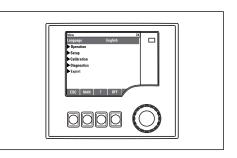


Pressing the navigator: launching a function



• Turning the navigator: selecting a value (e.g. from a list)





- Pressing the navigator: accepting the new value
- └► New setting is accepted

8.2.2 Locking or unlocking operating keys

Locking operating keys

1. Press the navigator for longer than 2 s.

 A context menu for locking the operating keys is displayed. You have the choice of locking the keys with or without password protection.
 "With password" means that you can only unlock the keys again by entering the correct password. This password is set here: Menu/Setup/General settings/ Extended setup/Data management/Change lock password.

- 2. Choose whether you want to lock without or without a password.
 - └→ The keys are locked. No more entries can be made. In the soft key bar, you will see the ☆symbol.

The password is 0000 when the device is delivered from the factory. **Make sure to note down any changes to the password**, as otherwise you will not be able to unlock the keypad yourself.

Unlocking operating keys

- 1. Press the navigator for longer than 2 s.
 - ← A context menu for unlocking the operating keys is displayed.

2. Select Key unlock.

- └ The keys are unlocked immediately if you did not choose to lock with a password. Otherwise you are asked to enter your password.
- 3. Only if keypad is password-protected: enter the right password.

8.3 Configuration options

8.3.1 Display only

- You can only read the values but cannot change them.
- Typical read-only values are: sensor data and system information
- Example: Menu/Setup/Inputs/../Sensor type

8.3.2 Picklists

- You receive a list of options. In a few cases, these also appear in the form of multiple choice boxes.
- Usually you just select one option; in rare instances you select one or more options.
- Example: Menu/Setup/General settings/Temperature unit

8.3.3 Numerical values

- You are changing a variable.
- The maximum and minimum values for this variable are shown on the display.
- Set a value within this range.
- Example: Menu/Operation/Display/Contrast

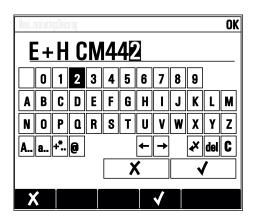
5							OK
			0	1	2	3	4
Min	5		5	6	7	8	9
Max	95)	<	+ \	C /
X		+	√				

8.3.4 Actions

- You trigger an action with the appropriate function.
- You know that the item in question is an action if it is preceded by the following symbol:
- Examples of typical actions include:
 - Deleting log entries
 - Saving or loading configurations
 - Triggering cleaning programs
- Example: Diagnostics/Logbooks/Configuration logbook/Delete all entries

8.3.5 Free text

- You are assigning an individual designation.
- Enter a text. You can use the characters in the editor for this purpose (upper-case and lower-case letters, numbers and special characters).
- Using the soft keys, you can:
 - Cancel your entries without saving the data (X)
- Delete the character in front of the cursor (🔌)
- Move the cursor back one position (
- Finish your entries and save (🗸)
- Example: Menu/Setup/General settings/Device tag



8.3.6 Tables

- Tables are needed to map mathematical functions .
- You edit a table by navigating through rows and columns with the navigator and changing the values of the cells.
- You only edit the numerical values. The controller automatically takes care of the engineering units.
- You can add lines to the table (**INSERT**) or delete lines from the table (**DEL**).
- Afterwards, you save the table (**SAVE**).
- You can also cancel your entries any time using the 🗡 soft key.
- Example: **Menu/Setup/Inputs**/pH/**Medium comp.**

9 Commissioning

9.1 Function check

WARNING

Incorrect connection, incorrect supply voltage

Safety risks for staff and device malfunctions

- Check that all connections have been established correctly in accordance with the wiring diagram.
- Ensure that the supply voltage matches the voltage indicated on the nameplate.

Saving the configuration settings as a screenshot

Yia the optional display , you can take screenshots at any time and save them to a SD card.

- 1. Insert an SD card into the SD card slot in the base module.
- 2. Press the navigator button for at least 3 seconds.
- 3. In the context menu select the **Screenshot**.
 - └ The current screen is saved as a bitmap file to the SD card in the "Screenshots" folder.

9.2 Power up

During the device startup phase, the relays and current outputs have an undefined status for a few seconds prior to initialization. Watch out for possible effects on any actuators which may be connected.

9.2.1 Setting the operating language

Configure language

- Switch on the supply voltage.
 Wait for initialization.
- 2. Press the soft key **MENU**. Set your language in the top menu item.
 - └ The device can now be operated in your chosen language.

9.2.2	Display behavior
-------	------------------

Menu/Operation/Display			
Function	Options	Info	
Contrast	5 to 95 % Factory setting 50 %	Adjust the screen settings to suit your working environment. Backlight = Automatic	
Backlight	Selection • On • Off • Automatic Factory setting Automatic	The backlighting is switched off automatically after a short time if a button is not pressed. It switches back on again as soon as you press the navigator button. Backlight = On The backlighting does not switch off automatically.	
Screen rotation	Selection Manual Automatic Factory setting Manual	If Automatic is selected, the single-channel measured value display switches from one channel to the next every second.	

9.3 User definable screens

Function	Options	Info
Meas. screen 1 6		You can create 6 measuring screens of your own and give them a name. The functions are identical for all 6 measuring screens.
Meas. screen	Selection • On • Off Factory setting Off	Once you have defined your own measuring screen, you can switch it on here. You can find the new screen under User definable screens in the measuring mode.
Label	Customized text, 20 characters	Name of the measuring screen Appears in the status bar of the display.
Number of lines	1 to 8 Factory setting 8	Specify the number of measured values displayed.
▶ Line 1 8	Display Information Label	Specify the content of Label in the submenu of each line.
Source of data	Selection None See list in "Info" column Factory setting None	 Select a source of data. You can choose from the following: Sensor inputs Heartbeat diagnostics of sensor inputs Controller Current inputs Fieldbus signals Mathematical functions Binary inputs and outputs Current outputs Relay Measuring range switching
Measured value Source of data is an input	Selection Depends on the input Factory setting None	You can display different main, secondary and raw measured values depending on the type of input. No options can be selected for outputs here.

Menu/Operation/User definable screens			
Function	Options	Info	
Actuator type Source of data is a controller	Selection None Bipolar Unipolar- Unipolar+ Factory setting None	For more information on controllers and manipulated variables: → 🖺 69.	
Label	Customized text, 20 characters	User-defined name for the parameter to be displayed	
\triangleright Set label to "%0V" ¹⁾	Action	If you perform this action you accept the parameter name that is automatically suggested. Your own parameter name (Label) is lost!	

 "%0V" here stands for text that depends on the context. This text is generated automatically by the software and inserted in place of %0V. In the simplest situations, the generated text could be the name of the measuring channel, for example.

9.4 Basic setup

Making basic settings

- 1. Go to the menu **Setup/Basic setup**.
 - └ Make the following settings.
- 2. **Device tag**: Give your device any name of your choice (max. 32 characters).
- **3. Set date**: Correct the set date if necessary.
- 4. **Set time**: Correct the set time if necessary.
 - └→ For quick commissioning, you can ignore the additional settings for outputs, relays etc. You can make these settings later in the specific menus.
- 5. Return to measuring mode by pressing and holding the soft key for **ESC** for at least one second.
 - Your controller now works with your basic settings. The sensors connected use the factory settings of the sensor type in question and the individual calibration settings that were last saved.

If you wish to configure your most important input and output parameters in the ${\bf Basic \ setup}$:

► Configure the current outputs, relays, limit switches, controllers, device diagnostics and cleaning cycles with the submenus which follow the time setting.

10 Operation

10.1 Display

10.1.1 Soft keys in the measurement mode

On the bottom row of the display you can find four soft keys in the measuring screens:

- With MENU, CAL and DIAG take you directly to the specific software menu.
- With **HOLD** you can activate an immediate, general hold for sensors. This also sets all the linked outputs, controllers and cleaning cycles to HOLD. Any sensor cleaning programs that are currently running are interrupted. However, you can also start manual sensor cleaning when a hold is active.

10.1.2 Measuring mode

There are different display modes: (press the navigator button to change the mode)

- (1) Overview of all the inputs and outputs
- (2) Main measured value of an input or output or the status of a relay
- (3) Main and secondary measured value of a sensor input
- (4) All measured values of a sensor input
- (5) Only for interface measurement:

Graphic display of the separation zone

There are also submenus:

- (6) User-defined screens
 - Choice of previously configured screens ($\rightarrow \implies 50$)
- (7) Heartbeat diagnostics

Quick overview of the health of the device and of each connected sensor that supports Heartbeat technology

Changing to display modes (2) - (5)

- Turn the navigator.
 - └ The display changes from channel to channel.

Sensor type	Main value	Main / secondary measured value	All values
pH, glass	pH value	pH value, temperature	Main value, Raw value, Temperature, Glass Impedance
Combined sensor pH and ORP	pH value or ORP or rH value	pH value or ORP or rH value, temperature	Main value, Raw value, Temperature, Glass Impedance
pH, ISFET	pH value	pH value, temperature	Main value, Raw value, Temperature
ORP	ORP	ORP, temperature	Main value, Raw value, Offset, Temperature
Conductivity, measured inductively	Conductivity, concentration	Conductivity, concentration, temperature	Main value, Raw value, Temperature
Conductivity, measured conductively	Conductivity, resistivity, concentration	Conductivity, resistivity, concentration, temperature	Main value, Raw value, Temperature
Oxygen, optical and amperometric	Oxygen	Oxygen, temperature	Partial pressure, Saturation , Concentration, Temperature
Disinfection	Chlorine or chlorine dioxide (depending on the sensor)	Chlorine or chlorine dioxide, temperature	Main value, Raw value, Temperature

Sensor type	Main value	Main / secondary measured value	All values
Nitrate	Nitrate	Nitrate, temperature	Main value, Raw value, Temperature
Turbidity	Turbidity	Turbidity, temperature	Main value, Raw value, Temperature
Spectral absorption coefficient (SAC)	SAC	SAC, temperature	Main value, Raw value, Temperature
Sludge level	Turbidity	Turbidity, temperature	Main value, Raw value, Temperature
Ammonium, ion- selective	Ammonium	Ammonium, temperature	Main value, Raw value, Temperature
Nitrate, ion-selective	Nitrate	Nitrate, temperature	Main value, Raw value, Temperature
Potassium, ion- selective	Potassium	Potassium, temperature	Main value, Raw value, Temperature
Interface measurement	UIS	UIS	Main value, Raw value, Temperature Separation zone (graphic)

Heartbeat diagnostics

(optional or with additional activation code)

- Heartbeat status information on the health of the device and the condition of the sensor Smileys for immediate status information: good, OK, bad
- Heartbeat diagnostics screen with graphic indicators for the health of the device and sensor and with a maintenance or (sensor-dependent) calibration timer
- The Heartbeat sensor health is the evaluation of the calibration results and the sensor diagnostic functions.

10.1.3 Device status

Icons on the display alert you to special devicestates.

Icon	Location	Description
F	Header bar	Diagnostic message "Failure"
М	Header bar	Diagnostic message "Maintenancerequest"
C	Header bar	Diagnostic message "Check"
S	Header bar	Diagnostic message "Outof specification"
←→	Header bar	Fieldbus orTCP/IP communication active
I	Header bar	Holdactive (forsensors)
I	At measured value	Hold for the actuator (currentoutput, limit switch etc.) is active
玊	At measured value 1)	An offset has been addedto the measured value
8	At measured value	Measured value in "Bad" or "Alarm" state
ATC	At measured value	Automatictemperature compensation active (forsensors)
MTC	At measured value	Manualtemperature compensation active (forsensors)
SIM	Header bar	Simulation mode active or Memocheck SIM connected
SIM	At measured value	The measured value is influencedby a simulated value
SIM	At measured value	The displayed measured valueis simulated (for sensors)
\odot	After the channel number	Heartbeat diagnostics: condition of sensor is good

Icon	Location	Description
8	After the channel number	Heartbeat diagnostics: condition of sensor is bad
	After the channel number	Heartbeat diagnostics: condition of sensor is OK

1) Only pH or ORP measurement

If two or more diagnostic messages occur simultaneously, only the icon for the message with the highest priority is shown on the display (for the order of priority according to NAMUR, → 🗎 110).

10.1.4 Assignment views

Assignment views, e.g. **Channel assignment view**, appear as the last function in many sections of the menu. You can use this function to see which actuators or functions are connected to an input or output. The assignments appear in hierarchical order.

10.2 General settings

10.2.1 Basic settings

Menu/Setup/General settings			
Function	Options	Info	
Device tag	Customized text, 32 characters	Select any name for your controller. Use the TAG name for example.	
Temperature unit	Selection ● °C ● °F ● K		
	Factory setting ℃		
Current output range	Selection • 020 mA • 420 mA	In accordance with Namur NE43, the linear range is from 3.8 to 20.5 mA (420 mA) or from 0 to 20.5 mA (020 mA). If the range is	
	Factory setting 420 mA	exceeded or undershot, the current value stops at the range limit and a diagnostic message (460 or 461) is output.	
Error current	0.0 to 23.0 mA Factory setting 22.5 mA	The function meets NAMUR NE43. Set the current value that should be output at the current outputs in the event of an error.	
output range = 020 mA output range = 420 mA	you should set an error curre you could also define a value current within the measuring	uring range. If you decided that your Current nt between 20.1 and 23 mA. If the Current < 4 mA as the error current. g range. In such instances pay attention to possible	
Alarm delay 0 to 9999 s Factory setting 0 s		The system only displays the errors that are present longer than the set delay time. This makes it possible to suppress messages that only occur briefly and are caused by normal process- specific fluctuations.	
Device hold	Selection Disabled Enabled	You can enable an immediate, general hold (for sensors) here. The function acts in the same way as the HOLD soft key in the screens.	
	Factory setting Disabled		

10.2.2 Date and time

Menu/Setup/General settings/Date/Time		
Function	Options	Info
Set date	Depends on the format	Editing mode: Day (two-digit): 01 to 31 Month (two-digit): 01 to 12 Year (four-digit): 1970 to 2106
Set time	Depends on the format	Editing mode: hh (hour): 00 to 23 / 0 am to 12 pm mm (minutes): 00 to 59 ss (seconds): 00 to 59
Extended setup		
Date format	Selection DD.MM.YYYY YYYY-MM-DD MM-DD-YYYY	Decide which date format you want to use.
	Factory setting DD.MM.YYYY	
Time format	Selection HH:MM am (12h) HH:MM (24h) HH:MM:SS (24h)	Decide whether you want to use the 12-hour or 24-hour clock. Seconds can also be displayed with the latter version.
	Factory setting HH:MM:SS (24h)	
Time zone	Selection None Choice of 35 time zones	None = Greenwich Mean Time (London).
	Factory setting None	
DST	Selection Off Europe USA Manual Factory setting Off	The controller adapts the summertime/normal time changeover automatically if you choose European or American daylight saving time. Manual means that you can specify the start and end of daylight saving time yourself. Here, two additional submenus are displayed in which you specify the changeover date and time.

10.2.3 Hold settings

Menu/Setup/General settings/Hold settings		
Function	Options	Info
Settings automatic Hold		
Hold release time	0 to 600 s Factory setting 0 s	The hold status is maintained for the duration of the delay time when you switch to the measuring mode.
Setup menu Diagnostics menu	Selection Disabled Enabled	Decide whether the device outputs should switch to the defined hold state when the particular menu is opened.
	Factory setting Disabled	
Calibration active	Factory setting Enabled	



If a device-specific hold status is activated, any cleaning previously started is interrupted. When a hold is active you can only start manual cleaning.

10.2.4 Logbooks

Logbooks record the following events:

- Calibration/adjustment events
- Operator events
- Diagnostic events

You define how the logbooks should store the data.

In addition, you can also define individual data logbooks .

- 1. Assign the logbook name.
- 2. Select the measured value to be recorded.
- 3. Set the recording rate (**Scan time**).
 - └ You can set the recording rate individually for every data logbook.

Further information on the logbooks: $\rightarrow \square$ 116.

Menu/Setup/General settings/Logbooks		
Function	Options	Info
Logbook ident	Customized text, 16 characters	Part of the file name when exporting a logbook
Event logbook	Selection • Off • Ring buffer • Fill up buffer Factory setting Ring buffer	All diagnostic messages are recorded Ring buffer If the memory is full, the most recent entry automatically overwrites the oldest entry. Fill up buffer If the memory is full, there is an overflow, i.e. no new values can be saved. The controller displays a corresponding diagnostic message. The memory then has to be cleared manually.
▶ Overflow warnings		
Event logbook = Fill up buffer		
Calibration logbook	Selection	Decide whether you want to receive a diagnostic
Diagnostic logbook	OffOn	message if the fill-up buffer of the relevant logbook overruns.
Configuration logbook	Factory setting Off	
▶ Data logbooks		
▶ New		You can create a maximum of 8 data logbooks.
Logbook name	Customized text, 20 characters	
Source of data	Selection Sensor inputs Heartbeat signals Controller Current inputs Fieldbus signals Binary inputs Mathematical functions Factory setting None	Select a data source for the logbook entries. You can choose from connected sensors, available controllers, current inputs, fieldbus signals, binary input signals and mathematical functions.
Measured value	Selection depend on Source of data Factory setting None	You can record different measured values depending on the data source.

Options	Info
•	
Factory setting 0:01:00	Minimum interval between two entries Format: H:MM:SS
Selection Ring buffer Fill up buffer 	Ring buffer If the memory is full, the most recent entry automatically overwrites the oldest entry.
Factory setting Ring buffer	Fill up buffer If the memory is full, there is an overflow, i.e. n new values can be saved. The controller display a corresponding diagnostic message. The memory then has to be cleared manually.
Selection Off 	Decide whether you want to receive a diagnosti message if the fill-up buffer of the relevant
• On	logbook overruns.
Factory setting Off	
Action	Only if you want to create another data logbool immediately. You add a new data logbook at a later date using New .
Action	This allows you to exit the menu New .
Action	Appears if you have created more than one dat logbook. With one mouse click, you can start or stop recording all the data logbooks.
	The name of this submenu is based on the nam of the logbook and only appears once you have created a logbook.
al times if you have several	data logbooks.
Read only	This is for information purposes only. If you want to record another value, delete this logbod and create a new data logbook.
Read only	Displays the days, hours and minutes remaining
i caa omy	until the logbook is full.
Read only	Displays the number of entries remaining until
	the logbook is full.
Customized text, 20 characters	You can change the name here again.
0:00:01 to 1:00:00	As above
Factory setting 0:01:00	Minimum interval between two entries Format: H:MM:SS
Selection Ring buffer Fill up buffer 	Ring buffer If the memory is full, the most recent entry automatically overwrites the oldest entry.
Factory setting Ring buffer	Fill up buffer If the memory is full, there is an overflow, i.e. n new values can be saved. The controller display a corresponding diagnostic message. The memory then has to be cleared manually.
Selection Off 	Decide whether you want to receive a diagnosti message if the fill-up buffer of the relevant
• On	logbook overruns.
	I0:00:01 to 1:00:00Factory setting 0:01:00Selection • Ring bufferFactory setting Ring bufferFactory setting Off0 ActionActionActionActionActionRead onlyRead onlyRead onlySelection • 0:0:01 to 1:00:00Factory setting 0:0:0:01 to 1:00:00Factory setting • Ring buffer • Fill up buffer • Fill up bufferSelection • Ring buffer • Fill up bufferSelection • Ring buffer • Fill up buffer • Fill up bufferFactory setting Ring bufferSelection • Ring buffer

Menu/Setup/General settings/Logbooks		
Function	Options	Info
Line plotter		Menu to define the graphic display
Axes	Selection • Off • On Factory setting On	Should the axes (x, y) be displayed (On) or not (Off)?
Orientation	Selection Horizontal Vertical Factory setting Horizontal	You can choose whether the value curves should be displayed from left to right (Horizontal) or from top to bottom (Vertical). If you want to display two data logbooks simultaneously, make sure that both logbooks have the same settings here.
X-Description	Selection	Decide whether a description should be
Y-Description	 Off On Factory setting 	displayed for the axes and whether gridlines should be shown. In addition, you can also
Grids		decide whether pitches should be displayed.
Pitches	On	
X Pitch/Grid distance	10 to 50%	Specify the pitches.
Y Pitch/Grid distance	Factory setting	
⊳ Remove	Action	This action removes the data logbook. Any data that have not been saved are lost.

Example: New data logbook (Setup/General settings/Logbooks/Data logbooks/New)

1. Make the settings:

- Logbook name
 - Assign a name. Example: "01".
- Source of data Select a data source. Example Sensor connected to channel 1 (CH1).
- Measured value
- Select the measured value to be recorded. Example: pH value.
- Scan time

Specify the time interval between two logbook entries.

- Data logbook Activate the logbook: specify the data storage method.
- 2. Run the ../**Finished**: action.
 - └ The device shows the new logbook in the list of data logbooks.
- 3. Select data logbook "01".
 - ← Additional display: **Log time left**in the measuring mode.

4. Only for **Fill up buffer**:

Choose **Overflow warning**: **On** or **Off**in the measuring mode.

- └ **On**: The device displays a diagnostic message in the event of memory overflow.
- 5. Submenu **Line plotter**: specify the type of graphic representation.

10.2.5 Advanced setup

Diagnostics settings

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The list of diagnostic messages displayed depends on the path selected. There are device-specific messages, and messages that depend on what sensor is connected.

Function	Options	Info
List of diagnostic messages		Select the message to be changed. Only then car you make the settings for this message.
Diag. code	Read only	
Diagnostic message	Selection • On • Off Factory setting Depends on the message	You can deactivate or reactivate a diagnostic message here. Deactivating means: • No error message in the measuring mode • No error current at the current output
Error current	Selection • On • Off	Decide whether an error current should be output at the current output if the diagnostic message display is activated.
	Factory setting Depends on the message	In the event of general device errors, the error current is output at all the current outputs. In the event of channel-specific errors, the error current is only output at the assigned current output.
Status signal	Selection Maintenance (M) Out of specification (S) Function check (C) Failure (F) Factory setting Depends on the message	The messages are divided into different error categories in accordance with NAMUR NE 107. Decide whether you want to change a status signal assignment for your application.
Diag. output	Selection None Alarm relay Binary output Relay 1 to n (depends on the device version) Factory setting None	You can use this function to select an output to which the diagnostic message should be assigned. Before being able to assign the message to an output you must first configure a relay output t Diagnostics . (Menu/Setup/Outputs: Assign the Diagnostic function and set the Operating mode to as assigned .)
An alarm relay is alwa	ys available, regardless of the dev	rice version. Other relays are optional.
Cleaning program (for sensors)	Selection None Cleaning 1 Cleaning 2 Cleaning 3 Cleaning 4	Decide whether the diagnostic message should trigger a cleaning program. You can define the cleaning programs under: Menu/Setup/Additional functions/Cleaning.
	Factory setting None	
Detail information	Read only	Here you can find more information on the diagnostic message and instructions on how to resolve the problem.

HART bus address

The list of diagnostic messages displayed depends on the path selected. There are device-specific messages, and messages that depend on what sensor is connected.

Menu/Setup/General settings/Extended setup/HART		
Function Options Info		Info
Bus address	0 to 63 Factory setting 0	You can change the device address to integrate several HART devices in a single network (Multidrop mode).

If you reset the device to the factory settings (**Diagnostics/Reset/Factory default**), the bus address is not reset. Your setting is retained.

PROFIBUS DP

Menu/Setup/General settings/Extended setup/PROFIBUS		
Function	Options	Info
Enable	Selection • Off • On	You can switch off communication at this point. The software can then only be accessed via local operation.
	Factory setting On	
Termination	Read only	If the device is the last in the bus, you can terminate via the hardware. $\rightarrow \bigoplus 37$
Bus address	1 to 125	If you have addressed the bus via hardware (DIP switches on the module, $\rightarrow {}$ 37), you can only read the address here. If an invalid address is set via the hardware, you have to assign a valid address for your device either here or via the bus.
Ident number	Selection Automatic PA-Profile 3.02 (9760) Liquiline CM44x (155D) Manufacturer specific	
	Factory setting Automatic	

Modbus

Menu/Setup/General settings/Extended setup/Modbus		
Function	Options	Info
Enable	Selection • Off • On Factory setting On	You can switch off communication at this point. The software can then only be accessed via local operation.
Termination	Read only	If the device is the last in the bus, you can terminate via the hardware. $\rightarrow \textcircled{B} 37$

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Menu/Setup/General settings/Extended setup/Modbus		
Function	Options	Info
Settings		
Transmission Mode	Selection TCP RTU ASCII Factory setting (Modbus-RS485 only) RTU	The transmission mode is displayed depending on the version ordered. In the case of RS485 transmission, you can choose between RTU and ASCII . There are no choices for Modbus-TCP.
Baudrate <i>Modbus-RS485 only</i>	Selection 1200 2400 4800 9600 19200 38400 57600 115200 Factory setting 19200	
Parity Modbus-RS485 only	Selection Even (1 Stopbit) Odd (1 Stopbit) None (2 Stopbit) Factory setting Even (1 Stopbit)	
Byte order	Selection • 1-0-3-2 • 0-1-2-3 • 2-3-0-1 • 3-2-1-0 Factory setting 1-0-3-2	
Watchdog	0 to 999 s Factory setting 5 s	If no data transmission takes place for longer than the time set, this is an indicator that communication has been interrupted. After this time, input values received via the Modbus are considered to be invalid.

Menu/Setup/General settings/Extended setup/Modbus

Web server

Menu/Setup/General settings/Extended setup/Webserver		
Function	Options	Info
Webserver	Selection • Off • On Factory setting	You can switch off communication at this point. The software can then only be accessed via local operation.
	On	
Webserver TCP Port 80	Read only	The Transmission Control Protocol (TCP) is an arrangement (protocol) as to how data should be exchanged between computers. A port is a part of an address which assigns data segments to a network protocol.
Webserver login	Selection • Off • On Factory setting On	You can switch user administration on and off at this point. This makes it possible to create multiple users with password access.

Menu/Setup/General settings/Extended setup/Webserver		
Function	Options	Info
User administration		
List of users already created	View/edit	You can change user names or passwords or delete users. A user is already created at the factory: "admin" with password "admin".
New user:		
Name	Free text	Create new user
Enter new user password	Free text	 Press INSERT. Assign any name to the new user.
Confirm new user password	Free text	 3.Select a password for the user. 4.Confirm the password. You can now change the password at any
Change user password	Free text	time.

EtherNet/IP

Menu/Setup/General settings/Extended setup/Ethernet		
Function	Options	Info
Enable	Selection • Off • On Factory setting On	You can switch off communication at this point. The software can then only be accessed via local operation.
Settings		
Link settings	Selection Auto negotiation 10MBps Half duplex 10MBps Full duplex 100MBps Half duplex 100MBps Full duplex Factory setting Auto negotiation	 Transmission methods of the communication channels Full duplex: Data can be transmitted simultaneously in both directions. Half-duplex: Data can only be transmitted alternately in both directions, i.e. not at the same time. Source: Wikipedia
DHCP	Selection • Off • On Factory setting On	The Dynamic Host Configuration Protocol (DHCP) makes it possible to assign the network configuration to clients via a server. With DHCP, it is possible to automatically integrate the device into an existing network without the need for manual configuration. Normally only the automatic assignment of the IP address must be configured at the client. During startup, the IP address, the netmask and the gateway are retrieved from a DHCP server. Do you want to assign the IP address of the device manually? If so, you must set DHCP = Off .
IP-Address	XXX.XXX.XXX	An IP address is an address in computer networks which are based on the Internet protocol (IP). You can only set the IP address if DHCP is switched off.

Menu/Setup/General settings/Extended setup/Ethernet		
Function	Options	Info
Netmask	XXX.XXX.XXX	On the basis of the IP address of a device, the netmask specifies which IP addresses this device searches for in its own network and which addresses it could access in other networks via a router. It therefore divides the IP address into a network part (network prefix) and a device part. The network part must be identical for all devices in the individual network, and the device part must be different for every device within the network.
Gateway	X.X.X.X	A gateway (protocol converter) enables communication between networks that are based on completely different protocols.
Service switch	Read only	
MAC-Address	Read only	The MAC address (Media Access Control address) is the hardware address of every individual network adapter which is used to uniquely identify the device in a computer network.
EtherNetIP Port 44818	Read only	A port is a part of an address which assigns data segments to a network protocol.

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Accepting settings

Have you changed settings manually, such as the IP address?

▶ Before you leave the **Ethernet** menu: Select **SAVE**to apply your settings.

└ In the **DIAG/System information** menu you can check whether the new settings are used.

Data management

Firmware update

Please contact your local sales office for information on firmware updates available for your controller and its compatibility with earlier versions.

The current firmware version can be found at: Menu/Diagnostics/System information/.

Back up your current setup and your logbooks to an SD card.

To install a firmware update, you must have the update available on an SD card.

1. Insert the SD card into the controller card reader.

2. Go to: Menu/Setup/General settings/Extended setup/Data management/ Firmware update.

└ The update files on the SD card are displayed.

3. Select the desired update and select yes when the following question is displayed:

The current firmware will be overwritten.

After this the device will reboot.

Do you want to proceed?

└ The firmware is loaded and the device is then started with the new firmware.

Saving the setup

Saving the setup gives you the following advantages:

- Copying settings for other devices
- Quick and easy switching between various setups, e.g. for different user groups or for recurring sensor type change
- Restoring a tried-and-tested setup, e.g. if you have changed a lot of settings and no longer know what the original settings were
- 1. Insert the SD card into the controller card reader.
- 2. Go to: Menu/Setup/General settings/Extended setup/Data management/Save setup.
- 3. **Name**: Assign a file name.
- 4. Then select Save.
 - If you have already assigned the file name, you will be asked whether you want to overwrite the existing setup.
- 5. Select **OK** to confirm, or cancel the operation and assign a new file name.
 - Your setup is stored on the SD card and you can upload it quickly to the device at a later date.

Loading the setup

When you load a setup, the current configuration is overwritten.

- 1. Insert the SD card into the controller card reader. A setup must have been saved to the SD card.
- 2. Go to: Menu/Setup/General settings/Extended setup/Data management/Load setup.
 - A list of all the setups on the SD card is displayed.
 An error message is displayed if there is no valid setup on the card.
- 3. Select the desired setup.
 - └ A warning is displayed:

The current parameters will be overwritten and the device will reboot. Warning: Please note that cleaning and controller programs can be active. Do you want to proceed?

4. Select **OK** to confirm, or cancel the operation.

└ If you select **OK** to confirm, the device restarts with the desired setup.

Exporting the setup

Exporting the setup offers the following advantages:

- Export in XML format with a stylesheet for formatted display in an XML-compatible application such as Microsoft Internet Explorer
- Importing the data (drag and drop the XML file into a browser window)
- 1. Insert the SD card into the controller card reader.
- 2. Go to: Menu/Setup/General settings/Extended setup/Data management/Export setup.
- 3. Name: Assign a file name.
- 4. Then select **Export**.
 - If you have already assigned the file name, you will be asked whether you want to overwrite the existing setup.

5. Select **OK** to confirm, or cancel the operation and assign a new file name.

└ Your setup is saved on the SD card in the "Device" folder.

You cannot upload the exported setup to the device again. You must use the **Save setup** function for this purpose. This is the only way you can save a setup to an SD card and reload it later on or upload it to other devices.

Activation code

You require activation codes for:

- Additional functions, e.g. fieldbus communication
- Firmware upgrades
- Retrofits, e.g. deactivation of fieldbus protocols

If activation codes are available for your device, these codes are provided on the inner nameplate. The corresponding device functions are activated at the factory. You only require the codes if servicing the device or deactivating fieldbus protocols.

1. Enter the activation code: Menu/Setup/General settings/Extended setup/Data management/Activation code.

- 2. Confirm your entry.
 - └ Your new hardware or software function is activated and can be configured.

The table below tells you what functions an activation code enables:

Function	Activation code beginning with
Second Memosens input (CM442R only)	062
Deactivation of fieldbus when 485 or ETH module is removed $^{1)}$	0B0
Two current outputs (BASE-E module only)	081
HART	0B1
PROFIBUS PA	0B2
PROFIBUS DP	0B3
Modbus TCP	0B4
Modbus RS485	0B5
EtherNet/IP	0B6
Measuring range switching, set 1	211
Measuring range switching, set 2 ²⁾	212
Feedforward control	220
Chemoclean Plus	25
Mathematical function Cation exchanger capacity	301
Heartbeat monitoring	2D1
Heartbeat verification	2E1

- The device displays an error message if you remove the 485 or ETH module with the fieldbus protocol activated. You must now enter the activation code on the inside nameplate. The fieldbus is only deactivated once you do this. Afterwards you must enter the appropriate activation code to activate current outputs of the base module. Additional current outputs (CM444R and CM448R only) are activated as soon as the corresponding module is used.
- 2) When you order the "Measuring range switching" option, you receive two activation codes. Enter both codes to have two sets for measuring range switching.

Change password

You can lock the operating keys with a password (access the context menu by pressing the navigator for longer). The keys can then only be enabled by entering the right password.

Set the password to lock the keys here: **Menu/Setup/General settings/Extended setup/ Data management/Change lock password**.

- 1. Enter the current password (factory setting 0000).
 - └ Enter new lock password
- 2. Enter a new password.
 - └ Confirm new lock password
- 3. Enter the new password again.
 - ← The lock password has been changed successfully.

Press the navigator for longer to return to the measuring mode.

10.3 Current inputs

The input can be used as the data source for limit switches and logbooks, for example. Furthermore, external values can be made available as set points for controllers.

Menu/Setup/Inputs/Current input x:y ¹⁾		
Function	Options	Info
Mode	Selection • Off • 0 - 20mA • 4 - 20mA Factory setting 4 - 20mA	Select the same current range as in the data source (connected device).
Input mode	Selection • Flow rate • Parameter • Current Factory setting Current	Select the input variable.
Meas. value format	Selection # #.#. #.### Factory setting #.#	Specify the number of decimal places.
Parameter name Input mode = Parameter	Customized text, 16 characters	Assign a useful name, such as the parameter name, which the data source uses.
Unit of measure Input mode = Parameter	Customized text, 16 characters	You cannot choose the unit from a list. If you want to use a unit, you must enter it here as customized text.
Lower range value Input mode = Parameter	-20.0 Upper range value <unit measure="" of=""> Factory setting 0.0 <engineering unit=""></engineering></unit>	Enter the measuring range. The lower and upper range values are assigned to the 0 or 4 mA value and the 20 mA value respectively. The system uses the engineering unit which you entered beforehand.
Upper range value Input mode = Parameter	Lower range value to 10000.0 <engineering unit> Factory setting 10.0 <engineering unit=""></engineering></engineering 	
Damping	0 to 60 s Factory setting 0 s	The damping causes a floating average curve of the measured values over the time specified.

1) x:y = slot no. : input number

10.4 Outputs

10.4.1 Current outputs

The basic version of the device always has two current outputs.

You can configure additional current outputs with extension modules.

Setting the current output range

• Menu/Setup/General settings: select 0..20 mA or 4..20 mA.

Function	Options	Info
Current output	Options • Off • On Factory setting	Use this function to activate or deactivate a variable being output at the current output
Source of data	Off Options None	The sources of data on offer depend on your device version.
	Connected inputsController	The all the sensors and controllers connected to inputs are available for selection.
	Factory setting None	
Measured value	Options None Depends on the Source of data 	The measured value you can select depends on the option selected under Source of data .
	Factory setting None	
Apart from measured value The best way to do so is b	ues from connected sensors, ye	l in the Measured value <i>depending on the</i> Source ou can also select a controller as the data source. ons menu. Here, you can select and configure the
Range lower value	Range of adjustment and	You can output the entire measuring range or
Range upper value	factory settings depending on the Measured value	just some of it at the current output. For this purpose, specify the upper and lower range values in accordance with your requirements.
Hold behavior	Options Freeze Fixed value None 	Freeze The device freezes the last current value.
		Fixed value You define a fixed current value that is output a
	Factory setting Depends on the channel:output	the output.
		None A hold does not affect this current output.
** 11 .	0.0 to 23.0 mA Specify which current should be o	Specify which current should be output at this
Hold current		current output in the hold state.

1) x:y = slot: output number

Measured value depending on the Source of data

Source of data	Measured value
pH Glass	Selection
pH ISFET	 Raw value mV pH Temperature

Source of data	Measured value
ORP	Selection • Temperature • ORP mV • ORP %
Oxygen (amp.)	Selection
Oxygen (opt.)	 Temperature Partial pressure Concentration liquid Saturation Raw value nA (only Oxygen (amp.)) Raw value µs (only Oxygen (opt.))
Cond i	Selection Temperature
Cond c	Conductivity
Cond c 4-pol	 Resistance (only Cond c) Concentration (only Cond i and Cond c 4-pol)
Disinfection	Selection Temperature Sensor current Concentration
ISE	Selection Temperature pH Ammonium Nitrate Potassium Chloride
TU/TS	Selection
TU	 Temperature Turbidity g/l (only TU/TS) Turbidity FNU (only TU/TS) Turbidity Formazine (only TU) Turbidity solid (only TU)
Nitrate	Selection Temperature NO3 NO3-N
Ultrasonic interface	Selection Temperature Interface Turbidity
SAC	Selection • Temperature • SAC • Transm. • Absorption • COD • BOD

Source of data	Measured value
Controller 1	Selection
Controller 2	 Bipolar (only for current outputs) Unipolar+ Unipolar-
Mathematical functions	All the mathematical functions can also be used as a data source and the calculated value can be used as the measured value.

Outputting the controller manipulated variable via the current output

Assign **Unipolar+** to the output to which an actuator that can increase the measured value is connected. Assign **Unipolar-** to the output to which an actuator that can decrease the measured value is connected.

To output the manipulated variable of a two-sided controller, positive manipulated variables and negative manipulated variables generally have to be output to different actuators, as most actuators are able to influence the process in one direction only (not in both). For this purpose, the instrument splits the bipolar manipulated variable y into two unipolar manipulated variables, y+ and y-.

Only the two unipolar manipulated variable parts are available for selection for outputting to modulated relays. If outputting the values via a current output, you also have the possibility of outputting the bipolar manipulated variable y to one current output only (split range).

10.4.2 Alarm relay and optional relays

The basic version of the device always has one alarm relay. Additional relays are also available depending on the version of the device.

The following functions can be output via a relay:

- Limit switch status
- Controller manipulated variable for controlling an actuator
- Diagnostic messages
- Status of a cleaning function in order to control a pump or a valve

You can assign a relay to multiple inputs in order to clean several sensors with just one cleaning unit, for example.

Function	Options	Info
Function	Options Off Limit switch Controller Diagnostics Cleaning (sensor) Factory setting Alarm relays: Diagnostics Other relays: Off	The following functions depend on the option selected. These versions are illustrated individually in the following sections to provide a clearer understanding of the options. Function = Off Switches off the relay function and means no further settings are required.

Menu/Setup/Outputs/Alarm relay or relay at channel no.

Outputting the status of a limit switch

Function = Limit switch		
Function	Options	Info
Source of data	Options None Limit switch 1 8 Factory setting None	Select the limit switch via which the status of the relay is to be output. The limit switches are configured in the menu: Setup/Additional functions/Limit switches in the measuring mode.

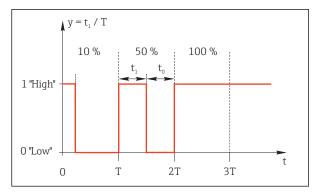
Outputting the manipulated variable of a controller

To output a controller manipulated variable via a relay, the relay is modulated. The relay is energized (pulse, t_1) and is then de-energized (interval, t_0).

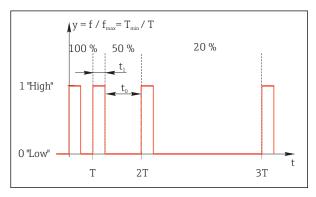
Function = Controller		
Function	Options	Info
Source of data	Options None Controller 1 Controller 2 Factory setting None	Select the controller that should act as the data source.
Operating mode	Options • PWM • PFM Factory setting PWM	PWM=pulse width modulation PFM=pulse frequency modulation

1. **PWM** (pulse width modulation):

The duty cycle is varied within a period \mathbf{T} (T=t₁+t₀). The cycle duration remains constant.



- ☑ 50 Typical application: solenoid valve
- 2. **PFM** (pulse frequency modulation): Here, pulses of a constant length (t_1) are output and the interval between the pulses varies (t_0) . At a maximum frequency, $t_1 = t_0$.



■ 51 Typical application: dosing pump

Function = Controller				
Function	Options	Info		
Actuator type	Options • None • Unipolar(-) • Unipolar(+) Factory setting None	Here you specify what part of the controller should power the relay. Unipolar(+) is the part of the manipulated variable which the controller uses to increase the process value (e.g. for heating purposes). On the other hand, select Unipolar(-) if you want to connect an actuator to the relay that causes the controlled variable to drop (e.g. for cooling purposes).		
Cycle duration Operating mode = PWM	Shortest turn-on time to 999.0 s Factory setting 10.0 s	Specify the cycle duration within which the duty cycle should be varied (only PWM).		
The settings for Cycle duration and Shortest turn-on time mutually affect one another. The following applies Cycle duration \geq Shortest turn-on time .				
Shortest turn-on time Operating mode = PWM	0.3 s to Cycle duration Factory setting 0.3 s	Pulses that are shorter than this limit value are not output in order to conserve the actuator.		
Maximum frequency Operating mode = PFM	1 to 180 min ⁻¹ Factory setting 60 min ⁻¹	Maximum number of pulses per minute The controller calculates the pulse duration based on this setting.		

Outputting diagnostic messages via the relay

If a relay is defined as a diagnostic relay (**Function** = **Diagnostics**), it works in the **"fail-safe mode"**.

This means that the relay is always energized ("normally closed", n.c.) in the basic state if an error is not present. In this way it can also indicate a drop in voltage, for example. The alarm relay always works in the failsafe mode.

You can output two categories of diagnostic messages via the relay:

- Diagnostic messages from one of the 4 Namur classes $\rightarrow \implies 110$
- Diagnostic messages which you have individually assigned to the relay output

A message is individually assigned to the relay output at 2 specific points in the menu:

- Menu/Setup/General settings/Extended setup/Diagnostics settings/Diag. behavior (device-specific messages)
- Menu/Setup/Inputs/<Sensor>/Extended setup/Diagnostics settings/Diag. behavior (sensor-specific messages)

Before being able to assign the relay output to a special message in **Diag. behavior** you must first configure **Outputs**/Relay x:y or /**Alarm relay/Function = Diagnostics** .

Function = Diagnostics			
Function	Options	Info	
Operating mode	Options • as assigned • Namur M • Namur S • Namur C • Namur F Factory setting as assigned	as assigned If this option is selected, the diagnostic messages which you have individually assigned to the relay are output via the relay. Namur M Namur F If you decided to use one of the Namur classes, all the messages that are assigned to the individual class are output via the relay. You can also change the Namur class assignment for every diagnostic message. (Menu/Setup/General settings/Extended setup/Diagnostics settings/Diag. behavior or Menu/Setup/Inputs/ <sensor>/Extended setup/Diagnostics settings/Diag. behavior)</sensor>	
Attributed diagnostic messages	Read only	All the messages assigned to the relay output	
Operating mode = as assigned		appear on the display. You do not have the option of editing the information here.	

Outputting the status of a cleaning function

Function = Cleaning			
Function	Options	Info	
Assignments	 Options None Depends on the type of cleaning Factory setting None 	 Here you can specify how a cleaning function should be displayed for the relay. Depending on the cleaning program selected (Menu/Setup/Additional functions/Cleaning) you can choose from the following: Cleaning type = Standard clean Cleaning 1 - Water, Cleaning 2 - Water, Cleaning 3 - Water, Cleaning 4 - Water Cleaning type = Chemoclean Cleaning 1 - Cleaner, Cleaning 2 - Water, Cleaning 3 - Cleaner, Cleaning 3 - Water, Cleaning 3 - Cleaner, Cleaning 4 - Water, Cleaning 4 - Cleaner, Cleaning 1 - Water, Cleaning 2 - Cleaner, Cleaning 4 - Water, Cleaning 2 - Cleaner, Cleaning 4 - Water, Cleaning 2 - Cleaner 	

1) %0V is variable text which you can assign in Menu/Setup/Additional functions/Cleaning/Chemoclean Plus/Output label 1 ... 4 .

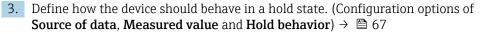
10.4.3 HART

Specify which device variables should be output via HART communication.

You can define a maximum of 16 device variables.

1. Define the data source.

- └ You can choose from sensor inputs and controllers.
- 2. Choose the measured value which should be output.



Please note that if you select **Hold behavior** = **Freeze**, the system not only flags the status but also actually "freezes" the measured value.

More information is provided in:

Operating Instructions "HART Communication", BA00486C

10.4.4 PROFIBUS DP

Device variables (device \rightarrow PROFIBUS)

Specify which process values should be mapped to the PROFIBUS function blocks and are thereby available for transmission via PROFIBUS communication.

You can define a maximum of 16 device variables (AI Blocks).

- 1. Define the data source.
 - └ You can choose from sensor inputs, current inputs and mathematical functions.
- 2. Choose the measured value which should be transmitted.

In addition, you can define 8 binary variables (DI Blocks):

- 1. Define the data source.
- 2. Select the limit switch or relay whose status should be transmitted.

PROFIBUS variables (PROFIBUS \rightarrow device)

A maximum of 4 analog (AO) and 8 digital (DO) PROFIBUS variables are available as measured values in the controller, limit switch or current output menus.

Example: Using an AO or DO value as the set point for the controller

Menu/Setup/Additional functions/Controller 1

1. In the menu mentioned, define PROFIBUS as the data source.

2. Select the desired analog output (AO) or digital output (DO) as the measured value.

More information is provided in:

Guidelines for Communication via PROFIBUS, SD01188C

10.4.5 Modbus RS485 and Modbus TCP

Specify which process values should be output via Modbus RS485 communication or via Modbus TCP.

In the case of Modbus RS485, you can switch between the RTU and the ASCII protocol.

You can define a maximum of 16 device variables.

1. Define the data source.

└ You can choose from sensor inputs and controllers.

- 2. Choose the measured value which should be output.
- 3. Define how the device should behave in the event of a "Hold" . (Configuration options of **Source of data**, **Measured value** and **Hold behavior**) $\rightarrow \cong 67$

Please note that if you select **Hold behavior** = **Freeze**, the system not only flags the status but also actually "freezes" the measured value.

More information is provided in:

Guidelines for Communication via Modbus, SD01189C

10.4.6 EtherNet/IP

Specify which process values should be output via EtherNet/IP communication.

You can define a maximum of 16 analog device variables (AI).

- 1. Define the data source.
 - └ You can choose from sensor inputs and controllers.
- 2. Choose the measured value which should be output.
- **3.** Define how the device should behave in the event of a "Hold" . (Configuration options of **Source of data**, **Measured value** and **Hold behavior**) $\rightarrow \triangleq 67$
- 4. In the case of controllers, also specify the type of manipulated variable.

Please note that if you select **Hold behavior** = **Freeze**, the system not only flags the status but also actually "freezes" the measured value.

In addition you can define digital device variables (DI):

- Define the data source.
 - ← You can choose from relays, binary inputs and limit switches.

More information is provided in:

Guidelines for Communication via EtherNet/IP, SD01293C

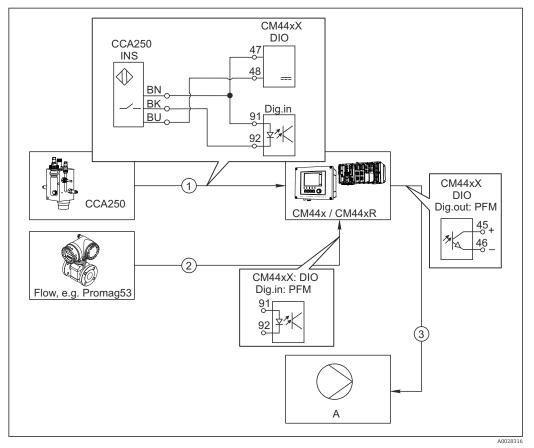
10.5 Binary inputs and outputs

Hardware options, such as the "DIO" module with 2 digital inputs and 2 digital outputs or fieldbus module "485" enable the following:

- Via a digital input signal
 - measuring range switching for conductivity (upgrade code required, $\rightarrow \implies 137$)
 - switching between different calibration datasets in the case of optical sensors
 - external hold
 - a cleaning interval to be triggered
 - PID controller switch-on/switch-off, e.g. via the proximity switch of the CCA250
 - the use of the input as an "analog input" for pulse-frequency modulation (PFM)
- Via a digital output signal
 - diagnostic states, point level switches, or similar states transmitted statically (similar to a relay)
 - the dynamic transmission (comparable to a non-wearing "analog output") of PFM signals, e.g. to control dosing pumps

10.5.1 Application examples

Chlorine control with feedforward control



E 52 Example of chlorine control with feedforward control

- 1 Connection of the inductive proximity switch INS of CCA250 to the digital input of the DIO module
- 2 Connection of the signal from a flowmeter to the digital input of the DIO module
- 3 Activation of a (pulse) dosing pump via a digital output of the DIO module
- A Dosing pump

Utilize the advantage of the effectively wear-free control with binary outputs versus a control system with relay. With pulse frequency modulation (PFM), it is possible to achieve virtually continuous dosing using a dosing pump with higher input frequency.

- 1. Connect the proximity switch INS of the CCA250 assembly to a digital input of the DIO module (e.g. slot 6, port 1).
- Configure a controller in the software and for the source select the binary input (e.g. Binary input 1) to which the proximity switch is connected. (Menu/Additional functions/Controllers/Controller 1/Controller Enable = Binary input 1)
- 3. Signal type: For the selected input, select the factory setting (Static signal).
- 4. Connect the measured value of a flowmeter to the second input of the DIO module (e.g. slot 6, port 2).

5. Signal type: for this input, select PFM. (Menu/Inputs/Binary input 6:2/Signal type = PFM)

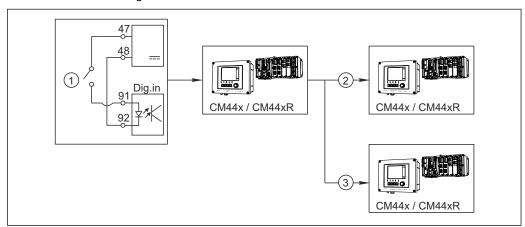
- 6. **Input mode**: select the corresponding measured value (**Flow rate**).
 - You can now use the input you have just configured as the disturbance variable for your controller ²).

²⁾ An activation code, Order No. 71211288, is necessary for the "feedforward control" function.

- Disturbance variable: In the controller menu, select the binary input to which the flow measured value is connected. (Menu/Additional functions/Controllers/Controller 1/Disturbance variable/Source of data = Binary input 6:2 and Measured value = PFM value)
- You can activate a dosing pump through PFM via a digital output of the DIO module. Connect the pump to an output of the DIO module (e.g. slot 6, port 1) and choose the following settings in the menu: Menu/Outputs/Binary output 6:1/Signal type = PFM and Source of data = Controller 1.

Take the direction of action of your dosing into account. Select the correct parameter (Actuator type = Unipolar+ or Unipolar-).

You must make additional settings in the controller menu to fully customize the control to suit your process conditions.



CM44x as the cleaning master

■ 53 Example of a central cleaning control

1 External cleaning trigger at the binary input

- 2 Transferring the external hold over binary output to other measuring devices without connected cleaning functions
- 3 Transferring the cleaning trigger over a binary output to other self-cleaning measuring points
- **1.** An external trigger actuates a cleaning operation at the master. A cleaning unit is connected via a relay or a binary output, for example.
- 2. The cleaning trigger is transferred to another device via a binary output. This does not have its own connected cleaning unit, but its sensors are installed in the medium affected by cleaning the master and are set to hold by the trigger.
- **3.** The trigger is transferred via an additional binary output to another device, whose connected sensors have their own cleaning units. The signal can be used to simultaneously activate a self-cleaning with the master.

10.5.2 Binary input configuration

Menu/Setup/Inputs/Binary input x:y ¹⁾		
Function	Options	Info
Binary input	Selection • Off • On Factory setting On	Switches the input on/off
Signal type	Selection Static signal PFM Factory setting Static signal	Select the signal type. Static signal Use this setting to read out the position of, for example, an on/off switch, an inductive proximity switch or a PLC binary output. Signal application: for measuring range switching, acceptance of an external hold, as a cleaning trigger or for controller activation PFM The PFM setting produces a pulse-frequency- modulated signal that is subsequently available on the device as a quasi-continuous process value. Example: Measuring signal of a flowmeter
Signal type = Static signa	al	
Signal level	Selection • Low • High Factory setting High	Determine which input signal levels should activate, for example, measuring range switching or a cleaning. Low Input signals between 0 and 5 V DC High Input signals between 11 and 30 V DC
Signal type = PFM		
Max. frequency	100.00 to 1000.00 Hz Factory setting 1000.00 Hz	Maximum frequency of the PFM input signal Is to equal the maximum possible upper limit of the measuring range. If the value selected is too small, higher frequencies will not be detected. If the value is too large, on the other hand, the resolution for small frequencies will be relatively inexact.
Meas. value format	Selection # #.# #.## Factory setting #.##	Specify the number of decimal places.

Menu/Setup/Inputs/Binary input x:y ¹⁾		
Function	Options	Info
Input mode	Selection • Frequency • Parameter • Flow rate Factory setting Frequency	Frequency Display in Hz in the measuring menu Parameter You subsequently determine the parameter name and unit. These are then displayed in the measuring menu. Flow rate For connecting a flowmeter
Parameter name Input mode = Parameter	Customized text, 16 characters	Define a name for the parameter, e.g. "pressure".
Unit of measure Input mode = Parameter	Customized text, 16 characters	Define the unit for your parameter, e.g. "hPa".
Flow rate unit Input mode = Flow rate	Selection I/s I/h m ³ /s m ³ /h cfs cfd mgd Factory setting I/s	Define the unit for the flow. cfs = cubic feet per second cfd = cubic feet per day mgd = mega gallon per day
Lower range value Input mode = Parameter or Flow rate	-2000.00 to 0.00 Factory setting 0.00	The start of measuring range corresponds to a frequency of 0 Hz. Your previously defined unit is additionally displayed.
Upper range value Input mode = Parameter or Flow rate	0.00 to 10000.00 Factory setting 0.00	The end of measuring range corresponds to the maximum frequency defined above. Your previously defined unit is additionally displayed.
Damping	0 to 60 s Factory setting 0 s	The damping causes a floating average curve of the measured values over the time specified.

1) x:y = slot no. : input number

10.5.3 Configuration of binary outputs

Menu/Setup/Outputs/Binary output x:y ¹⁾		
Function	Options	Info
Binary output	Options Off On Factory setting On 	Switches the output on/off
Signal type	Options Static signal PFM Factory setting Static signal	Select the signal type. Static signal Comparable to a relay: output of a diagnostic status or a limit switch PFM You can output a measured value, e.g. the chlorine value or the manipulated variable of a controller. It functions as a "wear-free" switching contact that can be used to activate a dosing pump, for example.

Menu/Setup/Outputs/Binary output x:y ¹⁾		
Function	Options	Info
Signal type = Static signal		
Function	Options None Limit switches Diagnostics message Cleaning Factory setting None	Source for the outputted switching state The following functions depend on the option selected. Function = None Switches off the function. There are no other settings.
Assignments Function = Cleaning	Multiple selection Cleaning 1 - Water Cleaning 4 - Cleaner 	Here you can decide which binary outputs should be used for activating the valves and pumps. Here you concretely assign a control signal to the binary output for the cleaner/water dosing of a cleaning program. You can define cleaning programs under: Menu/ Setup/Additional functions/Cleaning in the measuring mode.
Data sources Function = Limit switches	Multiple selection Limit switch 1 8	Select the limit switches that should be output via the binary output. Configuration of the limit switches: Menu / Setup/Additional functions/Limit switches in the measuring mode.
Operating mode Function = Diagnostics message	Options as assigned Namur M Namur S Namur C Namur F Factory setting as assigned	 as assigned With this selection, the diagnosis messages are transmitted over the binary output that you individually allocated to it. Namur M F When you choose one of the Namur classes, all messages allocated to that respective class are output. You can change the Namur class assignment for every diagnostic message → 🖺 111.
Signal type = PFM		
Max. frequency	1.00 to 1000.00 Hz Factory setting 1000.00 Hz	Maximum frequency of the PFM output signal Is to equal the maximum possible upper limit of the measuring range.
Meas. value format	Options	Specify the number of decimal places.

Menu/Setup/Outputs/Binary output x:y ¹⁾)
mental betap: batpato, binary batpating	

Menu/Setup/Outputs/Binary output x:y ¹⁾		
Function	Options	Info
Source of data	Options None Sensor inputs Binary inputs Controller Fieldbus signals Mathematical functions	Source, whose value should be read out as a frequency over the binary output.
	Factory setting None	
Measuring value Source of data ≠ Controller	Options Depends on: Source of data	Choose the measured value which should be output as the frequency via the binary output.
Actuator type Source of data = Controller	Options • None • Bipolar • Unipolar+ • Unipolar- Factory setting None	Specify which controller component the connected actuator, e.g. the dosing pump, should trigger. Bipolar "Split range" Unipolar+ Part of the manipulated variable that the controller uses to increase the process value Unipolar- For connected actuators that decrease the controlled variable
Hold behavior	Options • Freeze • Fixed value • None Factory setting None	Freeze The device freezes the last value. Fixed value You define a fixed current value that is transmitted at the output. None A hold does not affect this output.
Hold value	0 to 100 %	
Hold behavior = Fixed value	Factory setting 0 %	
Error behavior	Options Freeze Fixed value Factory setting Fixed value	Freeze The device freezes the last value. Fixed value You define a fixed current value that is transmitted at the output.
Error value	0 to 100 %	
Error behavior = Fixed value	Factory setting 0 %	

1) x:y = slot no. : input number

10.6 Additional functions

10.6.1 Limit switches

There are different ways to configure a limit switch:

- Assigning a switch-on and switch-off point
- Assigning a switch-on and switch-off delay for a relay
- Setting an alarm threshold and also outputting an error message
- Starting a cleaning function

Menu/Setup/Additional functions/Limit switches/Limit switch 1 8		witch 1 8
Function	Options	Info
Source of data	Selection None Sensor inputs Binary inputs Controller Fieldbus signals Mathematical functions MRS set 1 2 Factory setting None	Specify the input or output which should be the source of data for the limit switch. The sources of data on offer depend on your device version. You can choose from connected sensors, binary inputs, fieldbus signals, mathematical functions, controllers and sets for measuring range switching.
Measuring value	Selection Depends on: Source of data	Select the measured value, see the following table.

Ν	Menu/Setup/Additional functions/Limit switches/Limit switch 1 8

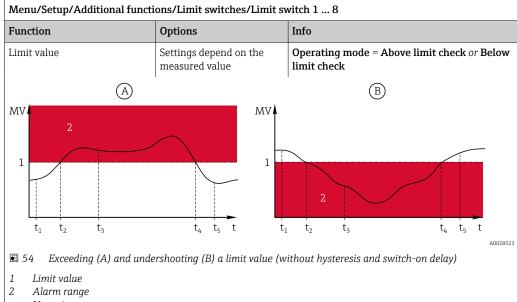
Measured value depending on the Source of data

Source of data	Measured value	
pH Glass	Selection	
pH ISFET	 Raw value mV pH Temperature 	
ORP	Selection Temperature ORP mV ORP % 	
Oxygen (amp.)	Selection	
Oxygen (opt.)	 Temperature Partial pressure Concentration liquid Saturation Raw value nA (only Oxygen (amp.)) Raw value µs (only Oxygen (opt.)) 	
Cond i	Selection	
Cond c	 Temperature Conductivity 	
Cond c 4-pol	 Resistance (only Cond c) Concentration (only Cond i and Cond c 4-pol) 	
Disinfection	Selection Temperature Sensor current Concentration 	
ISE	Selection Temperature pH Ammonium Nitrate Potassium Chloride	

Source of data	Measured value	
TU/TS	Selection	
TU	 Temperature Turbidity g/l (only TU/TS) Turbidity FNU (only TU/TS) Turbidity Formazine (only TU) Turbidity solid (only TU) 	
Nitrate	Selection • Temperature • NO3 • NO3-N	
Ultrasonic interface	Selection Temperature Interface Turbidity 	
SAC	Selection • Temperature • SAC • Transm. • Absorption • COD • BOD	
Controller 1	Selection	
Controller 2	 Bipolar (only for current outputs) Unipolar+ Unipolar- 	
Mathematical functions	All the mathematical functions can also be used as a data source and the calculated value can be used as the measured value.	

You can monitor the manipulated variable by assigning the controller manipulated variable to a limit switch (e.g. configure a dosing time alarm).

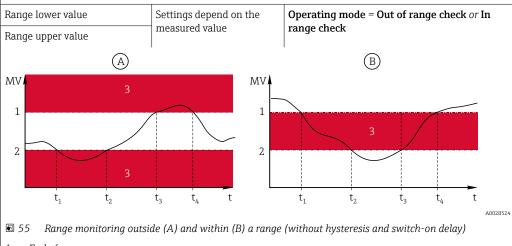
Menu/Setup/Additional functions/Limit switches/Limit switch 1 8		
Function	Options	Info
Cleaning program	Selection None Cleaning 1 4 Factory setting None	Use this function to choose the cleaning instance which should be started when the limit switch is active.
Function	Selection • Off • On Factory setting Off	Activating/deactivating the limit switch
Operating mode	Selection Above limit check Below limit check In range check Out of range check Change rate Factory setting Above limit check	 Type of limit value monitoring: Limit value overshoot or undershoot → € 54 Measured value within or outside a range → € 55 Rate of change → € 57



 $t_{1,3,5}$ No action

 $t_{2,4}$ An event is generated

- If the measured values (MV) are increasing, the relay contact is closed when the on-value is exceeded (Limit value + Hysteresis) and the start delay (Start delay) has elapsed.
- If the measured values are decreasing, the relay contact is reset when the off-value is undershot (Limit value - Hysteresis) and following the drop-out delay (Switch off delay).



1 End of range

2 Start of range

3 Alarm range

 t_{1-4} An event is generated

- If the measured values (MV) are increasing, the relay contact is closed when the on-value is exceeded (Range lower value + Hysteresis) and the start delay (Start delay) has elapsed.
- If the measured values are decreasing, the relay contact is reset when the off-value is undershot (Range upper value - Hysteresis) and following the drop-out delay (Switch off delay).

Menu/Setup/Additional functions/Limit switches/Limit switch 1 8		
Function	Options	Info
Hysteresis	Settings depend on the measured value	Operating mode ≠ Change rate
MV		The hysteresis is needed to ensure a stable switching behavior. The device software adds or subtracts the value set here to/from the limit value (Limit value , Range lower value or Range upper value). This results in double the Hysteresis value for the hysteresis range around the limit value. An event is then only generated if the measured value (MV) completely passes through the hysteresis range.
E 56 Hysteresis taking the exercise overshoot	ample of limit value	
 Limit value Alarm range Hysteresis range t_{1,2} An event is generated 		
Start delay	0 to 9999 s	Synonyms: pick-up and drop-out delay
Operating mode ≠ Change rate	Factory setting 0 s	
Switch off delay		
Operating mode ≠ Change rate		
Delta value	Settings depend on the measured value	Operating mode = Change rate The slope of the measured value (MV) is
Delta time	00:01 to 23:59	monitored in this mode.
	Factory setting 01:00	An event is generated if, in the given timeframe (Delta time), the measured value increases or decreases by more than the specified value
Auto Confirm	00:01 to 23:59	(Delta value). No further event is generated if the value continues to experience such a steep
	Factory setting 00:01	increase or decrease. If the slope is back below the limit value, the alarm status is reset after a
$MV \downarrow \qquad \Delta MV_2 \downarrow \qquad \\ \Delta MV_1 \downarrow \qquad \\ t_1 t_2 t_3 t_4$	ΔMV ₃ t ₅ t ₆ t	preset time (Auto Confirm). Events are triggered by the following conditions in the example given: $t_2 - t_1 < Delta time and \Delta MV1 > Delta value$ $t_4 - t_3 > Auto Confirm and \Delta MV2 < Delta value$ $t_6 - t_5 < Delta time and \Delta MV3 > Delta value$
$t_1 t_2 t_3 t_4$ Image: The second seco		

10.6.2 Controller

$\begin{array}{c} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ &$

Controller structure in Laplace representation

■ 58 Block diagram of the controller structure

Integral action time (I-value)

Derivative action time (D-value)

Time constant for set point damping

Time constant for anti-windup feedback

- I Integral value D Derivative value
 - - aT_V Damping time constant with a = 0 to 1
 - e Control deviation
 - w Set point
 - x Controlled variable
 - y Manipulated variable

P Proportional value

Neutral zone

Output limiting

Gain (P-value)

Α

В

Kp

 T_n

 T_{ν}

 T_w

 T_{wu}

The controller structure of the device comprises set point damping at the input to prevent erratic changes in the manipulated variable if the set point changes. The difference between the set point w and the controlled variable (measured value) X results in the control deviation which is filtered by a neutral zone.

The neutral zone is used to suppress control deviations (e) that are too small. The control deviation thus filtered is now fed to the actual PID controller which divides into three parts based on the P (proportional), I (integral) and D (derivative) values (top-down). The integral section (middle) also comprises an anti-windup mechanism for limiting the integrator. A low-pass filter is added to the D-section to damp hard D-terms in the manipulated variable. The sum of the 3 sections results in the internal controller manipulated variable which is limited according to the settings (for PID-2s to -100% to +100%).

The graphic does not illustrate a downstream filter for limiting the rate of change of the manipulated variable (can be configured in the menu in **Max y change rate**).

In the menu do not configure the gain K_p . Instead configure the reciprocal value, the proportional band X_p ($K_p = 1/X_p$).

Configuration

Make the following decisions when configuring a controller:

- (1) What type of process can your process be assigned to? → **Process type**
- (2) Should it be possible to influence the measured variable (controlled variable) in one direction or in both directions? One-sided or two-sided controller, → Controller type
- (3) What should be the controlled variable (sensor, measured value)? → Controlled variable
- (4) Do you have a disturbance variable that should be active at the controller output? → Disturbance variable

- (5) Define the parameters for the controller:
 - Set point, \rightarrow **Setpoint**
 - Neutral zone, $\rightarrow Xn$
 - Proportional band, $\rightarrow Xp$
 - Integral action time (I-value), \rightarrow **Tn**
 - Derivative action time (D-value), $\rightarrow \mathbf{Tv}$
- (6) What should the controller do in the event of a hold (measured error, sensor replacement, cleaning etc.)?
 - Pause or continue with dosing? →**Hold behavior/Manipulated Variable**
 - At the end of a hold, continue or restart the control loop (affects I-value)? →Hold behavior/State
- (7) How should the actuator be triggered?
 - **Unipolar+**: Assign this setting to the output for an actuator which can increase the measured value.
 - **Unipolar**-: Assign this setting to the output for an actuator which can decrease the measured value.
 - **Bipolar**: Select this setting if you want to output the manipulated variable via one current output only (split range).
- (8) Configure the outputs and switch on the controller.

Menu/Setup/Additional fu	nctions/Controller 1 2	
Function	Options	Info
Control	Selection • Off • Automatic • Manual mode Factory setting Off	First configure the controller and leave the switch at the factory setting (Off). Once you have made all the settings, you can assign the controller to an output and switch it on.
Manual mode	I	
у	-100 to 100 % Factory setting 0 %	Specify the manipulated variable that should be output in manual mode.
y Actual output	Read only	Manipulated variable actually output.
Setpoint		Current set point
Х		Current measured value
Disturbance variable		Current measured value of disturbance variable
Norm. disturb. value		
Name	Free text	Give the controller a name so you can identify it later on.
Controller Enable	Selection None Binary inputs Limit switches Fieldbus variables Factory setting None	In connection with the DIO module, you can select a binary input signal, e.g. from an inductive proximity switch, as a source for enabling the controller.
Setup Level	Selection • Standard • Advanced Factory setting Standard	Changes the number of parameters that can be configured. → Parameters → 🗎 90 Standard : If you choose this, the other controller parameters are active nevertheless. The system uses the factory settings which usually suffice in most cases.

Menu/Setup/Additional functions/Controller 1 ... 2

Function	Options	Info
Process type	Selection Inline Batch	Decide what type of process best describes your particular process.
	Factory setting Inline	

Batch process

The medium is in a closed system.

The task of the control system is to dose in such a way that the measured value (controlled variable) changes from its start value to its target value. No more dosing is needed once the set point has been reached and the system is stable. If the target value is overshot, a two-sided control system can compensate for this. In the case of 2-sided batch control systems, a neutral zone is used/configured to suppress oscillations around the set point.

In-line process

Co

In an in-line process, the control system works with the medium flowing by in the process.

Selection

PID 1-sided

PID 2-sided

Factory setting

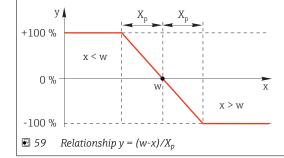
Here, the controller has the task of using the manipulated variable to set a mixture ratio between the medium and dosing agent such that the resulting measured variable corresponds to the set point. The properties and volume of the medium flow can change at any time and the controller has to react to these changes on a continuous basis. If the flow rate and medium remain constant, the manipulated variable can also assume a fixed value once the process has settled. Since the control process is never "finished" here, this type of control is also referred to as continuous control.

A mixture of both process types can often be found in practice: the semi-batch process. Depending on the |**i**| ratio between the flow and the container volume, this arrangement behaves either like a batch process or an in-line process.

- DID 1 -:-1
 PID 1-sid
 PID 2-sid
Factory set PID 2-sided
PID 2-sided

Depending on the actuator connected, you influence the process in just one direction (e.g. heating) or in both directions (e.g. heating and cooling).

A 2-sided controller can output a manipulated variable in the range from -100% to +100%, i.e. the manipulated variable is bipolar. The manipulated variable is positive if the controller should increase the process value. In the case of a pure P-controller, this means that the value of the controlled variable x is smaller than the set point w. On the other hand, the manipulated variable is negative if the process value should be decreased. The value for x is greater than the set point w.

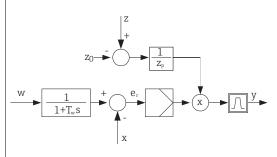


Menu/Setup/Additional funct	ions/Controller 1 2	
Function	Options	Info
Effective direction Controller type = PID 1-sided	Selection Direct Reverse Factory setting Reverse	 In what direction should the controller influence the measured value? The measured value should increase as a result of dosing (e.g. heating) → Reverse The measured value should decrease as a result of dosing (e.g. cooling) → Direct
Reverse : If the controller should becomes active when the proces	d increase the process value, s ss value is too small (range A) tion, the controller acts as a "c	it can only influence the process in one direction. et this as the direction of action. The controller lownwards controller". It becomes active when the
y X _p +100 % A W -100 % W € 60 Red: overlap between t	X _p X B he curves of the two 1-sided co	se tra llava
Controlled variable		
Source of data	Selection None Sensor inputs Current inputs Fieldbus signals Binary inputs Mathematical functions Factory setting None	Specify the input or output which should be the source of data for the controlled variable.
Measured value	Selection depend on Source of data Factory setting None	Specify the measured value that should be your controlled variable. You can use different measured values depending on the data source. → 🗎 80
► Setpoint		Target value of the controlled variable This menu is not displayed if you selected a fieldbus as the source (Source of data = fieldbus).
Setpoint	Range of adjustment and factory setting depending on the Source of data	Specify the target value for the controlled variable.
Tw Setup Level = Advanced	0.0 to 999.9 s Factory setting 2.0 s	Time constant for the set point damping filter
 Disturbance variable 		• optional, activation code necessary

Menu/Setup/Additional functions/Controller 1 ... 2

Function	Options	Info

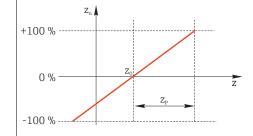
With "flowing medium" (inline) controls, it can happen that the flow rate is non-constant. In some circumstances, strong fluctuations are possible. In the case of a settled control system in which the flow rate is suddenly halved, it is desirable that the dosed quantity from the controller is also directly halved. In order to achieve this type of "flow-rate-proportional" dosing, this task is not left to the I-component of the controller, but rather one enters the (to be measured) flow rate as disturbance variable z multiplicative at the controller output.



Strictly speaking, feedforward control involves an open-loop control system, since its effect is not measured directly. That means that the feed flow is directed exclusively forward. Hence the designation "feedforward control."

For the additive feedforward control that is alternatively available in the device, the (standardized) disturbance variable is added to the controller manipulated variable. This enables you to set up a type of variable base load dosing.

The standardization of the disturbance variable is required both for multiplicative and for additive feedforward control and is done using parameters Z_0 (zero point) and Z_p (proportional band): $z_n = (z - z_0)/z_p$



Example

Flowmeter with measuring range 0 to 200 m³/ h

The controller would currently dose 100% without feedforward control.

The feedforward control should be configured such that at $z = 200m^3/h$, the controller still doses at 100% ($z_n = 1$).

If the flow rate drops, the dosing rate should be reduced, and at a flow rate of less than 4 m³/h, dosing should stop entirely ($z_n = 0$).

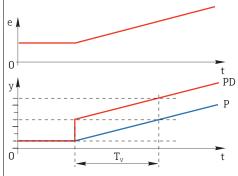
 \rightarrow Select the zero point $z_0 = 4 \text{ m}^3/\text{h}$ and the proportional band $Z_p = 196 \text{ m}^3/\text{h}$.

		A
Function	Selection • Off • Multiply • Add Factory setting Off	Selecting multiplicative or additive feedforward control
Source of data	Selection None Sensor inputs Current inputs Fieldbus signals Binary inputs Mathematical functions Factory setting None	Specify the input which should be the source of data for the disturbance variable.

Function	Options	Info
Measured value	Selection depend on Source of data	Specify the measured value that should be your disturbance variable.
	Factory setting None	You can use different measured values depending on the data source. $\rightarrow \cong 80$
Zp	Range of adjustment	Proportional band>
ZO	depending on the selection of the measured value	Zero point
Parameters		
 Derivative action time T Proportional band X_p 	v	
Setup Level = Advanced:	With this setup level, you can also o	configure the following:
Setup Level = Advanced: • Time constant T _{wu} • Time constant α • Width of the neutral zon • Width of the hysteresis	ne X _n range of the neutral zone X _{hyst}	configure the following:
Setup Level = Advanced: • Time constant T _{wu} • Time constant α • Width of the neutral zon • Width of the hysteresis	ne X _n range of the neutral zone X _{hyst}	The integral action time specifies the effect of
Setup Level = Advanced: Time constant T _{wu} Time constant α Width of the neutral zon Width of the hysteresis Cycle time of the contro Tn	ne X _n range of the neutral zone X _{hyst} ller 0.0 to 9999.0 s Factory setting 0.0 s	The integral action time specifies the effect of the I-value If Tn > 0 the following applies: Clock < Twu < 0.5(Tn + Tv)
Setup Level = Advanced: Time constant T _{wu} Time constant α Width of the neutral zou Width of the hysteresis Cycle time of the contro Tn The integral action time is	ne X _n range of the neutral zone X _{hyst} ller 0.0 to 9999.0 s Factory setting 0.0 s	The integral action time specifies the effect of the I-value If Tn > 0 the following applies: Clock < Twu < 0.5(Tn + Tv) response to achieve a change in the manipulated

Menu/Setup/Additional functions/Controller 1 2		
Function	Options	Info
Twu	0.1 to 999.9 s Factory setting 20.0 s	Time constant for anti-windup feedback The lower the value the greater the integrator inhibition. Exercise extreme caution when making changes. Clock < Twu < 0.5(Tn + Tv)
Tv	0.1 to 999.9 s Factory setting 0.0 s	The derivative action time specifies the effect of the D-value

The derivative action time is the time by which the ramp response of a PD controller reaches a specific value of the manipulated variable at an earlier stage than it would solely as a result of its P-value.



0.0 to 1.0	Affects the additional damping filter of the D- controller. The time constant is calculated from
$\begin{array}{c} \text{Factory setting} \\ 0.3 \\ \end{array} \alpha T_{v}. \end{array}$	
Selection	Symmetric
SymmetricAsymmetric	There is only one control gain and this applies for both sides of the process.
Factory setting Symmetric	Asymmetric You can set the control gain individually for both sides of the process.
Range of adjustment and factory setting depending on the Source of data	Proportional band, reciprocal value of the proportional gain K_p As soon as controlled variable x deviates more than x_p from the set point w, manipulated variable y reaches 100%.
Range of adjustment and	x_p for y < 0 (manipulated variable < 0)
factory setting depending on the Source of data	
-	x_p for y > 0 (manipulated variable > 0)
Range of adjustment and factory setting depending on the Source of data	Tolerance range about the set point that prevents minor oscillations about the set point if using two-sided control loops.
Range of adjustment and	x_n for x < w (controlled variable < set point)
factory setting depending on the Source of data	
	x_n for x > w (controlled variable > set point)
	Factory setting 0.3 Selection • Symmetric Factory setting Symmetric Range of adjustment and factory setting depending on the Source of data Range of adjustment and factory setting depending on the Source of data Range of adjustment and factory setting depending on the Source of data Range of adjustment and factory setting depending on the Source of data Range of adjustment and factory setting depending on the Source of data Range of adjustment and factory setting depending on the Source of data Range of adjustment and factory setting depending on the Source of data

Menu/Setup/Additional funct	ions/Controller 1 2	
Function	Options	Info
XHyst	0.0 to 99.9 % Factory setting 0.0 %	Width of the hysteresis range of the neutral zone, relative component of \mathbf{x}_{n}
y x _{hyst}	e = W-X	
point minus controlled variable	. Very low control deviation	re P-controller) over the control deviation e (set is are set to zero. Control deviations > x _n are igure a hysteresis to suppress oscillations at the
Clock	0.333 to 100.000 s Factory setting 1.000 s	Expert setting! Only change the cycle time of the controller if you know exactly what you are doing! Clock < Twu < 0.5(Tn + Tv)
Max y change rate	0.00 to 1.00 Factory setting 0.40	Limits the change of the output variable A value of 0.5 permits a maximum manipulated variable change of 50% within one second.
▶ Hold behavior		Hold=measured value is no longer reliable
Manipulated Variable	Selection Freeze 	How should the controller react to a measured value that is no longer reliable?
	 Fixed value Factory setting Freeze 	Freeze The manipulated variable is frozen at the current value
		Fixed value Manipulated variable is set to 0 (no dosing)
State	Selection	Internal controller status
	FreezeReset	Freeze No change
	Factory setting Freeze	Reset After a hold, the control system starts from scratch, and settling time takes place again.
▶ Outputs		Goes to the menu Outputs $\rightarrow \triangleq 67$
Controller assignment view		Shows an overview of the inputs and outputs used

10.6.3 Cleaning programs

ACAUTION

Cleaning not switched off during calibration or maintenance activities

- Risk of injury due to medium or cleaning agent
- If a cleaning system is connected, switch if off before removing a sensor from the medium.
- If you wish to check the cleaning function and have therefore not switched off the cleaning system, please wear protective clothing, goggles and gloves or take other appropriate measures.

Cleaning types

The user can choose from the following cleaning types:

- Standard clean
- Chemoclean
- Chemoclean Plus

State of cleaning: Indicates whether the cleaning program is active or not. This is for information purposes only.

Selecting the cleaning type

1. Menu/Setup/Additional functions/Cleaning: Select a cleaning program.

 You can configure 4 different types of cleaning which you can assign individually to the inputs.

2. Cleaning type: For each cleaning program decide which type of cleaning should be performed.

Standard cleaning

Standard cleaning involves cleaning a sensor with compressed air, for instance, as performed with the ion-selective sensor CAS40D (connection of the cleaning unit for CAS40D $\rightarrow \square$ 33)

Menu/Setup/Additional functions/Cleaning/Cleaning 1 4/Standard clean		
Function	Options	Info
Cleaning time	5 to 600 s Factory setting 10 s	Cleaning duration The cleaning duration and interval depend on the process and sensor. Determine the variables empirically or based on experience.

• Defining the cleaning cycle $\rightarrow \cong 95$

Chemoclean

An example is the use of the CYR10 injector unit to clean pH glass sensors. (CYR10 connection $\rightarrow \cong$ 33)

Menu/Setup/Additional functions/Cleaning/Cleaning 1 4/Chemoclean		
Function	Options	Info
Cleaning time	0 to 900 s Factory setting 5 s	Cleaning duration
Prerinse time Postrinse time	0 to 900 s Factory setting 0 s	The cleaning duration, pre-rinse and post-rinse times and the interval depend on the process and sensor. Determine the variables empirically or based on experience.

Chemoclean Plus

An example is the use of the CYR10 injector unit to clean pH glass sensors. (CYR10 connection $\rightarrow \cong$ 33)

Menu/Setup/Additional functions/Cleaning/Cleaning 1 4/Chemoclean Plus/ChemoCle		
Function	Options	Info
Cleaning steps setup	Table to create a time program	You define a maximum of 30 program steps which should be performed one after the other. For each step enter the duration $[s]$ and the state (0 = "off", 1 = "on") of each relay or output. You can specify the number and name of the outputs further down in the menu. See below for an example of programming.
Failsafe step setup	Table view	In the table specify the states that the relays or outputs should assume in the event of an error.
Limit contacts	0 to 2	Select the number of digital input signals (e.g. from limit position switches of the retractable assembly).
Limit contact 1 2	Selection Binary inputs Fieldbus signals	Define the signal source for each limit position switch.
Outputs	0 to 4	Select the number of outputs that actuators, such as valves or pumps, should activate.
Output label 1 4	Free text	You can assign a meaningful name to each output, e.g. "assembly", "cleaner 1", "cleaner 2" etc.

Programming example: regular cleaning with water and 2 cleaning agents

Limit switch	Duration [s]	Assembly CPA87x	Water	Cleaner 1	Cleaner 2
ES1 1	5	1	1	0	0
ES2 1	5	1	1	0	0
0	30	1	1	0	0
0	5	1	1	1	0
0	60	1	0	0	0
0	30	1	1	0	0
0	5	1	1	0	1
0	60	1	0	0	0
0	30	1	1	0	0
ES1 0	5	0	1	0	0
ES2 0	5	0	1	0	0
0	5	0	0	0	0

The pneumatic retractable assembly, e.g. CPA87x, is activated by compressed air via a twoway valve. As a result, the assembly assumes either the "Measure" position (sensor in medium) or the "Service" position (sensor in rinse chamber). Media such as water or cleaning agents are supplied via valves or pumps. Here there are two states: 0 (= "off" or "closed") and 1 (= "on" or "open").



The hardware required for "Chemoclean Plus", such as control valves, pumps, compressed air supply, media supply etc., must be provided by the customer.

Defining the cleaning cycle

Menu/Setup/Additional functions/Cleaning/Cleaning 1 4		
Function	Options	Info
Cleaning cycle	Selection • Off • Interval • Weekly program	Choose from a cleaning routine that is restarted at set intervals and a user-definable weekly program.
	Factory setting Weekly program	
Cleaning interval Cleaning cycle = Interval	0-00:01 to 07-00:00 (D-hh:mm)	The interval value can be between 1 minute and 7 days.
	Factory setting 1-00:00	Example: You have set the value "1-00:00". Each day, the cleaning cycle starts at the same time you started the first cleaning cycle.
Daily event times	00:00 to 23:59	1. Define up to 6 times (Event time 1 6).
Cleaning cycle = Weekly program	(HH:MM)	 └- You can then choose from these for each weekday afterwards. 2.For each day of the week, individually choose
Weekdays	Selection	which of the 6 times is to be used for a cleaning
Cleaning cycle = Weekly program	Monday Sunday	routine on this particular day.
		In this way you create weekly programs that are perfectly adapted to suit your process.

Other settings and manual cleaning

Menu/Setup/Additional functions/Cleaning/Cleaning 1 4		
Function	Options	Info
Start signal	 Selection None Fieldbus signals Signals of digital or analog inputs Factory setting None 	In addition to cyclic cleaning, you can also use an input signal to start event-controlled cleaning. Choose the trigger for such a cleaning process here. Interval programs and weekly programs are executed as normal, i.e. conflicts can occur. Priority is given to the cleaning program that was the first to be started.
Hold	Selection • Off • On Factory setting On	Decide whether there should be a hold during the cleaning process. This hold affects the inputs to which this cleaning process is assigned.
⊳ Start single	Action	Start an individual cleaning process with the selected parameters. If cyclical cleaning is enabled, there are times in which it is not possible to manually start the process.
Stop or Stop Failsafe	Action	End the cleaning process (cyclically or manually)
▶ Outputs		Goes to the menu Outputs $\rightarrow \triangleq 67$
Cleaning program assignment view		Shows an overview of the cleaning processes

10.6.4 Mathematical functions

In addition to "real" process values, which are provided by connected physical sensors or analog inputs, mathematical functions can be used to calculate a maximum of 6 "virtual" process values.

The "virtual" process values can be:

- Output via a current output or a fieldbus
- Used as a controlled variable
- Assigned as a measured variable to a limit switch
- Used as a measured variable to trigger cleaning
- Displayed in user-defined measuring menus

Difference

You can subtract the measured values of two sensors and use the result to detect incorrect measurements, for example.

To calculate a difference, you must use two measured values with the same engineering unit.

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Difference		
Function	Options	Info
Calculation	Selection • Off • On Factory setting Off	On/off switch for the function
У1	The options depend on the sensors connected	Select the sensors and the measured variables
Measured value		that should act as the minuend (Y1) or subtrahend (Y2) .
Y2		
Measured value		
Difference value	Read only	View this value in a user-defined measuring screen or output the value via the current output.
▶ Mathematical function assignment view		Overview of the configured functions

Redundancy

Use this function to monitor two or three sensors with redundant measurements. The arithmetic average of the two closest measured values is calculated and output as the redundancy value.

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Redundancy		
Function	Options	Info
Calculation	Selection • Off • On	On/off switch for the function
	Factory setting Off	
Ү1	The options depend on the	You can select a maximum of 3 different types of
Measured value	sensors connected	sensor that output the same measured value.
Y2	-	Example for temperature redundancy You have a pH sensor and an oxygen sensor at
Measured value		inputs 1 and 2. Select the pH sensor as Y1 and the oxygen sensor as Y2 . Measured value : In
Y3 (optional)		each case select Temperature .
Measured value		

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Redundancy		
Function	Options	Info
Deviation control	Selection • Off • On	You can monitor the redundancy. Specify an absolute limit value that may not be exceeded.
	Factory setting Off	
Deviation limit	Depends on the selected measured value	
Redundancy	Read only	View this value in a user-defined measuring screen or output the value via the current output.
Mathematical function assignment view		Overview of the configured functions

rH value

To calculate the rH value, a pH sensor and an ORP sensor must be connected. It is irrelevant whether you are using a pH glass sensor, an ISFET sensor or the pH electrode of an ISE sensor.



Instead of the mathematical functions, you can also connect a combined pH/ORP sensor. Simply set the main measured value to rH (Setup/).

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = rH calculation		
Function	Options	Info
Calculation	Selection • Off • On	On/off switch for the function
	Factory setting Off	
pH source	Connected pH sensor	Set the input for the pH sensor and the input for
ORP source	Connected ORP sensor	the ORP sensor. Measured value interrogation is obsolete as you must select pH or ORP mV.
Calculated rH	Read only	View this value in a user-defined measuring screen or output the value via the current output.
Mathematical function assignment view		Overview of the configured functions

Degassed conductivity

Carbon dioxide from the air can be a contributing factor to the conductivity of a medium. The degassed conductivity is the conductivity of the medium excluding the conductivity caused by carbon dioxide.

Advantages of using degassed conductivity taking the example of a power station:

- The conductivity caused by corrosion products or contamination in the feed water is determined as soon as the turbines are started. The system excludes the initially high conductivity values resulting from the ingress of air.
- If carbon dioxide is regarded as non-corrosive, the live steam can be directed to the turbine far earlier during startup.
- If the conductivity value increases during normal operation, it is possible to immediately determine an ingress of coolant or air by calculating the degassed conductivity.

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Degassed conductivity
Menu/Setup/Aduitional functions/Mathematical functions/MF1 to 0/Mode – Degassed conductivity

Function	Options	Info
Calculation	Selection • Off • On Factory setting Off	On/off switch for the function
Cation conductivity	Connected conductivity sensor	Cation conductivity is the sensor downstream from the cation exchanger and upstream from
Degassed conductivity	Connected conductivity sensor	the "degassing module", Degassed conductivity is the sensor at the outlet of the degassing module. Measured value interrogation is obsolete as you can only choose conductivity.
CO2 concentration	Read only	View this value in a user-defined measuring screen or output the value via the current output.
► Mathematical function assignment view		Overview of the configured functions

Dual conductivity

You can subtract two conductivity values and use the result, for example, to monitor the efficiency of an ion exchanger.

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Dual conductivity		
Function	Options	Info
Calculation	Selection Off On Engroup setting	On/off switch for the function
	Factory setting Off	
Inlet	The options depend on the	Select the sensors that should act as the
Measured value	sensors connected	minuend (Inlet , e.g. sensor upstream from the ion exchanger) or subtrahend (Outlet , e.g.
Outlet		sensor downstream from the ion exchanger).
Measured value		
Main value format	Selection Auto # # #.# #.## #.### Factory setting Auto	Specify the number of decimal places.
Cond. unit	Selection Auto μS/cm mS/cm S/cm μS/m mS/m S/m Factory setting Auto	
Dual conductivity	Read only	View this value in a user-defined measuring screen or output the value via the current output.
 Mathematical function assignment view 		Overview of the configured functions

Calculated pH value

The pH value can be calculated from the measured values of two conductivity sensors under certain conditions. Areas of application include power stations, steam generators and boiler feedwater.

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = pH calcul	ation from
conductivity	

Function	Options	Info
Calculation	Selection Off On Factory setting	On/off switch for the function
	Off	
Method	Selection NaOH NH3 LiOH	The calculation is performed on the basis of Guideline VGB-R-450L of the Technical Association of Large Power Plant Operators (Verband der Großkesselbetreiber, (VGB)).
	Factory setting NaOH	NaOH pH = 11 + log {($\kappa_v - 1/3 \kappa_h$)/273}
		NH3 pH = 11 + log {($\kappa_v - 1/3 \kappa_h$)/243}
		LiOH pH = 11 + log {($\kappa_v - 1/3 \kappa_h$)/228}
		$\kappa_v \dots$ Inlet direct conductivity $\kappa_h \dots$ Outlet acid conductivity
Inlet	The options depend on the	Inlet
Measured value	sensors connected	Sensor upstream from the cation exchanger, "direct conductivity"
Outlet		Outlet
Measured value		Sensor downstream from the cation exchanger, "acid conductivity"
		The choice of measured value is obsolete since it must always be Conductivity .
Calculated pH	Read only	View this value in a user-defined measuring screen or output the value via the current output.
Mathematical function assignment view		Overview of the configured functions

Cation exchanger capacity (optional, with activation code)

Cation exchangers are used to monitor the water/steam circuit for inorganic contamination. The cation exchangers eliminate the disruptive influence of alkalizing agents, such as ammonium hydroxide or caustic soda, which are added to the boiler feedwater.

The service life of cation exchangers depends on:

- The type of alkalizing agent
- The concentration of the alkalizing agent
- The amount of contamination in the medium
- The capacity of the cation exchanger (efficiency of the resin)

To ensure the smooth operation of power stations, it is important to continuously monitor the exchange column load. When a user-defined remaining capacity is reached, the transmitter displays a diagnostic message so that the ion exchange column can be replaced or regenerated in good time. The calculation of the remaining capacity depends on the following factors:

- Flow rate
- Volume of the exchanger
 Salinity of the water at the exchanger inlet
 Total volume capacity of the resin
- Degree of efficiency of the exchanger

Function	Options	Info
Cond IEX output	Read only	
Cond IEX input	-	
Flow rate	-	
Remaining capacity	-	
Remaining op. hours	-	
Time until %0B ¹⁾	-	
► Configuration		
Calculation	Selection • Off • On Factory setting Off	On/off switch for the function
Unit of volume	Selection I gal Factory setting l	
Exchanger volume	0.0 to 99999 Factory setting 0.0	Volume of the cation exchanger Unit depending on the option selected in Unit of volume
TVC Resin	0.0 to 99999 eq/l or eq/gal Factory setting 0.0 eq/l	TVC = total volume capacity Unit as equivalent per Unit of volume
Resin efficiency	1.0 to 100.0 % Factory setting 100.0 %	For information on the resin efficiency, refer to the data provided by the manufacturer of the resin used.
Set remaining capacity	Selection • Yes • No Factory setting No	Before you start monitoring, specify the remaining capacity of the exchanger resin. This value makes allowances for the re-use of resin that has already been used. If a value is not entered manually, 100% is taker as the initial value for calculating the current
Remaining capacity	0.0 to 100.0 %	remaining capacity.
Set remaining capacity = Yes	Factory setting 0.0 %	
Warning limit	1.0 to 100.0 %	Specify the remaining capacity at which the
-	Factory setting 20.0 %	transmitter should display a diagnostic message

Function	Options	Info
Cond IEX input	Connected conductivity sensor	Select the conductivity sensor upstream from the inlet of the exchanger column.
Cond IEX output	Connected conductivity sensor	Select the conductivity sensor downstream from the outlet of the exchanger column.
Max cond at IEX output	0.0 to 99999 μS/cm Factory setting 0.0 μS/cm	Here, enter the maximum value which the acid conductivity may have at the outlet of the cation exchanger. The transmitter displays a diagnostic message if this value is exceeded.
Flow rate type	Selection Source value Fixed value	Source value You have connected the measured value of a flowmeter via a current input or a binary input.
	Factory setting Source value	Fixed value Manual entry of a fixed flow rate
Flow rate	Selection None Current inputs Binary inputs Factory setting None	Specify the input at which you have connected and configured the measured value of a flowmeter (Menu/Setup/Inputs).
Fixed value	Free text	Specify the fixed flow value which you have read
Flow rate type = Fixed value		on an external flowmeter, for example.
Min flow rate	0.0 to 99999 l/h	
Max flow rate	Factory setting 0.0 l/h	
 Mathematical function assignment view 		Overview of the configured functions

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Cation exchanger capacity

1) %OB is a variable whose value depends on the configuration. The configured value is displayed, e.g. 20%.

Formula (optional, with activation code)

With the formula editor, it is possible to calculate a new value from a maximum of 3 measured values. A wide range of mathematical and logical (Boolean) operations are available for this purpose.

The Liquiline firmware offers you a powerful mathematics tool with the formula editor. You are responsible for the feasibility of your formula, and therefore of the result.

Symbol	Operation	Type of operands	Type of result	Example
+	Addition	Numerical	Numerical	A+2
-	Subtraction	Numerical	Numerical	100-В
*	Multiplication	Numerical	Numerical	A*C
1	Division	Numerical	Numerical	B/100
^	Power	Numerical	Numerical	A^5
2	Square	Numerical	Numerical	A ²
3	Cube	Numerical	Numerical	B ³
SIN	Sine	Numerical	Numerical	SIN(A)
COS	Cosine	Numerical	Numerical	COS(B)
EXP	Exponential function e ^x	Numerical	Numerical	EXP(A)
LN	Natural logarithm	Numerical	Numerical	LN(B)

Symbol	Operation	Type of operands	Type of result	Example
LOG	Decadic logarithm	Numerical	Numerical	LOG(A)
MAX	Maximum of two values	Numerical	Numerical	MAX(A,B)
MIN	Minimum of two values	Numerical	Numerical	MIN(20,B)
ABS	Absolute value	Numerical	Numerical	ABS(C)
NUM	Boolean → numerical conversion	Boolean	Numerical	NUM(A)
=	Equals	Boolean	Boolean	A=B
<>	Not equal to	Boolean	Boolean	A<>B
>	Greater than	Numerical	Boolean	B>5.6
<	Smaller than	Numerical	Boolean	A <c< td=""></c<>
OR	Disjunction	Boolean	Boolean	B OR C
AND	Conjunction	Boolean	Boolean	A AND B
XOR	Exclusive disjunction	Boolean	Boolean	B XOR C
NOT	Negation	Boolean	Boolean	NOT A

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Formula				
Function	Options	Info		
Calculation	Selection • Off • On	On/off switch for the function		
	Factory setting Off			
Source A C	Selection Select source	You can use all the sensor inputs, binary and analog inputs, mathematical functions, limit		
	Factory setting None	switches, fieldbus signals, controllers and data records for measuring range switching as the source for measured values.		
Measured value	Selection Depends on the source	1. Choose a maximum of three sources (A, B and C) for measured values.		
A C	The current measured value is displayed	 For each source, choose the measured value to be calculated. All available signals - depending on the selected source - are possible measured values. 		
		3. Enter the formula.		
		 4. Switch on the calculation function. The current measured values A, B and C as well as the result of the calculation using the formula are displayed. 		
Formula	Free text	 Table → ■ 101 Make sure the exact notation is used (upper case). Blank spaces before and after mathematical characters are irrelevant. Note the operator precedence, i.e. multiplication and division have priority before addition and subtraction. Use parentheses where possible. 		

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Formula		
Function	Options	Info
Result unit	Free text	Optionally, enter a unit for the calculated value.
Result format	Selection Select the number of decimal places. # # # # # # # # # # # # # # # # # #	
Result decimal	Read only	Current, calculated value
Mathematical function assignment view		Overview of the configured functions

Menu/Setup/Additional functions/Mathematical functions/MF1 to 6/Mode = Formula

Example: 2-point chlorine regulator with volume flow monitoring

A relay output activates a dosing pump. The pump should switch on when the following 3 conditions are met:

- (1) There is flow
- (2) The volume flow is above a defined value
- (3) The concentration of chlorine drops below a defined value
- 1. Connect a binary input signal from an "INS" point level switch of the CCA250 assembly to the DIO module.
- 2. Connect an analog input signal of a volume flow meter to the AI module.
- 3. Connect the chlorine sensor.
- 4. Configure the mathematical function **Formula** : **Source A** = DIO binary input, **Source B** = AI current input, **Source C** = input **Disinfection**.
 - ← Formula:
 - A AND (B > 3) AND (C < 0.9)

(where 3 is the lower limit value of the volume flow and 0.9 is the lower limit value of the chlorine concentration)

5. Configure the relay output with the mathematical function **Formula** and connect the dosing pump to the corresponding relay.

The pump is switched on if all 3 conditions are met. If one of the conditions is no longer met, the pump is switched off again.

🗓 Instead of outputting the result of the formula directly to a relay, you can also connect a limit switch in between in order to attenuate the output signal via a switch-on and switchoff delay.

Example: Load-based control

The load - i.e. the product of the concentration and volume flow - is needed for the dosage of precipitants, for instance.

- 1. Connect the input signal of a phosphate analyzer to the AI module.
- 2. Connect an analog input signal of a volume flow meter to the AI module.
- 3. Configure the mathematical function **Formula** : **Source A** = phosphate input signal and **Source B** = volume flow input signal.
 - ← Formula: A*B*x

(where x is an application-specific proportionality factor)

4. Select this formula as the source e.g. of the current output or of a modulated binary output.

5. Connect the valve or pump.

10.6.5 Measuring range switching

A measuring range switching (MRS) configuration includes the following options for each of the four binary input states:

- Operating mode (conductivity or concentration)
- Concentration table
- Temperature compensation
- Current output turndown
- Limit switch range

An MRS set is assigned to a channel and switched on. The measuring range configuration selected via the binary inputs is now applied instead of the normal configuration of the linked sensor channel. For current outputs and limit switches to be controlled by the MRS, they must be linked to the MRS set, not to the measuring channel.

Current outputs and limit switches can be linked to an MRS set. This MRS set gives you the measured value and the associated turn down (current outputs) or the range for limit value monitoring (limit switches).

A limit switch connected to an MRS set always uses the **Out of range check**mode. Consequently, it switches when the value is outside the configured range.

If a current output or limit switch is connected to an MRS set, the turndown, monitoring range and limit switch mode can no longer be configured manually. Therefore, these options are hidden in the menus (current outputs and limit switch).

	Beer	Water	Alkali	Acid
Binary input 1	0	0	1	1
Binary input 1	0	1	0	1
	Measuring range 00	Measuring range 01	Measuring range 10	Measuring range 11
Operating mode	Conductivity	Conductivity	Concentration	Concentration
Conc. Table	-	-	NaOH 015%	User table 1
Compensation	User table 1	Linear	-	-
Current output				
Range lower value	1.00 mS/cm	0.1 mS/cm	0.50 %	0.50 %
Range upper value	3.00 mS/cm	0.8 mS/cm	5.00 %	1.50 %
Limit switches				
Range lower value	2.3 mS/cm	0.5 mS/cm	2.00 %	1.30 %
Range upper value	2.5 mS/cm	0.7 mS/cm	2.10 %	1.40 %

Programming example: CIP cleaning in a brewery

Function	Options	Info
▶ MRS set 1 2		If you enter both activation codes, you have two independent parameter sets available for measuring range switching. The submenus are the same for both sets.
MRS	Selection Switches the function on or off • Off • On Factory setting Off	
Sensor	Selection None Connected conductivity sensors Factory setting None	This function can be used on conductivity sensors only.
Binary input 1 2	Selection None Binary inputs Fieldbus signals Limit switches Factory setting None	Source of the switching signal, can be selected for input 1 and 2 in each case
▶ Measuring range 00 11		Select the MRSs; a maximum of 4 are possible. The submenus are identical for each and thus are displayed only once.
Operating mode	Selection • Conductivity • Concentration • TDS • Resistance Factory setting Conductivity	 Selection depends on the sensor used: Inductive sensor and conductive four-pin sensor Conductivity Concentration TDS Conductive sensor Conductivity Resistance TDS
Conc. Table Operating mode = Concentration	Selection NaOH 015% NaOH 2550% HCI 020% HNO3 025% HNO3 2430% H2SO4 028% H3PO4 040% NaCl 026% User table 1 4 Factory setting NaOH 015%	Concentration tables saved at the factory: NaOH: 0 to 15%, 0 to 100 °C (32 to 212 °F) NaOH: 25 to 50%, 2 to 80 °C (36 to 176 °F) HCl: 0 to 20%, 0 to 65 °C (32 to 149 °F) HNO3: 0 to 25%, 2 to 80 °C (36 to 176 °F) H2SO4: 0 to 28%, 0 to 100 °C (32 to 212 °F) H2SO4: 40 to 80%, 0 to 100 °C (32 to 212 °F) H2SO4: 93 to 100%, 0 to 100 °C (32 to 212 °F) H3PO4: 0 to 40%, 2 to 80 °C (36 to 176 °F) NaCl: 0 to 26%, 2 to 80 °C (36 to 176 °F)
Compensation Operating mode = Conductivity	Selection None Linear NaCl (IEC 746-3) Water ISO7888 (20°C) Water ISO7888 (25°C) UPW NaCl UPW HCl USer table 1 4 Factory setting Linear	Various methods are available to compensate for the temperature dependency. Depending on you process, decide which type of compensation you want to use. Alternatively, you can also select None and thus measure uncompensated conductivity.

Menu/Setup/Additional functions/Measuring range switch			
Function	Options	Info	
Current output			
Range lower unit	Depends on the Operating	Units are only queried for Operating mode =	
Range lower value	mode	Conductivity . The other units are pre-defined and cannot be modified.	
Range upper unit		 Conductivity S/m, mS/cm, µS/cm, S/cm, µS/m, mS/m 	
Range upper value		 Concentration % TDS ppm Resistance Ωcm 	
Limit switches			
Range lower unit	Depends on the Operating		
Range lower value	mode	Conductivity . The other units are pre-defined and cannot be modified.	
Range upper unit	-	 Conductivity S(m mS(m vS(m mS(m mS(m mS(m mS(m mS(m m	
Range upper value		 S/m, mS/cm, µS/cm, S/cm, µS/m, mS/m Concentration % TDS ppm Resistance Ωcm 	

10.6.6 Diagnostic modules

Here you can configure a maximum of 8 individual diagnostic messages.

- A diagnostic module has the following properties:
- The feed source can be configured like a binary output (relay, digital output).
- You can choose whether the diagnostic message should be output at a high level or low level.
- You decide which error category (Namur class) should be assigned to the message.
- You can define a customized text to be output as the diagnostic message text.

In addition you can switch off the factory diagnostic code for limit switches. This allows you to:

- Use the limit switch on a purely functional basis (without a message)
- Configure application-specific message texts
- Control diagnostic modules directly by a digital signal or via a limit switch output (enables the use of switch-on/switch-off delay, for example).

Menu/Setup/Additional functions/Diagnostic modules		
Function	Options	Info
▶ Diagnostic module 1 (961) 8 (968)		
Source of data	Selection None Fieldbus signals Binary inputs Limit switches Factory setting None	Specify the input which should be the source of data for the diagnostic message.
Measured value	Selection depend on Source of data Factory setting None	Specify the measured value that should trigger the diagnostic message. You can use different measured values depending on the data source. $\rightarrow \cong 80$

Menu/Setup/Additional functions/Diagnostic modules		
Function	Options	Info
Active low	Selection • Off • On Factory setting On	On : The output value is equal to the inverse output value.
Short text	Free text	Give the diagnostic message a name.
▶ Diagnostic module assignment view		Shows an overview of the diagnostic modules used.

11 Calibration

- Sensors with Memosens protocol are calibrated at the factory.
- Users must decide whether the process conditions present require calibration during initial commissioning.
- Additional calibration is not required in many standard applications.
- Calibrate the sensors at sensible intervals depending on the process.

Operating Instructions "Memosens", BA01245C

12 Diagnostics and troubleshooting

12.1 General troubleshooting

The analyzer transmitter continuously monitors its functions itself.

If a diagnostic message occurs, the display alternates between the diagnostic message and the measured value in the measuring mode.

The color of the display background changes to red if a diagnostic message for error category "F" occurs.

12.1.1 Troubleshooting

A diagnostic message appears on the display or via the fieldbus, measured values are not plausible, or you identify a fault.

See the Diagnostics menu for the details on the diagnostic message.
 Follow the instructions to rectify the problem.

- If this does not help: search for the diagnostic message under "Overview of diagnostic information" (→
 ^(→) 112) in these Operating Instructions. Use the message number as a search criterion. Ignore the letters indicating the Namur error category.
 - ► Follow the troubleshooting instructions provided in the last column of the error tables.
- If the measured values are implausible, the local display is faulty or you encounter other problems, search for the faults under "Process errors without messages" (→ Operating Instructions for Memosens, BA01245C) or "Device-specific errors" (→
 109).
 - └ Follow the recommended measures.
- 4. Contact the Service Department if you cannot rectify the error yourself. Only cite the error number.

12.1.2 Process errors without messages

Operating Instructions "Memosens", BA01245C

12.1.3 Device-specific errors

Problem	Possible cause	Tests and/or remedial measures	
Dark display	No supply voltage	Check if supply voltage applied.	
(only with optional display)	Display connector plugged in incorrectly	Check. Must be in RJ45 socket on base module.	
	Base module defective	Replace base module	
Values appear on display but: • Display does not change and / or	Module not wired correctly	Check modules and wiring.	
 Device cannot be operated 	Impermissible operating system condition	Switch off device and switch it on again.	
Implausible measured values	Inputs defective	First perform tests and take measures as outlined in "Process-specific errors" section	
		Measuring input test: • Connect the Memocheck Sim CYP03D to the input and use it to check the function of the input.	

Problem	Possible cause	Tests and/or remedial measures
Current output, incorrect current	Incorrect adjustment	Check with integrated current simulation,
value	Load too large	connect mA meter directly to current output.
	Shunt / short to ground in current loop	
No current output signal	Base module defective	Check with integrated current simulation, connect mA meter directly to current output.

12.2 Diagnostic information on the local display (optional)

Up-to-date diagnostic events are displayed along with their status category, diagnostic code and short text. Clicking on the navigator lets you retrieve more information and tips on remedial measures.

12.3 Diagnostic information via web browser

The same information as for the local display is available via the web server.

12.4 Diagnostic information via fieldbus

Diagnostic events, status signals and more information are transmitted according to the definitions and technical capability of the respective fieldbus systems.

12.5 Adapting the diagnostic information

12.5.1 Classification of diagnostic messages

In the **DIAG/Diagnostics list** menu you can find more detailed information on the current diagnostic messages displayed.

In accordance with Namur specification NE 107, the diagnostic messages are characterized by:

- Message number
- Error category (letter in front of the message number)
 - $\mathbf{F} = (Failure)$ a malfunction has been detected The measured value of the affected channel is no longer reliable. The cause of the malfunction is to be found in the measuring point. Any control system connected should be set to manual mode.
 - **C** = (Function check), (no error)
 - Maintenance work is being performed on the device. Wait until the work has been completed.
 - ${\bf S}$ = (Out of specification), the measuring point is being operated outside its specification

Operation is still possible. However, you run the risk of increased wear, shorter operating life or lower measurement accuracy. The cause of the problem is to be found outside the measuring point.

- M = (Maintenance required), action should be taken as soon as possible
 The device still measures correctly. Immediate measures are not necessary. However, proper maintenance efforts would prevent a possible malfunction in the future.
- Message text
- If you contact the Service Department, please cite the message number only. Since you can individually change the assignment of an error to an error category, the Service Department cannot use this information.

12.5.2 Adapting the diagnostic behavior

All the diagnostic messages are assigned to specific error categories at the factory. Since other settings might be preferred depending on the application, error categories and the effect errors have on the measuring point can be configured individually. Furthermore, every diagnostic message can be disabled.

Example

Diagnostic message 531 **Logbook full**appears on the display. You want to change this message so that an error is not shown on the display for example.

- 1. Select: Menu/Setup/General settings/Extended setup/Diagnostics settings/Diag. behavior.
- 2. Select the diagnostic message and press the navigator button.
- Decide: (a) Should the message be deactivated? (Diagnostics message = Off)
 (b) Do you want to change the error category?(Status signal)
 - (c) Should an error current be output? (**Error current = On**)
 - (d) Do you want to trigger a cleaning program? (Cleaning program)
- 4. Example: You deactivate the message.
 - └ The message is no longer displayed. In the DIAG menu, the message appears as Past message.

Possible settings

The list of diagnostic messages displayed depends on the path selected. There are devicespecific messages, and messages that depend on what sensor is connected.

Menu/Setup//Extended setup/Diagnostics settings/Diag. behavior					
Function	Options	Info			
List of diagnostic messages		Select the message to be changed. Only then can you make the settings for this message.			
Diag. code	Read only				
Diagnostic message	Selection • Off • On Factory setting Depends on the Diag. code	You can deactivate or reactivate a diagnostic message here. Deactivating means: • No error message in the measuring mode • No error current at the current output			
Error current	Selection Off On Factory setting Depends on the Diag. code	Decide whether an error current should be output at the current output if the diagnostic message display is activated. In the event of general device errors, the error current is switched to all the current outputs. In the event of channel-specific errors, the error current is only switched to the current output in question.			
Status signal	Selection Maintenance (M) Out of specification (S) Function check (C) Failure (F) Factory setting Depends on the Diag. code	The messages are divided into different error categories in accordance with NAMUR NE 107. Decide whether you want to change a status signal assignment for your application.			

Menu/Setup//Extended se	Menu/Setup//Extended setup/Diagnostics settings/Diag. behavior				
Function	Options	Info			
Diag. output	Selection None Binary outputs Alarm relay Relay Factory setting None	 You can use this function to select an output to which the diagnostic message should be assigned. An alarm relay is always available, regardless of the device version. Other relays are optional. Before you can assign the message to an output: Configure one of the output types mentioned as follows: Menu/Setup/Outputs/(Alarm relay or Binary output or relay)/Function = Diagnostics and Operating mode = as assigned. 			
Cleaning program	Selection None Cleaning 1 4 Factory setting None	Decide whether the diagnostic message should trigger a cleaning program. You can define cleaning programs under: Menu/Setup/Additional functions/Cleaning .			
▶ Detail information	Read only	Here you can find more information on the diagnostic message and instructions on how to resolve the problem.			

12.6 Overview of diagnostic information

No.	Message	Factory	Factory settings		Tests or remedial action	
		S 1)	D ²⁾	F ³⁾		
202	Selftest active	F	On	Off	Wait for self-test to be finished	
216	Hold active	C	On	Off	Output values and status of the channel are on hold	
241	Firmware failure	F	On	On	Internal device error	
242	Firmware incomp.	F	On	On	1. Update the software	
243	Firmware failure	F	On	On	2. Contact the Service Department	
					3. Replace the backplane (Service)	
261	Electronics module	F	On	On	Electronics module defective	
					1. Replace the module	
					2. Contact the Service Department	
262	Module connection	F	On	On	Electronics module not communicating	
					1. Check the module , replace it if necessary	
					2. Contact the Service Department	
263	Incomp. detected	F	On	On	Wrong kind of electronics module	
					1. Replace the module	
					2. Contact the Service Department	
284	Firmware update	М	On	Off	Update completed successfully	

12.6.1 Device-specific, general diagnostic messages

No.	Message	Factory settings			Tests or remedial action
	5	S ¹⁾	D ²⁾	F ³⁾	
285	Update error	F	On	On	 Firmware update failed 1. Repeat 2. SD card error → use another card 3. Incorrect firmware → repeat with suitable firmware
302	Battery low	М	On	Off	 4. Contact the Service Department Buffer battery of real time clock is low The date and time are lost if the power is interrupted. Contact the Service Department (battery
304	Module data	F	On	On	replacement) At least 1 module has incorrect configuration data 1. Check the system information 2. Contact the Service Department
305	Power consumption	F	On	On	Total power consumption too high 1. Check installation 2. Remove sensors/modules
306	Software error	F	On	On	Internal firmware error Contact the Service Department
366	Module connection	F	On	On	No communication with the actuator module Check the internal connecting cable to the 1IF module
370	Internal voltage	F	On	On	Internal voltage outside the valid range ► Check supply voltage
373	Electronictemp. high	М	On	Off	 High electronics temperature Check ambient temperature and energy consumption
374	Sensor check	F	On	Off	No measurement signal from sensor 1. Check sensor connection 2. Check sensor, replace if necessary
401	Factory reset	F	On	On	Factory reset is performed
403	Device verification	М	Off	Off	Device verification active, please wait
405	Service IP active	С	Off	Off	 Service switch is switched on The device can be addressed at 192.168.1.212. Switch off the service switch to change to the saved IP settings
406	Param. active	С	Off	Off	• Wait for configuration to be finished
407	Diag. setup active	С	Off	Off	• Wait for maintenance to be finished
412	Writing backup	F	On	Off	• Wait for the write process to be finished
413	Reading backup	F	On	Off	▶ Wait
460	Output below limit Output above limit	S	On On	Off Off	Reasons Sensor in air Air pockets in assembly Sensor fouled Incorrect flow to sensor Check sensor installation Clean sensor Adjust assignment of current outputs

No.	Message	Factory	Factory settings		Tests or remedial action	
		S 1)	D ²⁾	F ³⁾		
502	No text catalog	F	On	On	Contact the Service Department	
503	Language change	М	On	Off	Language change failed	
					► Contact the Service Department	
529	Diag. setup active	С	Off	Off	• Wait for maintenance to be finished.	
530	Logbook at 80%	М	On	Off	1. Save the logbook to the SD card and then delete the logbook in the device	
531	Logbook full	М	On	Off	2. Set memory to ring memory	
					3. Deactivate logbook	
532	License error	M	On	Off	 Contact the Service Department 	
540	Parameter save fail	М	On	Off	Storage of configuration has failed	
					► Repeat	
541	Parameter load ok	М	On	Off	Configuration successfully loaded	
542	Parameter load fail	М	On	Off	Loading of configuration has failed	
					► Repeat	
543	Parameter load abort	М	On	Off	Configuration loading aborted	
544	Parameter reset ok	М	On	Off	Factory default successful	
545	Parameter reset fail	М	On	Off	Setting of device configuration to factory setting has failed	
906	Cat.exchanger failure	F	On	Off	Invalid values for conductivity or flow	
					1. Check for valid measured values in the menu of the mathematical function.	
					2. Check sensors.	
					3. Check minimum flow.	
907	Cat.exchanger warning	S	On	Off	Limit values exceeded for conductivity or flow.	
					Possible reasons: Resin depleted	
					 Blocked pipe 	
					Check application.	
908	IEX capacity low	М	On	Off	The capacity of the exchange resin will soon be exhausted.	
					► Schedule resin regeneration or replacement.	
909	IEX capacity exhausted	F	On	Off	The capacity of the exchange resin is exhausted.	
					• Regenerate or replace the resin.	
910	Limit switch	S	On	Off	Limit switch activated	
937	Controlled variable	S	On	Off	Controller input warning Status of the controller variable is not OK	
					 Check application 	
938	Controller setpoint	S	On	Off	Controller input warning	
					Status of set point is not OK Check application 	
939	Control. disturbance	S	On	Off	Controller input warning	
					Status of disturbance variable is not OK Check application 	
951 -	Hold active CH1	С	On	Off	Output values and status of the channels are on	
958					hold. Wait until the hold is released again.	

No.	Message	Factory	ry settings		Tests or remedial action	
		S ¹⁾	D 2)	F ³⁾		
961 - 968	Diagnostic module 1 (961)	S	Off	Off	Diagnostic module is enabled	
	Diagnostic module 8 (968)					
969	Modbus Watchdog	S	Off	Off	The device did not receive a Modbus telegram from the master within the specified time. The status of Modbus process values received is set to invalid	
970	Curr. input overload	S	On	On	Current input overloaded The current input is switched off from 23 mA due to overload and reactivated automatically when a normal load is present.	
971	Current Input low	S	On	On	Current input too low At 4 to 20 mA, the input current is less than the lower error current.	
					 Check the input for short-circuiting 	
972	Curr. input > 20 mA	S	On	On	Current output range exceeded	
973	Current Input < 4 mA	S	On	On	Current output range undershot	
974	Diagnostics confirm.	C	Off	Off	User has acknowledged the message displayed in the measuring menu.	
975	Device restart	C	Off	Off	Device reset	
976	PFM value high	S	On	Off	Pulse frequency modulation: output signal	
977	PFM value low	S	On	Off	exceeded/undershot. Measured value outside the specified range. Sensor in air Air pockets in assembly Incorrect flow to sensor Sensor fouled 1. Clean sensor	
					2. Check plausibility	
					3. Adjust the PFM configuration	
978	ChemoClean Failsafe	S	On	On	No feedback signal detected within the configured period.	
					1. Check the application	
					2. Check the wiring	
					3. Extend the duration	
990	Deviation limit	F	On	On	Redundancy: limit value of percentage deviation exceeded	
991	CO2 conc. range	F	On	On	CO_2 concentration (degassed conductivity) outside the measuring range	
992	pH calculation range	F	On	On	pH calculation outside the measuring range	
993	rH calculation range	F	On	On	rH calculation outside the measuring range	
994	Difference conduct.	F	On	On	Dual conductivity outside the measuring range	
995	Mathematical error	S	On	On	Incorrect calculation result	
					 Check the mathematical functions. Check the input variables. 	

1) 2) 3) Status signal Diagnostic message

Error current

12.6.2 Sensor-specific diagnostic messages

Derating Instructions "Memosens", BA01245C

12.7 Pending diagnostic messages

The Diagnostics menu contains all the information on the device status.

Furthermore, various service functions are available.

The following messages are directly displayed every time you enter the menu:

- Most important message
- Diagnostic message recorded with the highest criticality level
- Past message

Diagnostic message whose cause is no longer present.

All the other functions in the Diagnostics menu are described in the following chapters.

12.8 Diagnostics list

All the current diagnostic messages are listed here.

A time stamp is available for each message. Furthermore, the user also sees the configuration and description of the message as saved in **Menu/Setup/General settings/ Extended setup/Diagnostics settings/Diag. behavior**.

12.9 Event logbook

12.9.1 Available logbooks

Types of logbooks

- Logbooks physically available (all apart from the overall logbook)
- Database view of all logbooks (=overall logbook)

Logbook	Visible in	Max. entries	Can be disabled ¹	Logbook can be deleted	Entries can be deleted	Can be exported
Overall logbook	All events	20000	Yes	No	Yes	No
Calibration logbook	Calibration events	75	(Yes)	No	Yes	Yes
Operation logbook	Configuration events	250	(Yes)	No	Yes	Yes
Diagnostics logbook	Diagnostic events	250	(Yes)	No	Yes	Yes
Version logbook	All events	50	No	No	No	Yes
Hardware version logbook	All events	125	No	No	No	Yes
Data logbook for sensors (optional)	Data logbooks	150 000	Yes	Yes	Yes	Yes
Debugging logbook	Debug events (only accessible by entering the special service activation code)	1000	Yes	No	Yes	Yes

1) Data in brackets means this depends on the overall logbook

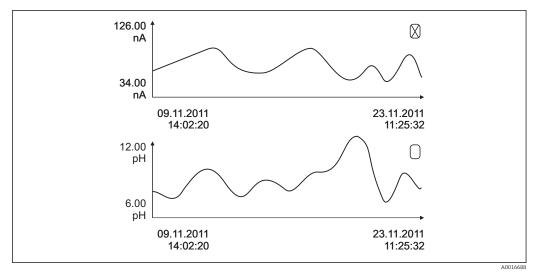
12.9.2 Menu Logbooks

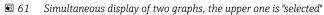
unction	Options	Info	
All events		Chronological list of all the logbook entries, with information on the type of event	
► Show	Events are displayed	Select a particular event to display more detailed information.	
► Go to date	User entry Go to date Time	Use this function to go directly to a specific time in the list. In this way, you avoid having to scrol through all the information. The complete list is always visible, however.	
Calibration events		Chronological list of the calibration events	
► Show	Events are displayed	Select a particular event to display more detailed information.	
► Go to date	User entry Go to date Time	Use this function to go directly to a specific time in the list. In this way, you avoid having to scroll through all the information. The complete list is always visible, however.	
⊳ Delete all entries	Action	You can delete all the calibration logbook entrie here.	
Configuration events		Chronological list of the configuration events.	
► Show	Events are displayed	Select a particular event to display more detail information.	
▶ Go to date	User entry Go to date Time	Use this function to go directly to a specific time in the list. In this way, you avoid having to scrol through all the information. The complete list is always visible, however.	
⊳ Delete all entries	Action	You can use this to delete all the operation logbook entries.	
Diagnostic events		Chronological list of the diagnostics events	
► Show	Events are displayed	Select a particular event to display more detailed information.	
► Go to date	User entry • Go to date • Time	Use this function to go directly to a specific time in the list. In this way, you avoid having to scrol through all the information. The complete list is always visible, however.	
\triangleright Delete all entries	Action	You can use this to delete all the diagnostics logbook entries.	

You can view your data logbook entries graphically on the display (Show plot).

You can also adapt the display to suit your individual requirements:

- Press the navigator button in the graphic display: you are given additional options such as the zoom function and x/y movement of the graph.
- Define the cursor: if you select this option, you can move along the graph with the navigator and view the logbook entry (data stamp/measured value) in text form for every point in the graph.
- Simultaneous display of two logbooks: Select 2nd plot and Show plot
- A small cross marks the currently selected graph for which the zoom can be changed or a cursor used, for example.
- In the context menu (press the navigator button), you can select the other graph. You can then apply the zoom function, a movement or a cursor to this graph.
- Using the context menu, you can also select both graphs simultaneously. This enables you, for example, to use the zoom function on both graphs simultaneously.





unction	Options	Info		
 Data logbooks 		Chronological list of the data logbook entries for sensors		
Data logbook 1 8 <logbook name=""></logbook>		This submenu is available for each data logboo that you have set up and activated.		
Source of data	Read only	Input or mathematical function is displayed		
Measured value	Read only	Measured value being recorded is displayed		
Log time left	Read only	Display of days, hours and minutes until logb is full. Pay attention to the information on selecting the memory type in the General settings/Logbooks .		
► Show	Events are displayed	Select a particular event to display more detai information.		
► Go to date	User entry Go to date Time	Use this function to go directly to a specific tim in the list. In this way, you avoid having to scro through all the information. The complete list always visible, however.		
Show plot	Graphic display of the logbook entries	The entries are displayed according to your settings in the General settings/Logbooks .		
Select 2nd plot	Select another data logbook	You can view a second logbook at the same tim as the current one.		
▷ Delete all entries	Action	You can use this to delete all data logbook entries.		
Save logbooks				
File format	Selection • CSV • FDM	Save the logbook in the preferred file format. You can then open the CSV file you saved on th PC in MS Excel, for example, and process it further ¹⁾ . You can import the FDM files into Fieldcare and archive them so they are tamper proof.		

DIAG/Logbooks						
Function	Options	Info				
 All data logbooks Data logbook 1 8 All event logbooks Calibration logbook Diagnostic logbook Configuration logbook HW version logbook Version logbook 	Action, commences as soon as the option is selected	Use this function to save the logbook to an SD card. Insert the SD card into the device card reader and select the logbook to be saved. Save the logbook in the preferred file format. You can then open the saved CSV file on a computer, such as in MS Excel, and make further edits there. You can import the FDM files into Fieldcare and archive them so they are tamper-proof.				

The file name consists of **Logbook ident (Menu/Setup/General settings/Logbooks)**, an abbreviation for the logbook and a time stamp.

 CSV files use international number formats and separators. Therefore they must be imported into MS Excel as external data with the correct format settings. If you double-click the file to open it, the data are only displayed correctly if MS Excel is installed with the US country setting.

12.10 Simulation

You can simulate values at inputs and outputs for testing purposes:

- Current values at current outputs
- Measured values at inputs
- Relay contact opening or closing

Only current values are simulated. Via the simulation function, it is not possible to calculate the totalized value for the flow or rainfall.

DIAG/Simulation			
Function	Options	Info	
Current output x:y		Simulation of an output current This menu appears once for each current output.	
Simulation	Selection • Off • On Factory setting Off	If you simulate the value at the current output, this is indicated on the display by a simulation icon in front of the current value.	
Current	2.4 to 23.0 mA Factory setting 4 mA	Set the desired simulation value.	
 Alarm relay Relay x:y 		Simulation of a relay state This menu appears once for each relay.	
Simulation	Selection • Off • On Factory setting Off	If you simulate the relay state, this is indicated on the display by a simulation icon in front of the relay display.	
State	Selection Low High Factory setting Low 	Set the desired state. The relay switches in accordance with your setting when you switch on the simulation. In the measured value display you see On (= Low) or Off(= High) for the simulated relay state.	

DIAG/Simulation			
Function	Options	Info	
Meas. inputs		Simulation of a measured value (only for	
Channel : parameter		sensors) This menu appears once for each measuring input.	
Simulation	Selection • Off • On	If you simulate the measured value, this is indicated on the display by a simulation icon in front of the measured value.	
	Factory setting Off		
Main value	Depends on the sensor	Set the desired simulation value.	
Sim. temperature	Selection Off On Factory setting Off	If you simulate the temperature measured value, this is indicated on the display by a simulation icon in front of the temperature.	
Temperature	-50.0 to +250.0 °C (-58.0 to 482.0 °F)	Set the desired simulation value.	
	Factory setting 20.0 °C (68.0 °F)		

12.11 Device test

Function	Options	Info
► Power Supply	Read only Digital Supply 1: 1.2V Digital Supply 2: 3.3V Analog Supply: 12.5V Sensor Supply: 24V Temperature	Detailed list of power supply to instrument. The actual values can vary without a malfunction being present.
Heartbeat		
▶ Perform verification		Heartbeat verification will influence the device's output signals and their statuses. Please ensure safe process control conditions.
		1. Press OK .
		 Answer the questions and confirm at the end by pressing OK. The overall result of the verification is displayed.
▷ Verification results		Result display • Customer Customized text, maximum 32 characters • Location Customized text, maximum 32 characters • Verification report Automatic time stamp • Verification ID Automatic counter • Overall result Passed or failed
▷ Export to SD- card		Export the verification report as a pdf file Detailed report on various device tests Input and output information Device information Sensor information
		The report is ready to be printed out and signed You can file it immediately in an operations log for example.

12.12 Resetting the measuring device

DIAG/Reset			
Function	Options	Info	
⊳ Device restart	Selection • OK • ESC	Restart and keep all the settings	
▷ Factory default	Selection • OK • ESC	Restart with factory settings Settings that have not been saved are lost.	

12.13 Device information

12.13.1 System information

DIAG/System information				
Function Options Info				
Device tag	Read only	Individual device tag → General settings		
Order code	Read only	You can order identical hardware with this code. This code changes on account of changes to the hardware and you can enter the new code you received from the manufacturer here ¹⁾ .		
To discover the version of address: www.products.en		ode into the search screen at the following		
Orig. order code ext.	Read only	Complete order code for the original device, resulting from the product structure.		
Current order code ext.	Read only	Current code, taking into account changes to the hardware. You must enter this code yourself.		
Serial number	Read only	The serial number allows you to access device data and documentation on the Internet: www.endress.com/device-viewer		
Software version	Read only	Current version		
▶ HART Only with the HART option	Read only Bus address Unique address Manufacturer ID Device type Device revision Software revision	HART-specific information The unique address is linked to the serial number and is used to access devices in a Multidrop environment. Device and software version numbers are incremented as soon as changes have been made.		
► Modbus Only with the Modbus option	Read only Enable Bus address Termination Modbus TCP Port 502	Modbus-specific information		
▶ PROFIBUS Only with the PROFIBUS option	Read only Termination Bus address Ident number Baudrate DPV0 state DPV0 fault DPV0 master addr DPV0 WDT [ms]	Module status and other PROFIBUS-specific information		
► Ethernet Only with the Ethernet, EtherNet/IP, Modbus TCP, Modbus RS485 or PROFIBUS DP option	Read only Enable Webserver Link settings DHCP IP-Address Netmask Gateway Service switch MAC-Address EtherNetIP Port 44818 Modbus TCP Port 502 Webserver TCP Port 80	Ethernet-specific information Display depends on the fieldbus protocol used.		
▶ SD card	Read only • Total • Free memory			

Function	Options	Info	
System modules			
Backplane	Read only	This information is provided for every electronics	
Base	DescriptionSerial number	module available. Specify the serial numbers and order codes when servicing, for example.	
Display module	 Order code Hardware version 		
Extension module 1 8	Software version		
▶ Sensors	Read only Description Serial number Order code Hardware version Software version	This information is provided for every sensor available. Specify the serial numbers and order codes when servicing, for example.	
Save system information			
⊳ Save to SD card	File name assigned automatically (includes a time stamp)	The information is saved on the SD card in a "sysinfo" subfolder. The csv file can be read and edited in MS Excel for example. This file can be used when servicing the device.	
► Heartbeat operation		Heartbeat functions are only available with the appropriate device version or optional access code.	
▶ Device	Read only Total operating time Counters since reset Availability Operating time Time in failure Number of failures MTBF MTTR ▶ Reset counters	Availability Percentage of time no error with the status signal F was pending (Operating time - Time in failure)*100% / Operating time Time in failure Total amount of time an error with the status signal F was pending MTBF Mean Time Between Failures (Operating time - Time in failure)/Number of failures MTTR	
		Milik Mean Time To Repair Time in failure/Number of failures	

1) Provided you give the manufacturer all the information about changes to the hardware.

12.13.2 Sensor information

► Select the channel you want from the list of channels.

Information in the following categories is displayed:

- Extreme values Extreme conditions to which the sensor was previously exposed, e.g. min./max. temperatures ³⁾
- Operating time
- Operating time of the sensor under defined extreme conditions
- Calibration information
 - Calibration data of the last calibration
- Sensor specifications Measuring range limits for main measured value and temperature
- General information
 Information on sensor identification

³⁾ Not available for all sensor types.

The specific data that are displayed depends on what sensor is connected.

12.14 Firmware history

Date	Version	Changes to firmware	Documentation
06/2017	01.06.04	 Extension Heartbeat Monitoring and Verification New mathematical function Formula New sensors: CUS50D and chlorine dioxide Calibration via EtherNet/IP pdf generator for Heartbeat Sample calibration CAS51D Improvements Changes to conductivity concentration tables Renaming of parameter chlorine → Disinfection Last active measuring screen restored after reboot Cap and electrolyte replacements are logged in the calibration logbook (oxygen, disinfection) Manual factor for nitrate 	BA01225C/07/EN/05.17 BA00486C/07/EN/02.13 BA01245C/07/EN/05.17
12/2016	01.06.03	 Expansion Sensor calibration via Modbus or EtherNet/IP: conductivity, oxygen, chlorine and turbidity Four-factor adjustment, SAC Flash meter, nitrate and SAC New sludge model CUS51D Improvement Local display can be locked via Modbus or EtherNet/IP The output status can also be recorded in the data logbook Name of Endress+Hauser pH buffer 9.18 changed to 9.22 CUS51D factor can be read out via fieldbus 	BA01225C/07/EN/04.16 BA00486C/07/EN/02.13 BA01245C/07/EN/04.16
03/2016	01.06.00	 Expansion Heartbeat verification User-configurable diagnostic modules Four-factor adjustment, SAC Offset calibration CUS71D New mathematical function, cation exchanger Configurable byte order for Modbus Improvement Sensor calibration validity check (adaptation to batch processes) pH-Offset can be saved in either the sensor or the transmitter (previously only possible in the transmitter) CUS71D screens (gain display, trend information) Modified menu texts 	BA01225C/07/EN/04.16 BA00486C/07/EN/02.13 BA01245C/07/EN/03.16
03/2015	01.05.02	Expansion Conductivity: - New sensor: CLS82D - Concentrationalways visible in measuring menus - Expansion of concentration tables Oxygen: New sensor: COS81D SAC, nitrate, turbidity: - Calibration settings adjusted - Adjustable flash rate (expert function) Improvement Menu corrections(functions, designations)	BA01225C/07/EN/03.15 BA00486C/07/EN/02.13 BA01245C/07/EN/02.15

Date	Version	Changes to firmware	Documentation
12/2013	01.05.00	 Expansion Chemoclean Plus Calendar functionfor cleaning Conductivity: Measuring range switchingalso for conductive conductivity measurement External temperature signal viacurrent input Oxygen: Externalpressure or temperature signals via current input Connected conductivity sensor can be used to calculate the salinity. SAC, nitrate, turbidity: Calibration settings can be configured via fieldbus Channel-specific diagnostics codesfor HOLD function Support for EtherNet/IP Improvement Web server login for managing multiple users 	BA01225C/07/EN/02.13 BA00486C/07/EN/02.13 BA01245C/07/EN/01.13
		 Set point and PID parameters for controllers can be configured via fieldbus 	
07/2013	01.04.00	Original firmware	BA01225C/07/EN/01.13 BA01227C/07/EN/01.13 BA00450C/07/EN/17.13 BA00451C/07/EN/16.13 BA00486C/07/EN/02.13

13 Maintenance

Effects on process and process control

 Take all the necessary precautions in time to ensure the operational safety and reliability of the entire measuring point.

The maintenance of the measuring point comprises:

- Calibration
- Cleaning the controller, assembly and sensor
- Checking the cables and connections.

WARNING

Process pressure and temperature, contamination, electrical voltage

Risk of serious or fatal injury

- If the sensor has to be removed during maintenance work, avoid hazards posed by pressure, temperature and contamination.
- Make sure the device is de-energized before you open it.
- Power can be supplied to switching contacts from separate circuits. De-energize these circuits before working on the terminals.

NOTICE

Electrostatic discharge (ESD)

Risk of damaging the electronic components

- Take personal protective measures to avoid ESD, such as discharging beforehand at PE or permanent grounding with a wrist strap.
- ► For your own safety, only use genuine spare parts. With genuine parts, the function, accuracy and reliability are also ensured after maintenance work.

13.1 Cleaning

13.1.1 External display (in installed state)

• Clean the front of the housing using commercially available cleaning agents only.

The front of the housing is resistant to the following in accordance with DIN 42 115:

- Ethanol (for a short time)
- Diluted acids (max. 2% HCl)
- Diluted bases (max. 3% NaOH)
- Soap-based household cleaning agents

NOTICE

Cleaning agents not permitted

Damage to the housing surface or housing seal

- Never use concentrated mineral acids or alkaline solutions for cleaning.
- ► Never use organic cleaners such as acetone, benzyl alcohol, methanol, methylene chloride, xylene or concentrated glycerol cleaner.
- ► Never use high-pressure steam for cleaning purposes.

13.1.2 Digital sensors

ACAUTION

Cleaning not switched off during calibration or maintenance activities

Risk of injury due to medium or cleaning agent

- If a cleaning system is connected, switch if off before removing a sensor from the medium.
- If you wish to check the cleaning function and have therefore not switched off the cleaning system, please wear protective clothing, goggles and gloves or take other appropriate measures.

Replacing the sensor while ensuring measuring point availability

If an error occurs or the maintenance schedule stipulates that the sensor has to be replaced, use a new sensor, or a sensor that has been precalibrated in the laboratory.

- A sensor is calibrated in the laboratory under optimum external conditions, thereby ensuring better quality of measurement.
- You must perform onsite calibration if you use a sensor that is not precalibrated.
- 1. Remove the sensor that requires maintenance.

2. Insert the new sensor.

- The sensor data are automatically accepted by the transmitter. A release code is not required.
 - Measurement is resumed.
- 3. Take the used sensor back to the laboratory.
 - └ In the laboratory you can get the sensor ready for reuse while ensuring the availability of the measuring point.

Prepare the sensor for reuse

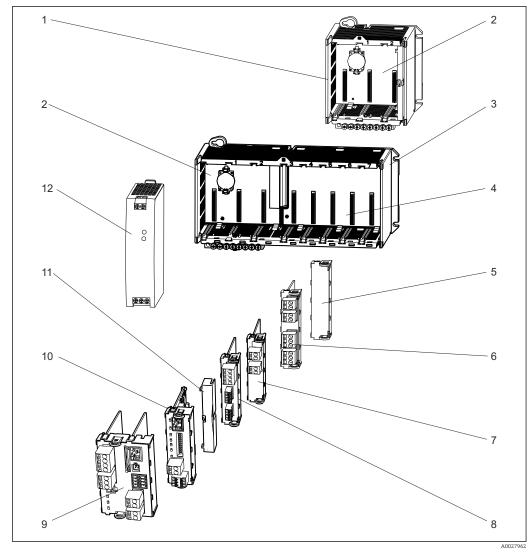
1. Clean the sensor.

- └ For this purpose, use the cleaning agent specified in the sensor manual.
- 2. Inspect the sensor for cracks or other damage.
- **3.** If no damage is found, regenerate the sensor. Where necessary, store the sensor in a regeneration solution (\rightarrow sensor manual).
- 4. Recalibrate the sensor for reuse.

13.1.3 Assemblies

Refer to the assembly operating manual for information on servicing and troubleshooting the assembly. The assembly operating manual describes the procedure for mounting and disassembling the assembly, replacing the sensors and seals, and contains information on the material resistance properties, as well as on spare parts and accessories.

14 Repairs



14.1 Spare parts

62 Spare parts: You can find the names of spare parts and their order numbers in the following table.

NOTICE

Damaged cables from careless maintenance or repair work

- Exercise care when replacing defective cables, particularly if you are removing them from a cable duct.
- Preferably use a junction box, which then acts as a stationary connection into the cabinet.

Item	Kit	Order no.
1	Kit CM442R Control cabinet installation housing, complete	71222273
2	Kit CM44x/CM44xR: electronics module backplane • Backplane complete • To be replaced only by Endress+Hauser Service	71101457
3	Kit CM444R, CM448R Control cabinet installation housing, complete	71222276

Item	Kit	Order no.
4	Kit CM44x/CM44xR: electronics module extension backplaneExtension backplane completeTo be replaced only by Endress+Hauser Service	
5, 11	Kit CM44R Set of covers for shock protection	71222282
6, 7, 8, 10	Kit CM44x/ CM44xR: extension module AOR (2 relays + 2 current outputs) Extension module AOR, complete Instructions for spare parts kit CM44x 	71111053
	Kit CM44x/CM44xR: terminal set, extension module AOR	71107453
	Kit CM44x/CM44xR: extension module 2R (2 relays) • Extension module 2R complete • Instructions for spare parts kit CM44x	71125375
	Kit CM44x/CM44xR: extension module 4R (4 relays) • Extension module 4R complete • Instructions for spare parts kit CM44x	71125376
	Kit CM44x/CM44xR: terminal set, extension module 2R, 4R	71155581
	Kit CM44x/CM44xR: extension module 2AO (2 x 0/4 to 20 mA) • Extension module 2AO complete • Instructions for spare parts kit CM44x	71135632
	Kit CM44x/CM44xR: extension module 4AO (4 x 0/4 to 20 mA) • Extension module 4AO complete • Instructions for spare parts kit CM44x	71135633
	Kit CM44x/CM44xR: terminal set, extension module 2AO, 4AO	71155582
	Kit CM44x/CM44xR: extension module DIO (2 x digital input, digital output in each case) Extension module DIO, complete Instructions for spare parts kit CM44x 	71135638
	Kit CM44x/CM44xR: terminal set, extension module DIO	71219784
	Kit CM44x/CM44xR: extension module 2DS (2 x digital sensor) • Extension module 2DS complete • Instructions for spare parts kit CM44x	71135631
	Kit CM44x/CM44xR: extension module 2AI (2 x analog input 0/4 to 20 mA) Extension module 2AI complete Instructions for spare parts kit CM44x 	71135639
	 Kit CM44x/CM44xR: extension module 485 (Ethernet configuration) Extension module 485 complete With activation code extendable to PROFIBUS DP or Modbus RS 485 or Modbus TCP or EtherNet/IP Instructions for spare parts kit CM44x 	71135634
	Kit CM44x/CM44xR: terminal set for extension module 2AI, 485	71155583
9	Kit CM44xR: base module BASE-E Base module, complete End cover Connecting cable to connect to the power unit Instructions for spare parts kit CM44x	71141336
	Kit CM44x: terminal set, base module	71107452
12	Kit CM444R/8R: DIN rail power unit DIN rail power unit 110 to 230 VAC DIN rail power unit 24 VDC	71222277 71222279

14.2 Return

The product must be returned if repairs or a factory calibration are required, or if the wrong product was ordered or delivered. As an ISO-certified company and also due to legal

regulations, Endress+Hauser is obliged to follow certain procedures when handling any returned products that have been in contact with medium.

To ensure swift, safe and professional device returns, please read the return procedures and conditions at www.endress.com/support/return-material.

14.3 Disposal

The device contains electronic components and must therefore be disposed of in accordance with regulations on the disposal of electronic waste.

Observe the local regulations.

Always dispose of batteries in accordance with local regulations on battery disposal.



Accessories

The following are the most important accessories available at the time this documentation was issued. For accessories not listed here, please contact your service or sales office.

15.1 Measuring cable

CYK10 Memosens data cable

- For digital sensors with Memosens technology
- Product Configurator on the product page: www.endress.com/cyk10

Technical Information TI00118C

Memosens data cable CYK11

- Extension cable for digital sensors with Memosens protocol
- Product Configurator on the product page: www.endress.com/cyk11

Technical Information TI00118C

15.2 Sensors

15.2.1 Glass electrodes

Orbisint CPS11D

- pH electrode for process technology
- Optional SIL version for connecting to SIL transmitter
- With dirt-repellent PTFE diaphragm
- Product Configurator on the product page: www.endress.com/cps11d

Technical Information TI00028C

Memosens CPS31D

- pH electrode with gel-filled reference system with ceramic diaphragm
- Product Configurator on the product page: www.endress.com/cps31d

Technical Information TI00030C

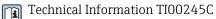
Ceraliquid CPS41D

- pH electrode with ceramic junction and KCl liquid electrolyte
- Product Configurator on the product page: www.endress.com/cps41d

Technical Information TI00079C

Ceragel CPS71D

- pH electrode with reference system including ion trap
- Product Configurator on the product page: www.endress.com/cps71d



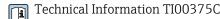
Memosens CPS171D

- pH electrode for bio-fermenters with digital Memosens technology
- Product Configurator on the product page: www.endress.com/cps171d

Technical Information TI01254C

Orbipore CPS91D

- pH electrode with open aperture for media with high dirt load
- Product Configurator on the product page: www.endress.com/cps91d



Orbipac CPF81D

- Compact pH sensor for installation or immersion operation
- In industrial water and wastewater
- Product Configurator on the product page: www.endress.com/cpf81d

Technical Information TI00191C

15.2.2 Enamel pH electrodes

Ceramax CPS341D

- pH electrode with pH-sensitive enamel
- Meets highest demands of measuring accuracy, pressure, temperature, sterility and durability
- Product Configurator on the product page: www.endress.com/cps341d

Technical Information TI00468C

15.2.3 ORP sensors

Orbisint CPS12D

- ORP sensor for process technology
- Product Configurator on the product page: www.endress.com/cps12d

Technical Information TI00367C

Ceraliquid CPS42D

- ORP electrode with ceramic junction and KCl liquid electrolyte
- Product Configurator on the product page: www.endress.com/cps42d

Technical Information TI00373C

Ceragel CPS72D

- ORP electrode with reference system including ion trap
- Product Configurator on the product page: www.endress.com/cps72d

Technical Information TI00374C

Orbipac CPF82D

- Compact ORP sensor for installation or immersion operation in process water and wastewater
- Product Configurator on the product page: www.endress.com/cpf82d

Technical Information TI00191C

Orbipore CPS92D

- ORP electrode with open aperture for media with high dirt load
- Product Configurator on the product page: www.endress.com/cps92d



Technical Information TI00435C

15.2.4 pH ISFET sensors

Tophit CPS441D

- Sterilizable ISFET sensor for low-conductivity media
- Liquid KCl electrolyte
- Product Configurator on the product page: www.endress.com/cps441d

Technical Information TI00352C

Tophit CPS471D

- Sterilizable and autoclavable ISFET sensor for food and pharmaceutics, process engineering
- Water treatment and biotechnology
- Product Configurator on the product page: www.endress.com/cps471d

Technical Information TI00283C

Tophit CPS491D

- ISFET sensor with open aperture for media with high dirt load
- Product Configurator on the product page: www.endress.com/cps491d

Technical Information TI00377C

15.2.5 pH and ORP combined sensors

Memosens CPS16D

- Combined pH/ORP sensor for process technology
- With dirt-repellent PTFE diaphragm
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cps16D

Technical Information TI00503C

Memosens CPS76D

- Combined pH/ORP sensor for process technology
- Hygienic and sterile applications
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cps76d

Technical Information TI00506C

Memosens CPS96D

- Combined pH/ORP sensor for chemical processes
- With poison-resistant reference with ion trap
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cps96d

Technical Information TI00507C

15.2.6 Conductivity sensors with inductive measurement of conductivity

Indumax CLS50D

- High-durability inductive conductivity sensor
- For standard and hazardous area applications
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cls50d

Technical Information TI00182C

Indumax H CLS54D

- Inductive conductivity sensor
- With certified, hygienic design for foodstuffs, beverages, pharmaceuticals and biotechnology
- Product Configurator on the product page: www.endress.com/cls54d

Technical Information TI00508C

15.2.7 Conductivity sensors with conductive measurement of conductivity

Condumax CLS15D

- Conductive conductivity sensor
- For pure water, ultrapure water and Ex applications
- Product Configurator on the product page: www.endress.com/CLS15d

Technical Information TI00109C

Condumax CLS16D

- Hygienic, conductive conductivity sensor
- For pure water, ultrapure water and Ex applications
- With EHEDG and 3A approval
- Product Configurator on the product page: www.endress.com/CLS16d

Technical Information TI00227C

Condumax CLS21D

- Two-electrode sensor in plug-in head version version
- Product Configurator on the product page: www.endress.com/CLS21d

Technical Information TI00085C

Memosens CLS82D

- Four-electrode sensor
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cls82d

Technical Information TI01188C

15.2.8 Oxygen sensors

Oxymax COS22D

- Sterilizable sensor for dissolved oxygen
- With Memosens technology or as an analog sensor
- Product Configurator on the product page: www.endress.com/cos22d

Technical Information TI00446C

Oxymax COS51D

- Amperometric sensor for dissolved oxygen
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cos51d

Tecl

Technical Information TI00413C

Oxymax COS61D

- Optical oxygen sensor for drinking water and industrial water measurement
- Measuring principle: quenching
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cos61d

Technical Information TI00387C

Memosens COS81D

- Sterilizable, optical sensor for dissolved oxygen
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cos81d

Technical Information TI01201C

15.2.9 Disinfection sensors

CCS142D

- Membrane-covered amperometric sensor for free chlorine
- Measuring range 0.01 to 20 mg/l
- With Memosens technology
- Product Configurator on the product page: www.endress.com/ccs142d

Technical Information TI00419C

15.2.10 Ion-selective sensors

ISEmax CAS40D

- Ion selective sensors
- Product Configurator on the product page: www.endress.com/cas40d

Technical Information TI00491C

15.2.11 Turbidity sensors

Turbimax CUS51D

- For nephelometric measurements of turbidity and solids in wastewater
- 4-beam scattered light method
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cus51d

Technical Information TI00461C

Turbimax CUS52D

- Hygienic Memosens sensor for turbidity measurement in drinking water, process water and in utilities
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cus52d

Technical Information TI01136C

15.2.12 SAC and nitrate sensors

Viomax CAS51D

- SAC and nitrate measurement in drinking water and wastewater
- With Memosens technology
- Product Configurator on the product page: www.endress.com/cas51d

Technical Information TI00459C

15.2.13 Interface measurement

Turbimax CUS71D

- Immersion sensor for interface measurement
- Ultrasonic interface sensor
- Product Configurator on the product page: www.endress.com/cus71d

Technical Information TI00490C

15.3 Additional functionality

15.3.1 Hardware extension modules

Kit, extension module AOR

- 2 x relay, 2 x 0/4 to 20 mA analog output
- Order No. 71111053

Kit, extension module 2R

- 2 x relay
- Order No. 71125375

Kit, extension module 4R

- 4 x relay
- Order No. 71125376

Kit, extension module 2AO

- 2 x 0/4 to 20 mA analog output
- Order No. 71135632

Kit, extension module 4AO

- 4 x analog output 0/4 to 20 mA
- Order No. 71135633

Kit, extension module 2DS

- 2 x digital sensor, Memosens
- Order No. 71135631

Kit, extension module 2AI

- 2 x 0/4 to 20 mA analog input
- Order No. 71135639

Kit, extension module DIO

- 2 x digital input
- 2 x digital output
- Auxiliary voltage supply for digital output
- Order No. 71135638

Kit, extension module 485

- Ethernet configuration
- Can be extended to PROFIBUS DP or Modbus RS485 or Modbus TCP or EtherNet/IP. This requires an additional activation code which can be ordered separately.
- Order No. 71135634

Kit, extension module ETH

- Ethernet configuration
- Can be extended to Modbus TCP or EtherNet/IP. This requires an additional activation code which can be ordered separately.
- Order No. 71279810

Upgrade kit, extension module 485 with PROFIBUS DP

- Extension module 485
- PROFIBUS DP (+ Ethernet configuration)
- Order No. 71140888

Upgrade kit, extension module 485 with Modbus RS485

- Extension module 485
- Modbus RS485 (+ Ethernet configuration)
- Order No. 71140889

Upgrade kit, extension module 485 with Modbus TCP

- Extension module 485
- Modbus TCP (+ Ethernet configuration)
- Order No. 71140890

Upgrade kit, extension module 485 with EtherNet/IP

- Extension module 485
- EtherNet/IP (+ Ethernet configuration)
- Order No. 71219868

Upgrade kit, extension module ETH with Modbus TCP

- Extension module ETH
- Modbus TCP (+ Ethernet configuration)
- Order No. 71279809

Upgrade kit, extension module ETH with EtherNet/IP

- Extension module ETH
- EtherNet/IP (+ Ethernet configuration)
- Order No. 71279812

15.3.2 Firmware and activation codes

SD card with Liquiline firmware

- Industrial Flash Drive, 1 GB
- Order No. 71127100

You must quote the serial number of the device when ordering the activation code.

Activation code for digital HART communication Order No. 71128428

Activation code for PROFIBUS DP Order No. 71135635

Activation code for Modbus RS485 Order No. 71135636

Activation code for Modbus TCP for module 485 Order No. 71135637

Activation code for EtherNet/IP for module 485 Order No. 71219871

Activation code for Modbus TCP for module ETH Order No. 71279813

Activation code for EtherNet/IP for module ETH Order No. 71279830

Kit CM442R: activation code for 2nd digital sensor input Order No. 71114663

Kit CM444R/CM448R: upgrade code for 2 x 0/4 to 20 mA for BASE-E Order No. 71140891

Activation code for feedforward control

- Requires current input or fieldbus communication
- Order No. 71211288

Activation code for measuring range switch

- Requires digital inputs or fieldbus communication
- Order No. 71211289

Activation code for ChemocleanPlus

- Requires relays or digital outputs or fieldbus communication and optional digital inputs
- Order No. 71239104

Activation code for Heartbeat Verification and Monitoring Order No. 71367524

Activation code for ion exchanger operating time

- Mathematical function
- Order No. 71367531

Activation code for mathematics

Formula editorOrder No. 71367541

Activation code for remote calibration interface

Order No. 71367542

15.4 Software

Memobase Plus CYZ71D

- PC software to support laboratory calibration
- Visualization and documentation of sensor management
- Sensor calibrations saved in the database
- Order as per product structure, www.endress.com/cyz71d

Technical Information TI00502C

Field Data Manager Software MS20

- PC software for central data management
- Visualization of series of measurements and logbook events
- SQL database for secure data storage
- Order No. 71129799

15.5 Other accessories

15.5.1 External display⁴⁾

Graphic display

- For installation in the control cabinet door or panel
- Order No. 71185295

Service display

- Portable, for commissioning
- Order No. 71185296

15.5.2 SD card

- Industrial Flash Drive, 1 GB
- Weight: 2 g
- Order No. 71110815

⁴⁾ The external display can be selected as an option in the product structure or ordered subsequently as an accessory.

15.5.3 **Communication-specific accessories**

Commubox FXA191

- Intrinsically safe HART communication with FieldCare via the RS232C interface
- Transforms HART signals on RS 232C interface

Technical Information TI00237F

Commubox FXA195

Intrinsically safe HART communication with FieldCare via the USB port

Technical Information TI00404F

Commubox FXA291

Connects the CDI interface of measuring devices with the USB port of the computer or laptop



Technical Information TI00405C

Wireless HART adapter SWA70

Wireless device connection

• Easily integrated, offers data protection and transmission safety, can be operated in parallel with other wireless networks, minimum cabling complexity



Technical Information TI00061S

Fieldgate FXA320

Gateway for the remote interrogation of 4-20 mA measuring devices via a Web browser



Technical Information TI00025S

FieldXpert SFX100

Compact, flexible and robust industrial handheld terminal for remote configuration and for obtaining measured values via the HART current output

Operating Instructions BA00060S

15.5.4 System components

RIA14, RIA16

- Field display unit for integration into 4-20 mA circuits
- RIA14 in flameproof metal enclosure

Technical Information TI00143R and TI00144R

RIA15

- Process display unit, Digital display unit for integration into 4-20 mA circuits
- Panel mounting
- With optional HART communication

Technical Information TI01043K

16 Technical data

16.1 Input

\rightarrow Documentation of the connected sensor
\rightarrow Documentation of the connected sensor
 Digital sensor inputs for sensors with Memosens protocol Analog current inputs (optional) Digital inputs (optional)
 Depending on version: Max. 8 x binary sensor signal 2 x 0/4 to 20 mA (optional), passive, potentially isolated from one another and from the sensor inputs 0 to 30 V
Cable type Memosens data cable CYK10 or sensor fixed cable, each with cable end sleeves or M12 round-pin connector (optional) Cable length Max. 100 m (330 ft)

16.2 Digital inputs, passive

Electrical specification	drawing power (passive)Galvanically isolated		
Span	High: Low:	11 to 30 V DC 0 to 5 V DC	
Nominal input current	max. 8 mA		
PFM function	Minimum pulse width: 500 µs	(1 kHz)	
Test voltage	500 V		
Cable specification	Max. 2.5 mm ² (14 AWG)		

16.3 Current input, passive

Span

Signal characteristic	Linear		
Internal resistance	Non-linear		
Test voltage	500 V		
	16.4 Output		
Output signal	 Depending on version: 2 x 0/4 to 20 mA, active, galvanically isolated from one another and from the sensor circuits 4 x 0/4 to 20 mA, active, galvanically isolated from one another and from the sensor circuits 6 x 0/4 to 20 mA, active, galvanically isolated from one another and from the sensor circuits 8 x 0/4 to 20 mA, active, galvanically isolated from one another and from the sensor circuits 8 x 0/4 to 20 mA, active, galvanically isolated from one another and from the sensor circuits 8 x 0/4 to 20 mA, active, galvanically isolated from one another and from the sensor circuits 9 x 0/4 to 20 mA, active, galvanically isolated from one another and from the sensor circuits 9 Optional HART communication (only via current output 1:1) 		
	HART		
	Signal encoding	FSK ± 0.5 mA above current signal	
	Data transmission rate	1200 baud	
	Galvanic isolation	Yes	
	Load (communication resistor)	250 Ω	
	PROFIBUS DP/RS485		
	Signal encoding	EIA/TIA-485, PROFIBUS DP-compliant acc. to IEC 61158	
	Data transmission rate	9.6 kBd, 19.2 kBd, 45.45kBd, 93.75 kBd, 187.5 kBd, 500 kBd, 1.5 MBd, 6 MBd, 12 MBd	
	Galvanic isolation	Yes	
	Connectors	Spring terminal (max. 1.5 mm), bridged internally (T-function), optional M12	
	Bus termination	Internal slide switch with LED display	
	Modbus RS485		
	Signal encoding	EIA/TIA-485	
	Data transmission rate	2,400, 4,800, 9,600, 19,200, 38,400, 57,600 and 115,200 baud	
	Galvanic isolation	Yes	

Connectors

Bus termination

Spring terminal (max. 1.5 mm), bridged internally (T-function), optional M12

Internal slide switch with LED display

	Ethernet and Modbus TCP		
	Signal encoding IEEE 802.3 (Ethernet)		
	Data transmission rate	10/100 MBd	
	Galvanic isolation	Yes	
	Connection	RJ45	
	IP address	DHCP (default) or configuration via menu	
	EtherNet/IP		
	Signal encoding	IEEE 802.3 (Ethernet)	
	Data transmission rate	10/100 MBd	
	Galvanic isolation	Yes	
	Connection	RJ45	
	IP address	DHCP (default) or configuration via menu	
Signal on alarm	 Adjustable, as per NAMUR Recommendation NE 43 In measuring range 0 to 20 mA (HART is not available with this measuring range): Error current from 0 to 23 mA In measuring range 4 to 20 mA: Error current from 2.4 to 23 mA Factory setting for error current for both measuring ranges: 21.5 mA 		
Load	Max. 500 Ω		
Linearization/transmission behavior	Linear		
	16.5 Digital outp	outs, passive	
Electrical specification	 Passive Open collector, max. 30 V, 15 mA 		
PFM function	Minimum pulse width: 500 µs (1 kHz)		
Auxiliary voltage	Electrical specification Galvanically isolated Unregulated, 24 V DC ± 20% Max. 50 mA (per DIO module)		
Test voltage	500 V		
Cable specification	Max. 2.5 mm ² (14 AWG)		

Span	0 to 23 mA	
	2.4 to 23 mA for HART communication	
Signal characteristic	Linear	
Electrical specification	Output voltage	
	Max. 24 V	
	Test voltage 500 V	
Cable specification	Cable type Recommended: shielded cable	
	Cable specification Max. 2.5 mm ² (14 AWG)	

16.6 Current outputs, active

16.7	Relay outputs
------	----------------------

Electrical specification

- 1 single-pin changeover contact (alarm relay)
- 2 or 4 single-pin changeover contacts (optional with extension modules)

Maximum load

Relay types

- Alarm relay: 0.5 A
- All other relays: 2.0 A
- Relay switching capacity

Base module (Alarm relay)

Switching voltage	Load (max.)	Switching cycles (min.)
230 V AC, $\cos\Phi$ = 0.8 to 1	0.1 A	700,000
	0.5 A	450,000
115 V AC, $\cos \Phi = 0.8$ to 1	0.1 A	1,000,000
	0.5 A	650,000
24 V DC, L/R = 0 to 1 ms	0.1 A	500,000
	0.5 A	350,000

Extension modules

Switching voltage	Load (max.)	Switching cycles (min.)
230 V AC, $\cos \Phi = 0.8$ to 1	0.1 A	700,000
	0.5 A	450,000
	2 A	120,000
115 V AC, $\cos \Phi = 0.8$ to 1	0.1 A	1,000,000
	0.5 A	650,000
	2 A	170,000
24 V DC, L/R = 0 to 1 ms	0.1 A	500,000
	0.5 A	350,000
	2 A	150,000

Cable specification Max. 2.5 mm

Max. 2.5 mm^2 (14 AWG)

16.8 Protocol-specific data

HART

Manufacturer ID	11 _h
Device type	155D _h
Device revision	001 _h
HART version	7.2
Device description files (DD/DTM)	www.endress.com/hart Device Integration Manager DIM
Device variables	16 user-definable and 16 predefined device variables, dynamic variables PV, SV, TV, QV
Supported features	PDM DD, AMS DD, DTM, Field Xpert DD

PROFIBUS DP

Manufacturer ID	11 _h	
Device type	155D _h	
Profile version	3.02	
GSD files	www.endress.com/profibus Device Integration Manager DIM	
Output values	16 AI blocks, 8 DI blocks	
Input variables	4 AO blocks, 8 DO blocks	
Supported features	 1 MSCY0 connection (cyclical communication, master class 1 to slave) 1 MSAC1 connection (acyclical communication, master class 1 to slave) 2 MSAC2 connections (acyclical communication, master class 2 to slave) Device lock: The device can be locked using the hardware or software. Addressing using DIL switches or software GSD, PDM DD, DTM 	

Modbus RS485

Protocol	RTU/ASCII
Function codes	03, 04, 06, 08, 16, 23
Broadcast support for function codes	06, 16, 23
Output data	16 measured values (value, unit, status), 8 digital values (value, status)
Input data	4 setpoints (value, unit, status), 8 digital values (value, status), diagnostic information
Supported features	Address can be configured using switch or software

Modbus TCP

TCP port	502
TCP connections	3
Protocol	TCP
Function codes	03, 04, 06, 08, 16, 23
Broadcast support for function codes	06, 16, 23
Output data	16 measured values (value, unit, status), 8 digital values (value, status)
Input data	4 setpoints (value, unit, status), 8 digital values (value, status), diagnostic information
Supported features	Address can be configured using DHCP or software

EtherNet/IP

Log	EtherNet/IP		
ODVA certification	Yes		
Device profile	Generic device (product type: 0x2B)		
Manufacturer ID	0x049E _h		
Device type ID	0x109C _h		
Polarity	Auto-MIDI-X		
Connections	CIP	12	
	I/O	6	
	Explicit message	6	
	Multicast	3 consumers	
Minimum RPI	100 ms (default)		
Maximum RPI	10000 ms		
System integration	EtherNet/IP	erNet/IP EDS	
	Rockwell	Add-on-Profile Level 3, Faceplate for Factory Talk SE	
IO data	Input (T \rightarrow O)	Device status and diagnostic message with highest priority	
		Measured values: 16 AI (analog input) + Status + Unit 8 DI (discrete input) + Status 	
	Output (O → T)	Actuating values: • 4 A0 (analog output) + status + unit • 8 DO (discrete output) + Status	

Web server

The web server enables full access to the device configuration, measured values, diagnostic messages, logbooks and service data via standard WiFi/WLAN/LAN/GSM or 3G routers with a user-defined IP address.

TCP port	80
Supported features	 Remote-controlled device configuration(1 session) Save/restore device configuration (via SD card) Logbook export (file formats: CSV, FDM) Access to web server via DTM or Internet Explorer Login Web server can be switched off

16.9 Power supply

Supply voltage	CM442 R Depending on version: • 100 to 230 V AC ± 15 %, 50/60 Hz • 24 V AC/DC +20/-15 %, 50/60 Hz		
	 CM444 R and CM448 R Depending on the version, via external DIN rail power unit: 100 to 230 V AC ± 15 %, 50/60 Hz 24 V DC +20 / -15 % 		
Fieldbus connection	Supply voltage: not applicable		

Power consumption	CM442 R Depending on supply voltage 100 to 230 V AC and 24 V AC: Max. 55 VA 24 V DC: Max. 22 W
	CM444 R and CM448 R Depending on supply voltage 100 to 230 V AC: Max. 150 VA 24 V DC: Max. 59 W
Fuse	Fuse not exchangeable
Overvoltage protection	Integrated overvoltage/lightning protection as per EN 61326 Protection category 1 and 3
Cable specification for optional display cable	Length of display cable provided: 3 m (10 ft)
	Maximum permitted length of a display cable: 5 m (16.5 ft)

16.10 Performance characteristics

Response time	Current outputs $t_{90} = max. 500 ms$ for an increase from 0 to 20 mA		
	Current inputs $t_{90} = max. 330 ms$ for an increase from 0 to 20 mA		
	Digital inputs and outputs t ₉₀ = max. 330 ms for an increase from low to high		
Reference temperature	25 °C (77 °F)		
Measured error for sensor inputs	\rightarrow Documentation of the connected sensor		
Measured error for current inputs and outputs	Typical measured errors: < 20 μA (with current values < 4 mA) < 50 μA (with current values 4 to 20 mA) at 25 °C (77° F) each		
	Additional measured error depending on the temperature: $< 1.5 \ \mu A/K$		
Frequency tolerance of digital inputs and outputs	≤ 1%		

Resolution of current inputs $< 5 \mu A$ and outputs

Repeatability

 \rightarrow Documentation of the connected sensor

16.11 Environment

Ambient temperature range	CM442 R -20 to 60 °C (0 to 140 °F)
range	 -2010 60° C (010 140° F) CM444 R Generally -20 to 55 °C (0 to 130 °F), with the exception of packages under the second point in the list -20 to 50 °C (0 to 120 °F) for the following packages: CM444R-**M40A7FI*+ CM444R-**M40A7FK*+ CM444R-**M4AA5F4*+ CM444R-**M4AA5FF*+ CM444R-**M4AA5FI*+ CM444R-**M4AA5FI*+ CM444R-**M4AA5FK*+ CM444R-**M4AA5FK*+ CM444R-**M4AA5FK*+ CM444R-**M4AA5FK*+ CM444R-**M4BA5FK*+ CM444R-**M4BA5FF*+ CM444R-**M4BA5FF*+ CM444R-**M4BA5FF*+ CM444R-**M4BA5FF*+ CM444R-**M4BA5FF*+ CM444R-**M4BA5FK*+ CM444R-**M4DA5FK*+ CM444R-**M4DA5FK*+ CM444R-**M4DA5FK*+ CM444R-**M4DA5FK*+

CM448R

- Generally –20 to 55 $^\circ C$ (0 to 130 $^\circ F), with the exception of packages under the second point in the list$
- \bullet –20 to 50 °C (0 to 120 °F) for the following packages:
 - CM448R-***6AA*+...
 - CM448R-***8A4*+...
 - CM448R-***8A5*+...
 - CM448R-**28A3*+...
 - CM448R-**38A3*+...
 - CM448R-**48A3*+...
 - CM448R-**58A3*+...
 - CM448R-**68A3*+...
 - CM448R-**26A5*+...
 - CM448R-**36A5*+...
 - CM448R-**46A5*+...
 - CM448R-**56A5*+...
 - CM448R-**66A5*+...
 - CM448R-**22A7*+... - CM448R-**32A7*+...
 - CM448R-**42A7*+...
 - CM448R-**52A7*+...
 - CM448R-**62A7*+...
 - CM448R-**86A5*+...
 - CM448R-**A6A7*+...
 - CM448R-**B6A5*+...
 - CM448R-**B6A7*+...
 - CM448R-**C6A5*+...
 - CM448R-**C6A7*+...
 - CM448R-**D6A5*+...
 - CM448R-**D6A7*+...

External display (optional)

-20 to 60 °C (0 to 140 °F)

Storage temperature	-25 to +85 °C (-10 to +185 °F)	
Humidity	DIN rail device 5 to 85%, not condensing	
	External display (in installed state) 5 to 95%, not condensing	
Degree of protection	DIN rail device IP20 shock protection	
	External display IP66 front-panel, when installed correctly including seal for housing door	
Climate class	As per IEC 60654-1: B2	
Vibration resistance	Environmental tests Vibration test based on DIN EN 60068-2, October 2008 Vibration test based on DIN EN 60654-3, August 1998	

	Wall mounting		
	Frequency range	10 to 150 Hz (sinusoid	al)
	Amplitude	10 to 12.9 Hz: 12.9 to 150 Hz:	0.75 mm 0.5 g ¹⁾
	Test duration	10 frequency cycles/ sp min)	oatial axis, in 3 spatial axes (1 oct./
	1) g gravitational acceler	ation (1 g \approx 9.81 m/s ²)	
Electromagnetic compatibility	Interference emission and interference immunity as per EN 61326-1:2013, Class A for Industry		
Electrical safety	IEC 61010-1, Class I equipment Low voltage: overvoltage category II Environment < 2000 m (< 6562 ft) above MSL		
Degree of contamination	DIN rail device The product is suitable for pollution degree 2. Optional display		
	The product is suitable fo	or pollution degree 4.	
	16.12 Mechanie	cal construction	

Dimensions	→ 🗎 15	
Weight	depending on the version:	
	CM442R (fully configured)	Approx. 0.45 kg (1 lbs)
	CM444R and CM448R (fully configured)	Approx. 0.95 kg (2.1 lbs)
	Individual module	Approx. 0.06 kg (0.13 lbs)
	External display (excluding cables)	Approx. 0.56 kg (1.2 lbs)
	Service display cover	0.46 kg (1 lbs)
	External power unit (CM444R, CM448R)	0.27 to 0.42 kg (0.60 to 0.92 lbs), depending on the power unit variant
	SD card	Max. 5 g (0.17 oz)

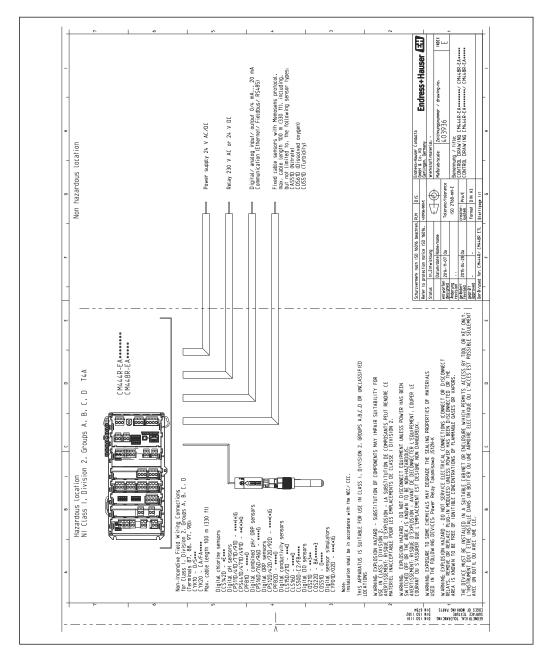
Materials

DIN rail housing	PC-FR
Display cover	PC-FR
Display seal	EPDM
Soft keys	EPDM
Module covers	PBT GF30 FR
Terminal strip	Nickel-plated brass
Ground terminals	Stainless steel 1.4301 (AISI304)
Threaded fasteners	Stainless steel 1.4301 (AISI304)
Mounting plate (optional display)	Stainless steel 1.4301 (AISI304)
Securing screws (optional display)	Steel, galvanized
Cover for service display (accessories)	EPDM

17 Installation and operation in hazardous environment Class I Div. 2 (CM444R and CM448R only)

Non-sparking device for use in specified hazardous environment in accordance with:

- cETLus Class I Div. 2
- Gas group A, B, C, D
- Temperature class T4A, 0 °C (32 °F) < Ta < 55 °C (131 °F)
- Control drawing: 403936



Index

Α

Accessories
Additional functionality
Communication-specific
Firmware and activation codes
Hardware extension modules
Measuring cable
Other
Sensors
Software
Activation code
Adapting the diagnostic behavior
Additional functions
Cleaning programs
Controller
Limit switches
Mathematical functions
Measuring range switching
Advanced setup
Alarm relay
Ambient temperature range 148
Assignment views
5

В

Basic settings	54
Basic setup	51
Bus termination	37

С

÷
Cable specification
Cable terminals
Calculated pH value
Calibration 108
Cation exchanger capacity 99
Change password
Check
Connection
Installation
Installation and function
Chemoclean
Chemoclean Plus
Chlorine control with feedforward control 75
Cleaning cycle
Cleaning function
Cleaning programs
Chemoclean
Chemoclean Plus
Manual cleaning
Standard cleaning
Cleaning types
Cleaning unit
Climate class
Commissioning
Configuration
Binary inputs
Binary outputs

Configure
Actions
Display behavior
Free text
Numerical values
Operating language
Picklists
Tables
User definable screens
Connection
Check
Fieldbus
Functional ground
Measuring device
Optional module
Sensors
Supply voltage
Web server
Controller
Controller structure
Current inputs
Current outputs

D

Data management	63
Date	
Degassed conductivity	
Degree of contamination	
Degree of protection	
Designated use	
Device description	
Device information	
Device status	
Device test	
Device variables	
Device-specific diagnostic messages	
Device-specific errors	
Diagnostic messages	
Adapting	110
Classification	
Device-specific	
Fieldbus	
Local display	
Outputting via the relay	
Pending	
Sensor-specific	
Web browser	110
Diagnostic modules	106
Diagnostics list	116
Dimensions	150
Display	. 52
Display behavior	
Display cable	. 18
Disposal	
Documentation	
Dual conductivity	. 98

Index

Ε	
Electrical safety	0
Electromagnetic compatibility	0
Ensuring the degree of protection 3	8
EtherNet/IP 43, 62, 74, 14	6
Event logbook	6
Exporting the setup	4

F Fieldh

Fieldbus
Connection
Termination
Firmware history
Firmware update
Formula
Function check
Functional ground
Fuse

Η

Hardware settings
HART 42, 73, 144
HART bus address
Heartbeat diagnostics
Heartbeat verification
Hold settings
Humidity

I

Incoming acceptance 13
Input
Current input, passive
Digital inputs, passive
Measured values
Input signal
Inputs
Binary
Current inputs
Installation
Check
Installation conditions
Installation environment

L

Laplace representation	85
Limit switches	, 80
Loading the setup	64
Logbooks	117

Μ

111
Maintenance
Manipulated variable
Materials
Mathematical functions
Calculated pH value
Cation exchanger capacity
Degassed conductivity
Difference
Dual conductivity

Measuring ranges	96 97 140 52 104 140 , 73 145
Modbus TCP	145
Nameplate	13
0	
Occupational safety	
Configure	. 52 . 54
Operational safety	8
Output Current outputs, active Digital outputs, passive Output signal Relay outputs Outputs Binary Current outputs EtherNet/IP HART Modbus PROFIBUS DP Relay Overvoltage protection	142 141 144 74 67 74 . 73 73 . 73
Р	
Power supply	49 147 146 147 34 30 24

Connecting optional modules
Connecting the measuring device
Fuse
Overvoltage protection
Power consumption
Sensor connection
Supply voltage
Power up
Process errors without messages 109
Product identification
Product safety
PROFIBUS DP 43, 60, 145
Device variables
PROFIBUS variables
PROFIBUS variables
Protocol-specific data

R

Relay 6	9
Remote operation	3
Repairs	8
Requirements for the personnel	7
Resetting the measuring device	1
Return	9
rH value	7

S

Safety
IT
Occupational safety
Operation
Product
Safety instructions
Saving the setup 64
Scope of delivery 14
Sensor
Connection
Sensor information
Sensor-specific diagnostic messages
Service interface
Settings
Advanced
Diagnostics
EtherNet/IP 62
General
Hardware
HART bus address
Modbus
PROFIBUS DP
Web server
Setup
Basic
Simulation
Slot and port assignment
Soft keys in the measurement mode
Spare parts
Standard cleaning
State of the art
Storage temperature 149
Supply voltage
Symbols
System information
System integration
Fieldbus
Service interface
Web server

Τ Τe

Гесhnical data	
Current input, passive	0
Current outputs, active	3
Digital inputs, passive	0
Digital outputs, passive	2
Environment	8
Input	0
Mechanical construction	0

U

Use		
D	esignated	7
Ν	on-designated	7
User	definable screens)

V

Vibration resistance	49
----------------------	----

W

Warnings .																					•						5
Web server	•	•			•	•			•					•	•					•			1	61	.,	14	¥б
Weight	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•		•	•	•	•		•	•	15	50



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